TITLE OF paper

**Author1\***, **Author1**, A**uthor2**

1 Affiliation, City, Country

2 Affiliation, City, Country

\* Corresponding author e-mail: xxxxxxxxxxxxxxxx

Abstract (Heading A)

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**Keywords:** 3- 5 keywords (Keywords)

# 1. Introduction (Heading 1)

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## 1.1 References (Heading 2)

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# 2. Heading 2 (Heading 1)

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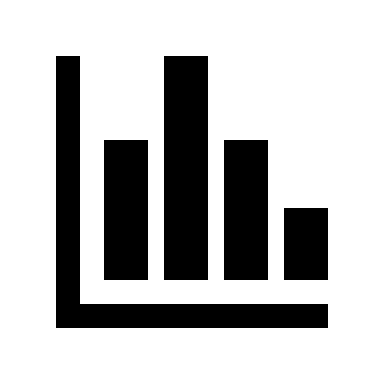
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Figure 1**:** xxxxxxxxxxxxxxxxxxxxxxxxxxxxx (Caption)

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Table 1**:** xxxxxxxxxxxxxxxxxxxxxxxxxxxx (Caption)

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# 3. HEADING 1

## 3.1 Heading 2

### 3.1.1. Heading 3

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Acknowledgements

Add acknowledgements here, if needed.

References

1. There is a marker at the end of the list that makes the final page columns equal length. Try to avoid deleting that.
2. Sheridan, T. B., & Verplank, W. (1978). Human and computer control of undersea teleoperators. Report, Man-machine systems laboratory, Department of mechanical engineering. MIT. Cambridge, MA, USA.
3. ISO, Regulatory Scoping Exercise for the Use of Maritime Autonomous Surface Ships (MASS), Proposal for a classification scheme for degrees of autonomy, IMO Document MSC 100/5/1, August 2018.
4. SAE J3016: “Taxonomy and definitions for terms related to on-road motor vehicle automated driving systems”, Revision September 2016, SAE International.
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