

## EFFECT OF WIND TURBINE YAW MISALIGNMENT ON WAKE MEANDERING

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### Outline

- Motivation and Introduction
- Methods and tools
- Dynamic wake meandering model (DIWA)
- Results and discussion
- Conclusions



#### Introduction and Motivation

- Empirical models for steady state wake calculation
  - Jiménez et al. [1] presented a preliminary a wake deflection model based on LES results
  - Bastankhah and Porté-Angel [2] developed an analytical model to predict the wake deflection using wind tunnel.
  - Qian and Ishihara [3] developed an Analytical Wake Model for based on RANS simulations
- Validity of these models for large scale wind turbines
- Can we use these yaw deflectiom models with meandering in dynamic wake meandrering program (DIWA)



#### Methods and tool

- RANS and LES for understanding the effect of yaw on wake deflection
- OpenFoam transient PisoFoam solver
- Actuator line model for the wind turbine
- RANS: K-epsilon turbulence model
- LES: Smagorinsky model
- Inflow conditions
  - Uambient = 8 m/s, TI = 10%
- Three yaw angles
  - 0, 10 and 20 degree





# RANS CFD studies of NREL 5MW without and with yaw



Yaw = 20

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Yaw = 0

#### NRE5MW: Verification of Yaw with CFD models



Yaw = 10 degree

Yaw = 20 degree

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#### Velocity deficit



With yaw (10 degree)

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Without yaw

#### 12 MW: Verification of Yaw with CFD models



Yaw = 10 degree

Yaw = 20 degree

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#### Velocity deficit (12 MW)



with yaw

without yaw



# Transient inflow condition: Meandering study (Yaw effect)



CFD domain OpenFoam (Actuator line model for wind turbine)



#### **Coupled results**





#### Implementation with meandering (Static yaw)

- Wake position due to yaw
  - $Y_d = \theta * X_k$  ( $\theta$  is wake deflection angle)
- Wake meandering positions
  - $Y_{k+1} = Y_k + v \Delta t + Y_d$
  - $Z_{k+1} = Z_k + w \Delta t$

Accounting of wake deflection in meandering velocity calculation



#### DIWA

- Wake model: Dynamic Wake Meandering modell
  - As recommended in the IEC standard (IEC 61400-1:2019)
- Aerodynamics: BEM with stiff blades.
- Wind turbine control: Cp-Ct curves as input, together with rotor speed and blade pitch angle and wind speed
- Turbulence boxes as input



#### CFD results with and without yaw





### Various methods of Wake center estimation [ref:4]

- Gaussian based approaches
  - 1-D Gaussian
  - 1-D Gaussian (Ideal Sigma)
  - 1-D Gaussian (Bastankhah)
  - 2-D Gaussian
- "constant momentum deficit" : The momentum or energy flux through the enclosed region
- "Constant area": A wake may be identified by contours that have a *constant area*
- Maximum power
- Deficit weighted average method





#### Wake center position in Y direction (X/D = 8)



Red: Without yaw Black: With yaw

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Time (s)

#### Wake center position in Z direction (X/D = 8)



Time (s)

(NREL5MW: Yaw =10)



Un-accounting of wake deflection in meandering velocity calculation

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Accounting of wake deflection in meandering velocity calculation

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(NREL5MW: Yaw = 20)



meandering velocity calculation

#### Conclusions

• Jimenez model overpredicts the wake deflection

• For large wind turbines (>5MW) Bastankhah, Shapiro, and Qian model underpredicts the initial wake deflection compared with current RANS simulations

• Need for better wake center tracking method

• The yawed turbine only affects meandering in horizontal plane

 Preliminary studies showed that effect of wake deflection can be directly added to the wake center positions in horizontal plane

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#### References

- [1] Jiménez et al, Application of a LES technique to characterize the wake deflection of a wind turbine in yaw, Journal of Wind energy, 2010
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- [4] Elon Quon, https://ewquon.github.io/waketracking/





#### Teknologi for et bedre samfunn