



Design Optimization of Floating Offshore Wind Turbine Substructures using Frequency Domain Dynamic Model and Genetic Algorithm

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High potential Worldwide, particularly in Europe









□ High potential Worldwide, particularly in Europe

Higher wind loads and extreme sea state











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Different type of substructures











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Complex manufacturing and low production rate











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High Levelized Cost of Energy



 ${}^{34^\circ N}_{25^\circ W}$

 $3^{\circ}W$

 $8^{\circ}E$

 $29^{\circ}E$

 $-14^{\circ}W$

[1]















Steel and concrete Tension Leg Platform









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Simple manufacturing and installation process

- 4 buoyancy bodies
- diagonal, vertical and horizontal pipes









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□ Numerical and experimental analysis



[2]







□ Steel and concrete Tension Leg Platform

Simple manufacturing and installation process

- 4 buoyancy bodies
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□Numerical and experimental analysis

Optimization framework for the design of the Universal Buoyancy Body (UBB)



[2]













□Numerical model: frequency domain dynamic model

Numerical model







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Optimizer: genetic algorithm









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Design parameterization: geometrical









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Objective: minimize the substructure's mass/cost









Numerical model: frequency domain dynamic model

Optimizer: genetic algorithm

Design parameterization: geometrical

Objective: minimize the substructure's mass/cost

Constraints: system's dynamic response















Numerical model







Numerical model

Response Amplitude for Floating Turbine (RAFT)

Open-source frequency domain code for FOWT







Numerical model

- Open-source frequency domain code for FOWT
- Verified against time domain OpenFAST simulations







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- Aerodynamics: steady-state Blade-Element-Momentum theory







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- Hydrodynamics: strip-theory for all submerged members







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- Aerodynamics: steady-state Blade-Element-Momentum theory
- Hydrodynamics: strip-theory for all submerged members
- Moorings: quasi-static model



















GICON-TLP with IEA 15-MW wind turbine

mass and hydrostatic properties









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- Inear hydrodynamic coefficients and mean aerodynamic load









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- solve mean offset position $\mathbf{C}_{struc} \, \bar{\boldsymbol{\xi}} = \bar{\mathbf{f}}_{aero} + \bar{\mathbf{f}}_{hydro} + \bar{\mathbf{f}}_{moor}(\bar{\boldsymbol{\xi}})^{[4]}$









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- compute linearized viscous drag excitation and damping
- solve system's dynamic response until convergence

 $(-\omega^{2}[\mathbf{M}_{struc} + \mathbf{A}_{sub}(\omega) + \mathbf{A}_{aero}(\omega)] + i\omega[\mathbf{B}_{sub}(\omega) + \mathbf{B}_{aero}(\omega)] + \mathbf{C}_{struc} + \mathbf{C}_{moor})\hat{\boldsymbol{\xi}}(\omega) = \hat{\mathbf{f}}(\omega)^{\mathbf{H}}$









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- compute linearized viscous drag excitation and damping
- solve system's dynamic response until convergence
- get system's mean offset and extreme values from standard deviations (RMS) of the response spectra.













Design parameterization











MSL

Design parameterization upper node diagonal pipe [5] □IEA 15MW wind turbine: • $D_{rot} \sim 240 \ m, RNA_{mass} \sim 1000 \ t$ vertical pipe • $H_{hub} \sim 150 \text{ m}, L_{tower} \sim 120 \text{ m}$ -----...... horizontal pipe This project has received funding from the European Union's Horizon 2020 research and innovation programme under morring line the Marie Skłodowska-Curie grant agreement N° 860879. EHRSTUHL WINDENERGIETECHNIK





Design parameterization

□IEA 15MW wind turbine:

- $D_{rot} \sim 240 m$, $RNA_{mass} \sim 1000 t$
- $H_{hub} \sim 150$ m, $L_{tower} \sim 120$ m

Mooring lines:

- $d \sim 0.15 m$, $\rho \sim 120 kg.m^{-1}$
- $E_A \sim 2 .10^9$ N, $L \sim 150 m$











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Design variables:

- length L_{UBB} and diameter D_{UBB}
- center *z*_{UBB}

















Often used for FOWT optimization studies







Often used for FOWT optimization studies

[6]

Cumulative: population extends







Often used for FOWT optimization studies

Cumulative: population extends

Fitness: -1 * M_{substructure}







Often used for FOWT optimization studies

Cumulative: population extends

Fitness: -1 * M_{sub}

Constraint handling technic: efficient penalty function







Often used for FOWT optimization studies

Cumulative: population extends

Fitness: -1 * M_{substructure}

Constraint handling technic: efficient penalty function

Fitness scaling and addition operation:

- global and Local optima
- fewer fitness function evaluation





























Optimizer: Genetic Algorithm Indiviudal Optima Latin Hypercube Initial population Sampling scale fitness to Fitness scaling population optima





















crosover

Optimizer: Genetic Algorithm











































FLOAting Wind Energy network

Genetic Algorithm







































Object Oriented (python)









Object Oriented (python)

Modular approach









Object Oriented (python)

Modular approach

Multiprocessing









Object Oriented (python)

Modular approach

Multiprocessing

Easy to use (GUI)















Study case:

GICON-TLP with IEA15 MW







FLOAKER FLOAKER

Results

Study case:

GICON-TLP with IEA15 MW

Environmental condition:

• $U_w = 12 \text{ m.s}^{-1}$, $H_s = 4 \text{ m}$, $T_p = 12 \text{ s}$







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Constraints:

- TwrBenMom < 6.10⁸ Nm
- H_{offset}< 5 m
- V_{offset} < 2 m</p>
- Pitch < 3°</p>







FLOA WE

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GA Parameters:

- Initial population size: 10
- Max population size: 1000
- max generation number: 300



























FLOAting Wind Energy network















Conclusion & Outlook

- \checkmark Model of the GICON-TLP with IEA 15 MW
- ✓ Asses its dynamic in the frequency domain using RAFT
- \checkmark Design optimization framework coupling a genetic algorithm with RAFT
- ✓ Preliminary results with minimized material cost and verified constraints
- Enhance hydrodynamic model
- >Compare numerical model with time domain model and experimental data
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References

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