

# Tradespace Exploration of Floating Offshore Wind Mooring Systems

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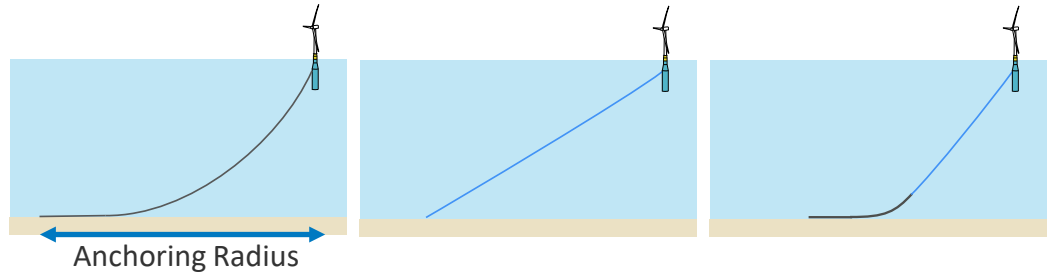
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# Methodology

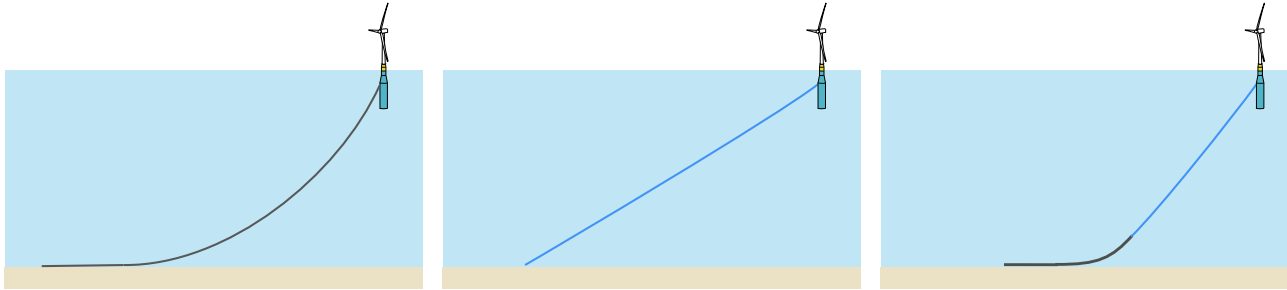
**Goal:** to design mooring systems across a range of depths and anchor spacings, allowing patterns in cost, optimal anchoring radius, and more to be mapped out

Three mooring system types:



Configuration	Line Type	Anchor Type	Water depth	Anchoring Radius
Catenary	Chain	DEA		
Taut	Polyester	Suction pile	100 to 1400 m	600 – 2400 m
Semi-taut	Chain and polyester	DEA		

# Methodology

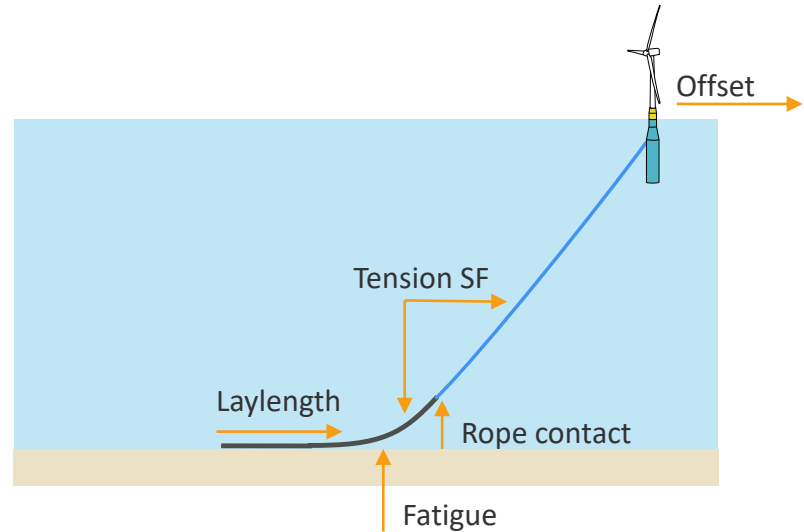


## Tools:

- LineDesign: quasi-static mooring line optimizer
- MoorPy: quasi-static mooring line model
- OpenFAST: wind turbine simulation tool
- MoorDyn: lumped mass mooring line dynamics model

