Convex optimization

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Convex optimization in two slides

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What do we get in return ?

- Recognizing (global) optimal solutions becomes easy
- Efficient algorithms (both in theory and in practice): interior-point methods Polynomial-time algorithmic complexity for (nearly) all common convex optimization problems:

 $\mathcal{O}\left(\sqrt{
u}\lograc{1}{\epsilon}
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where u is a measure of the problem size

- Duality: existence of another strongly related dual problem, a maximization problem with the same optimal value
 - How to check that solution to Ax = b is correct ? Plug x into equation
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Thanks for you attention