

EERA DeepWind Conference 2022

Installation and sub-structures

Paper number: 46

A parametric optimization approach for the initial design of FOWT's substructure and moorings in Brazilian deep-water fields

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Tanque de
Provas Numérico
da USP



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Agenda

- 1) Introduction
- 2) Methodology
- 3) Optimization Framework
- 4) Case Study
- 5) Conclusions

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Introduction



Interest from energy majors in the **renewable electrification of Offshore Production Units**



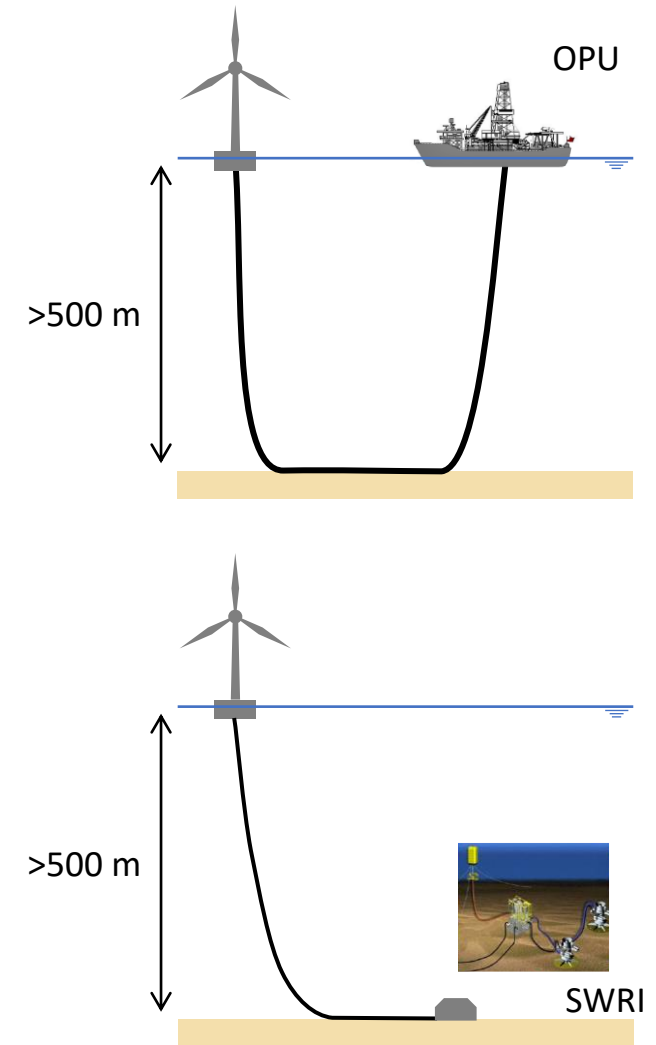
Offshore operations account for more than **90%** of the total amount of **Brazil's O&G production**



Renewable on offshore O&G operations: may help to **meet the environmental regulations** and **maximize production**.



Brazilian scenario challenges: **long distances from shore** and **deep-water conditions** (500 m – 2000 m)

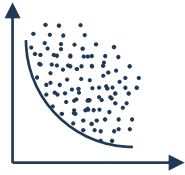


Objective

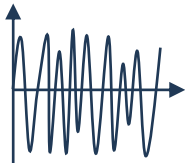
Parametric site-specific optimization of FOWT's hull and mooring systems

- 1) Introduction
- 2) Methodology**
- 3) Optimization Framework
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- 5) Conclusions

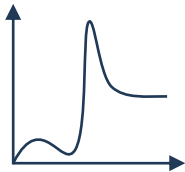
Methodology



FOWT hull and mooring design using an **optimization framework** based on the **Multi-Niche Crowding Genetic Algorithm strategy** – similar to Hall et al. (2013) and Karimi et al. (2017)



Assessment of **hull-mooring coupled dynamics** and fulfillment of the safety class requirements using **site-specific** data: adoption of **long-term environmental series** (12y)