# Design Constraints

Constraint	Catenary	Taut	Semi-taut
Tension safety factor	X	X	X
Fatigue damage	X		X
Platform offset	X	X	X
Chain laylength	X		X
Rope contact		X	X



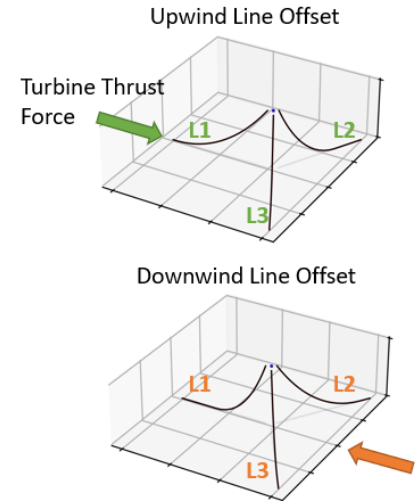
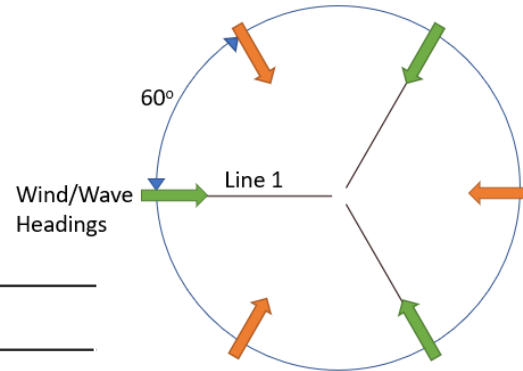
# Environmental Conditions

## Extreme load cases:

DLC	1.6
Wind speed (m/s)	10.59
Hs (m)	8.0
Tp (s)	12.7

## Fatigue load cases:

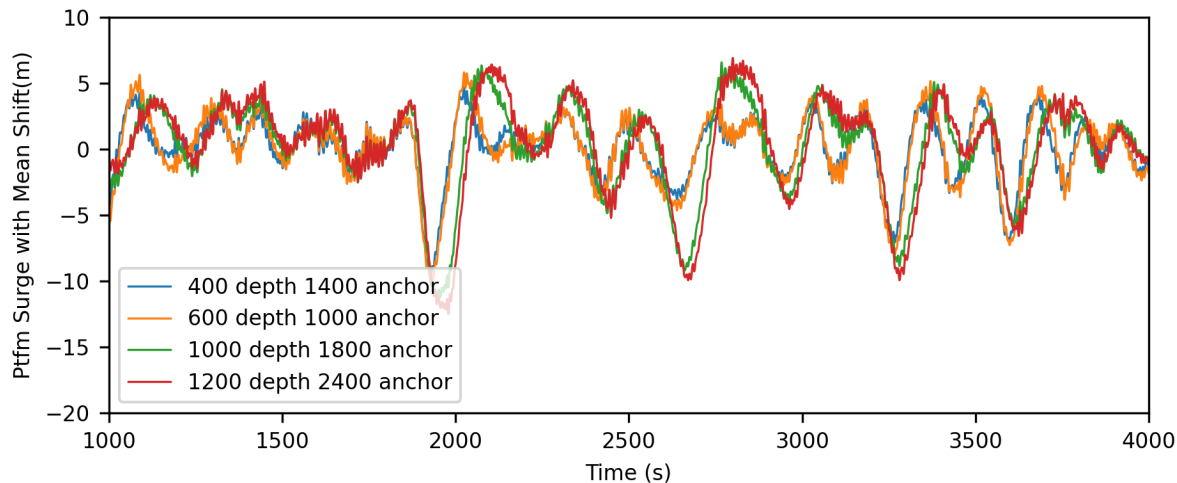
Load Case	1	2	3
Wind speed (m/s)	10	12	14
Hs (m)	1.54	1.84	2.19
Tp (s)	7.65	7.44	7.46
Probability	34.2%	35.4%	30.4%



# Simulation Approach

~300 moorings x 7 load cases x ~5 iterations = 10500 simulations

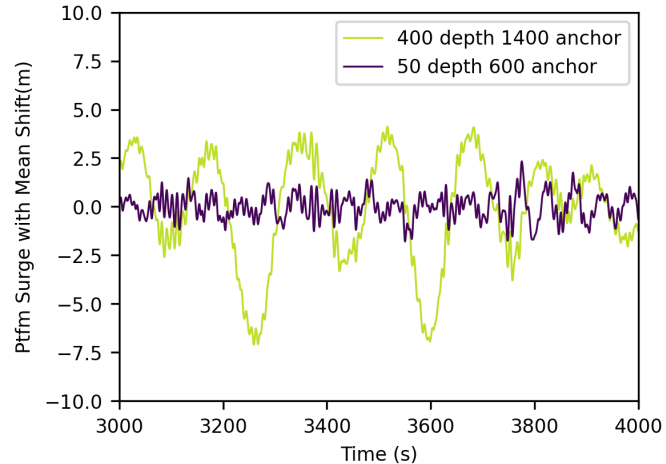
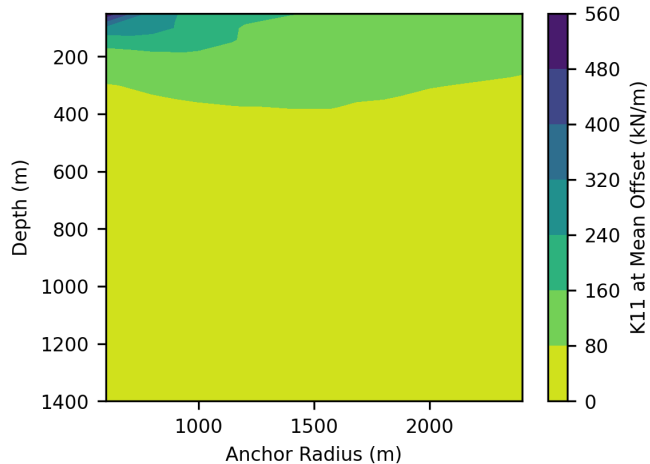
Simplification: platform oscillations are similar across mooring systems for a range of depths and anchor spacings



# Simulation Approach

Simplification: platform oscillations are similar across mooring systems for a range of depths and anchor spacings

Except in shallow water!

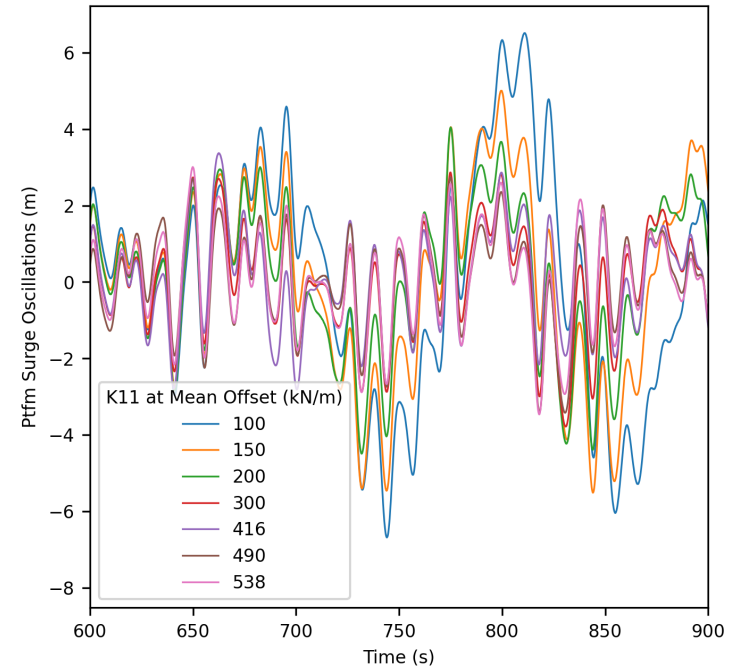




# Overall Procedure

1. Optimize initial mooring designs
2. Simulate a subset in OpenFAST and extract platform motion time series (**motions**)
3. Apply turbine load in MoorPy to get mean offset (**mean**)
4. Simulate in MoorDyn driver with prescribed platform motions (**mean + motions**)
5. Evaluate tensions and fatigue damage
6. Reoptimize mooring designs with dynamic inputs

## Platform Motions Library

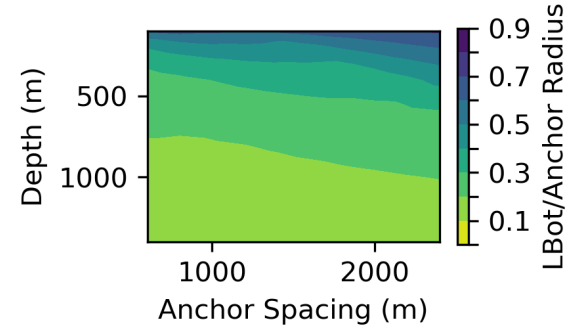
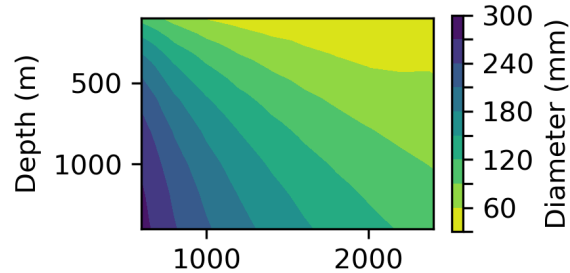
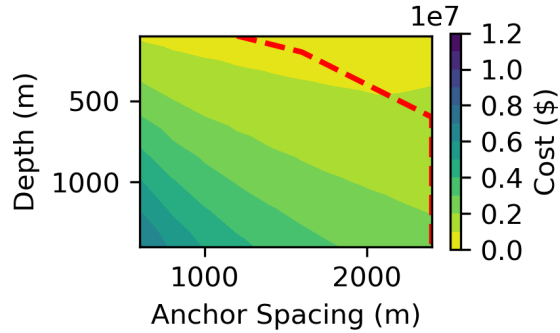


# Results

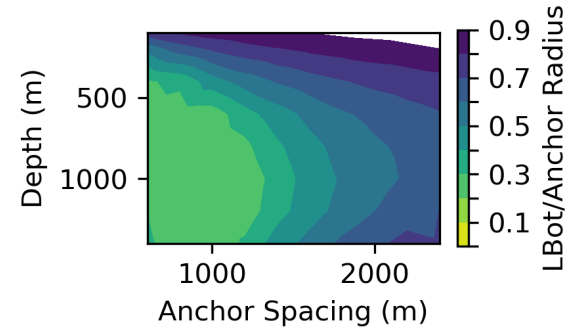
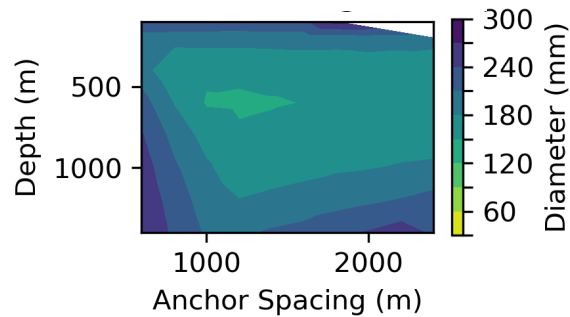
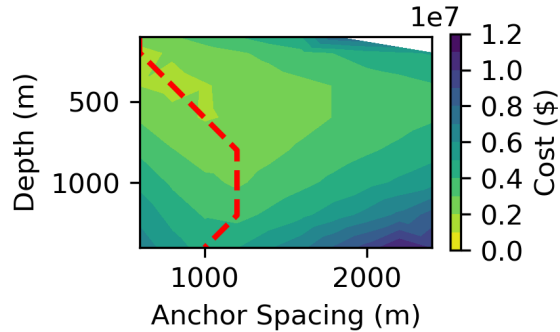
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# Catenary Results

## Initial Designs



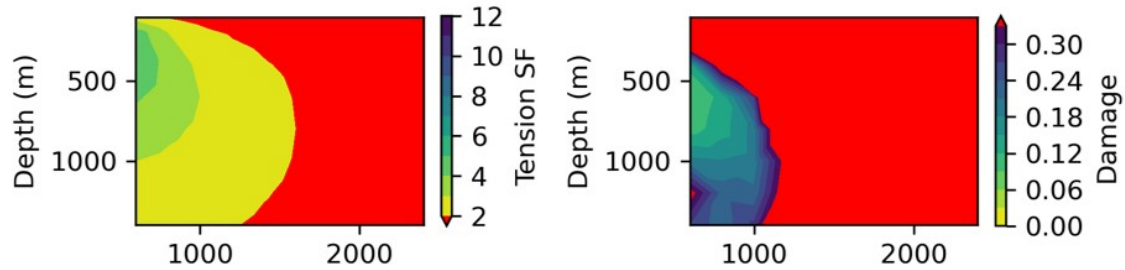
## Final Designs



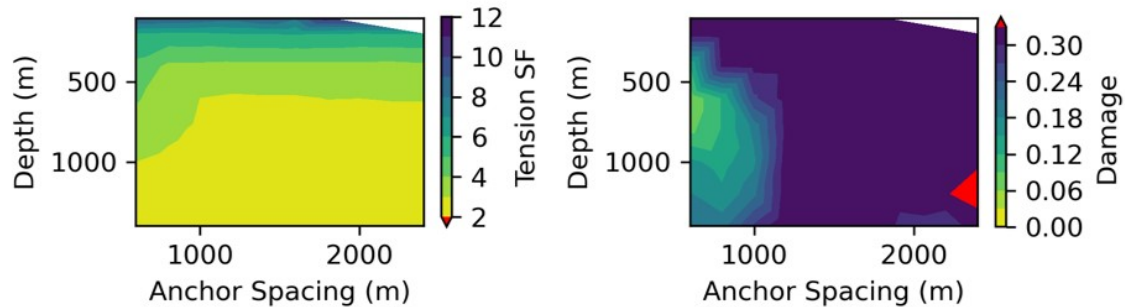
--- Least-cost spacing

# Catenary Results

## Initial Designs

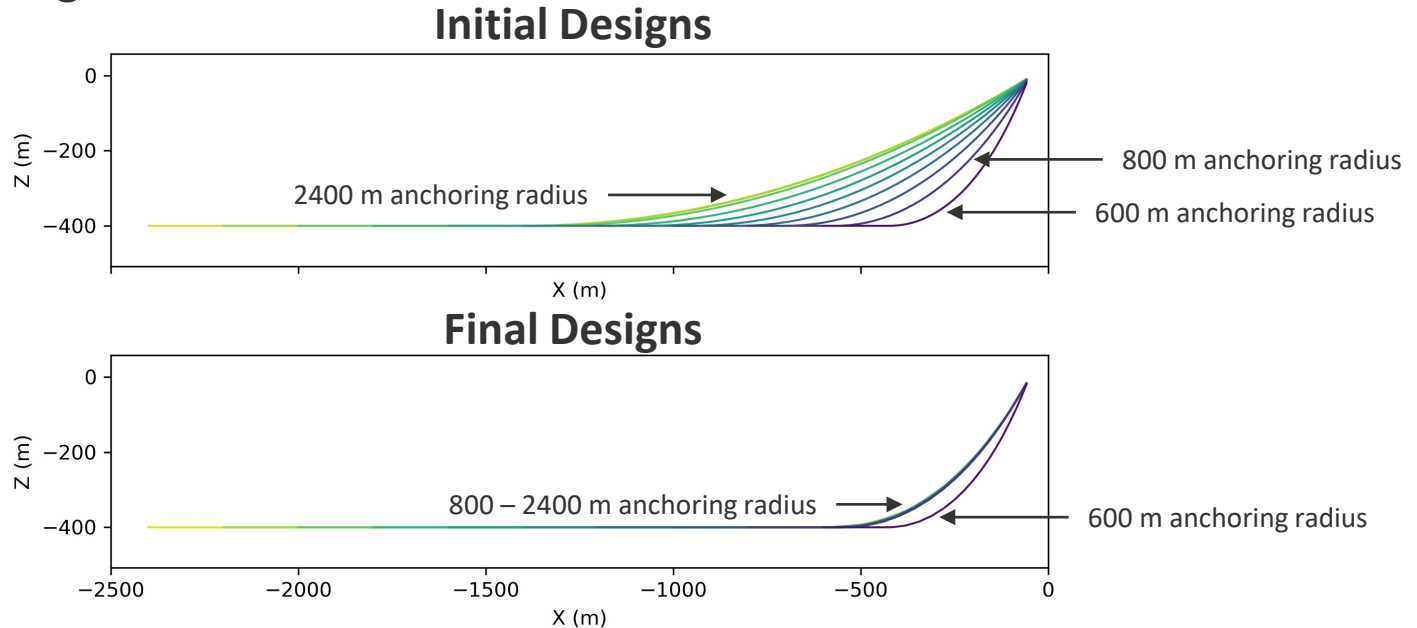


## Final Designs



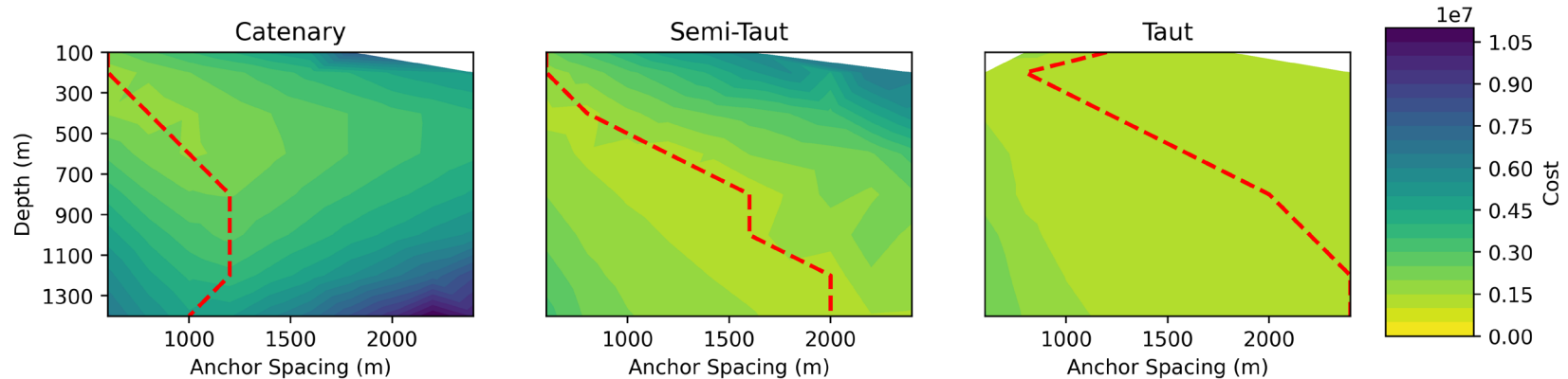
# Catenary Results

Dynamic performance iterations significantly change the profile of the mooring designs



# Conclusions

- Able to map patterns in optimal mooring systems and make comparisons
- Full design and performance for range of mooring systems
  - Mooring line lengths and diameters, anchor sizes, cost breakdown
  - System performance: mean and extreme offsets, tensions, line motions



# Q&A

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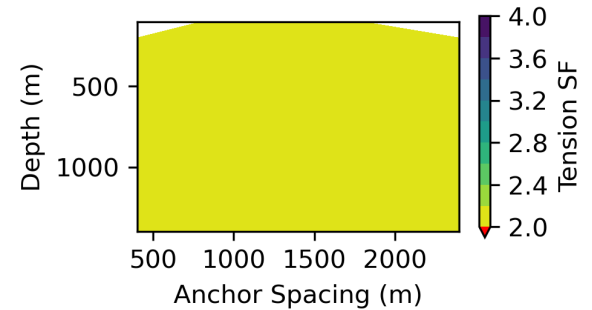
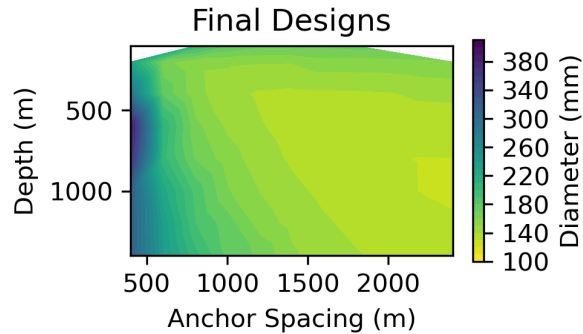
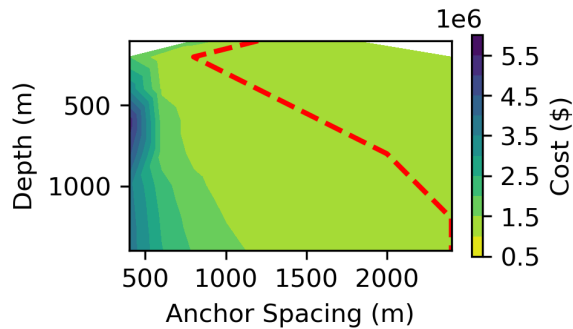
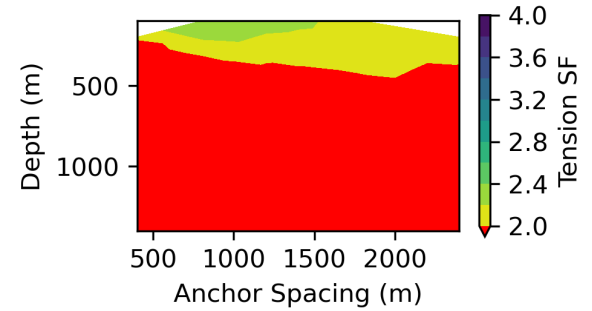
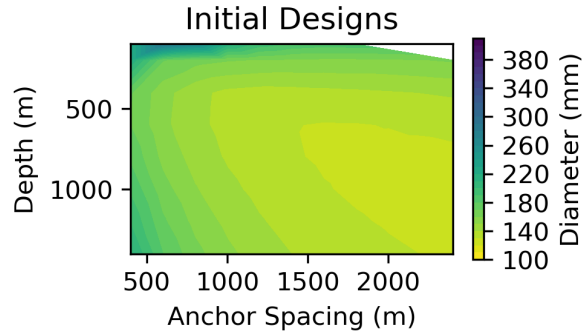
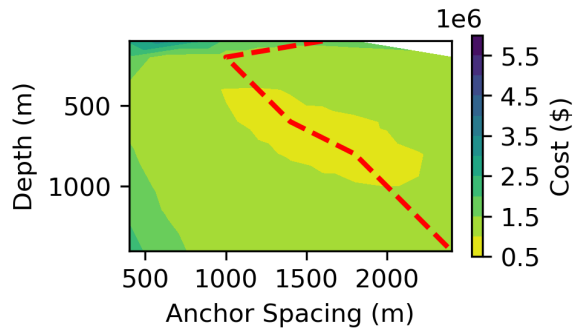
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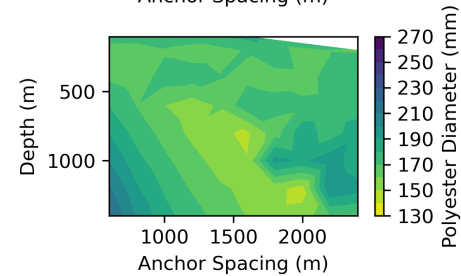
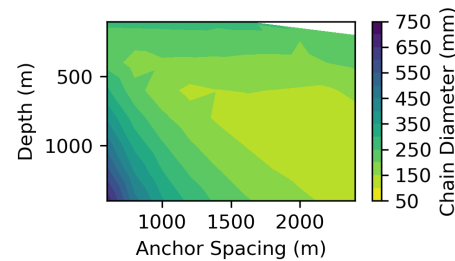
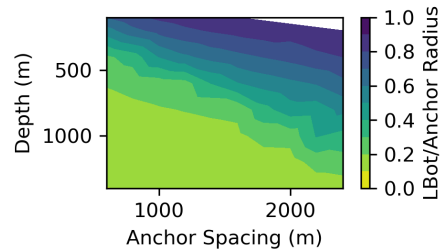
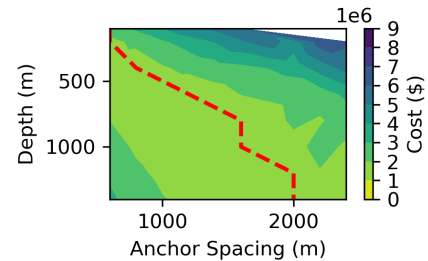
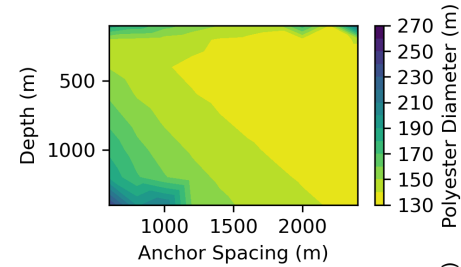
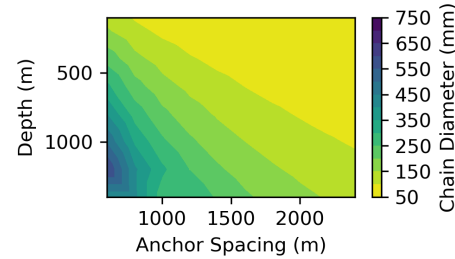
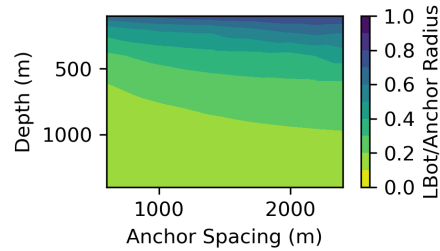
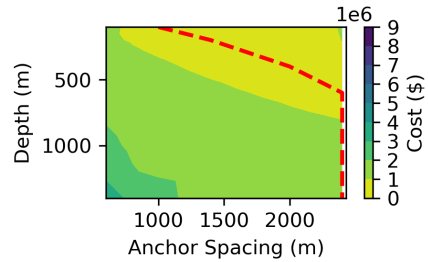


# Taut Results

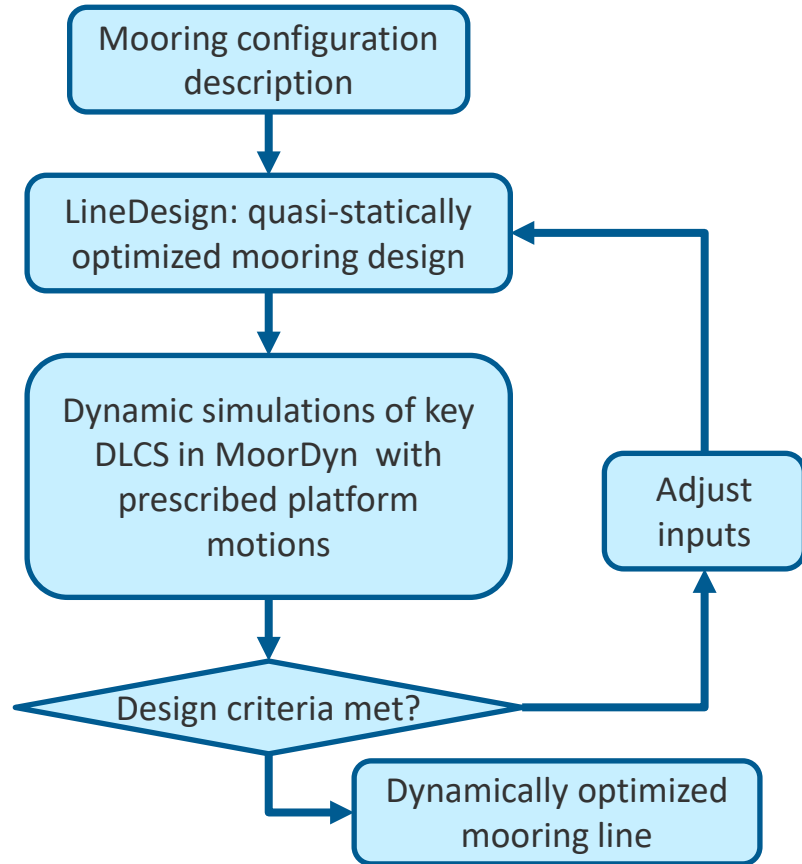




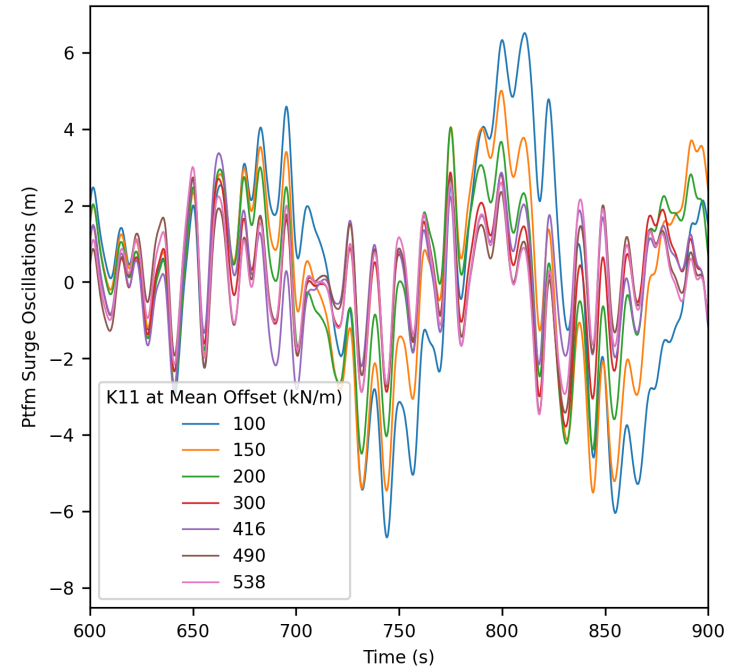
# Semi-taut Results



# Design and Analysis Procedure



## Platform Motions Library



# Allowable Platform Offset