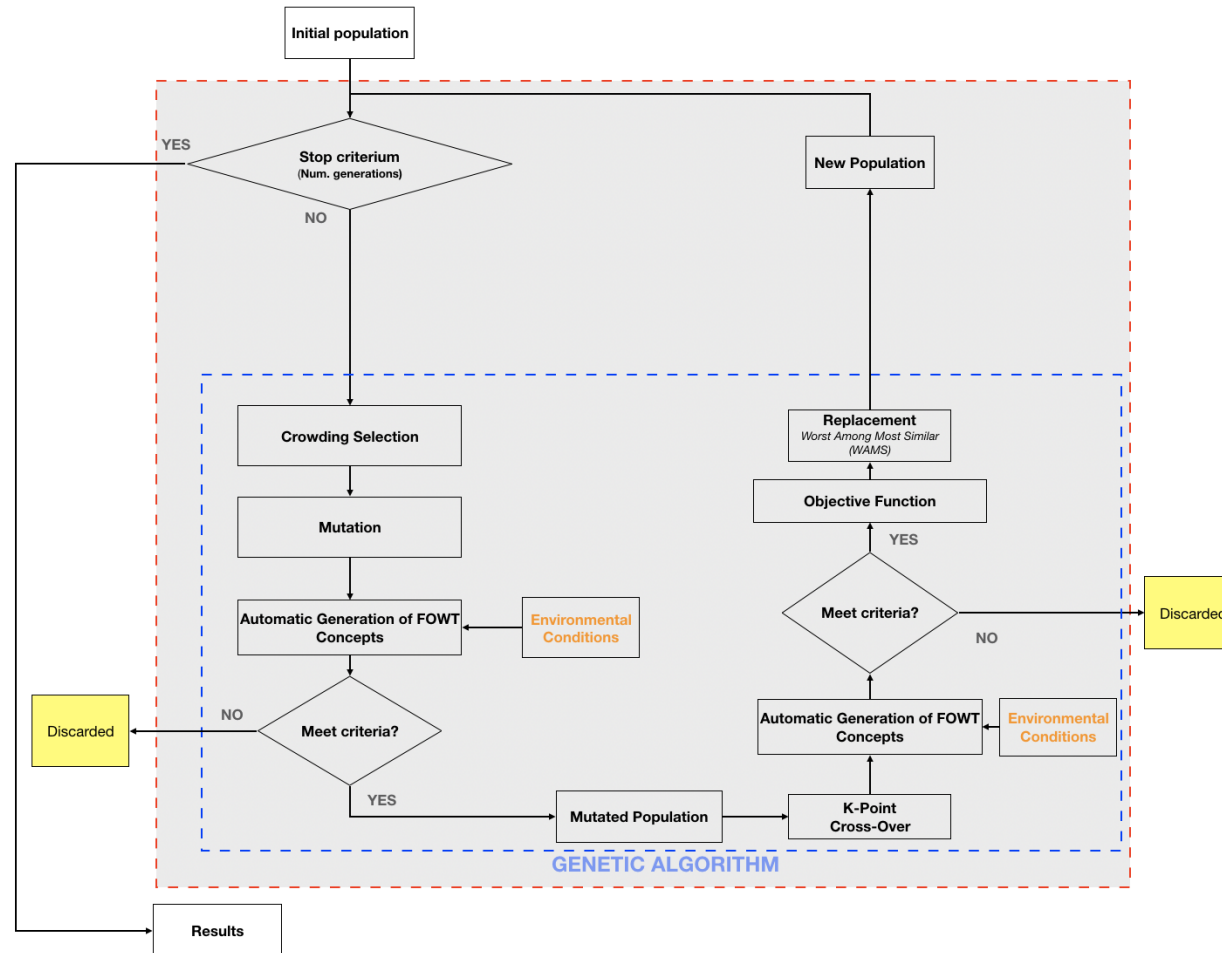
Frequency domain modelling and the **explicit formulation for the stiffness matrix** around a generic offset position



Floater motion responses are investigated by means of **nacelle horizontal acceleration RAOs** at each sea state condition

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Optimization Framework (1/6)



Optimization Framework (2/6)

Cost function:

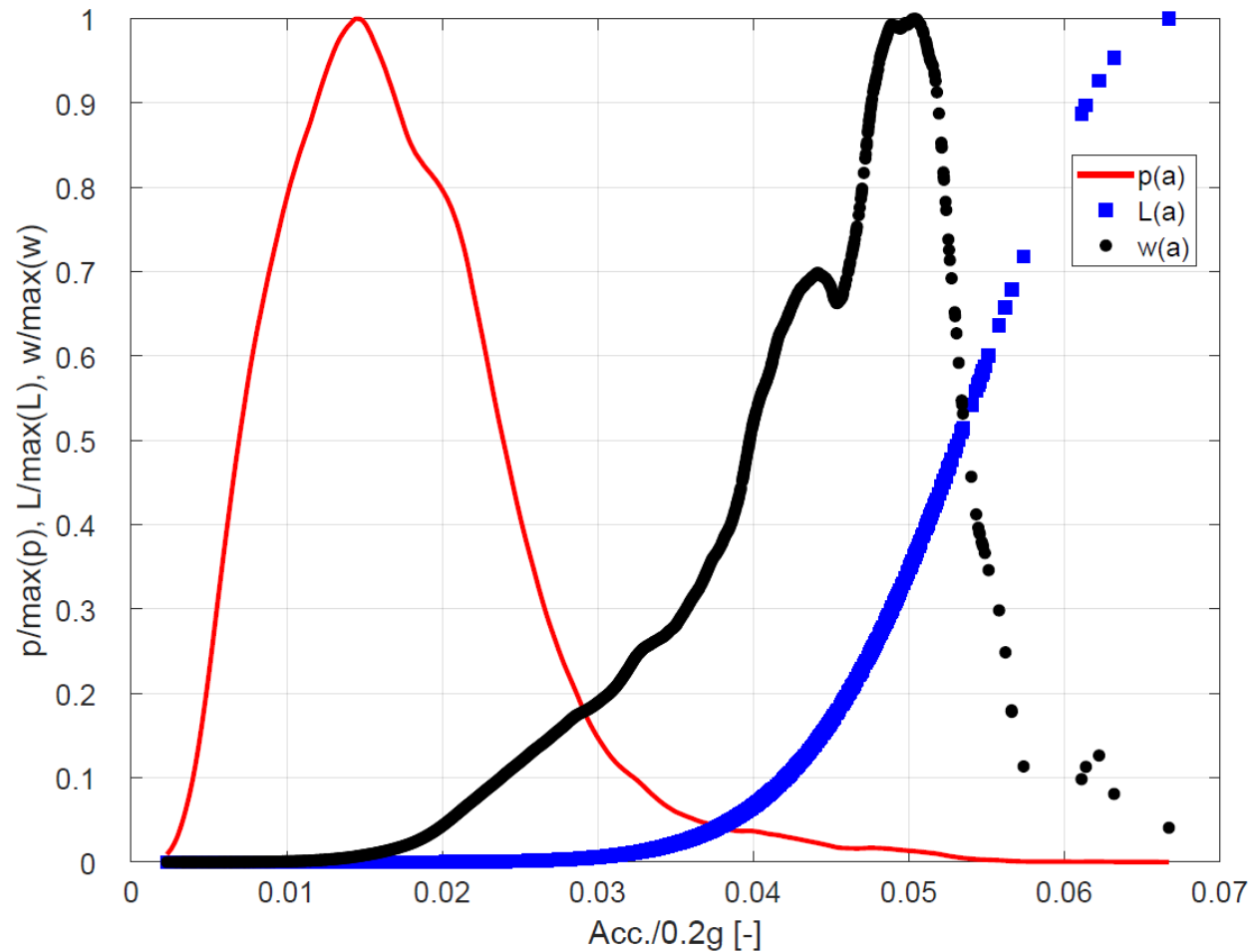
Performance evaluation:
Weighted nacelle horizontal acceleration

$$\min\{F\} = \min \left\{ \left[Cost_{CAPEX}^{hull}, Cost_{CAPEX}^{mooring} \right], \left[\sum_{i=1}^N \left(w_i \cdot \frac{a_i}{0.2g} \right) \right] \right\}$$

Cost model:
Bjerkseter and Agotnes (2013)
and Karimi et al. (2017)

CAPEX	Description	value	Units
Hull	Acquisition & Manufacturing	2.100,00	[USD/ton]
Mooring Chain	Acquisition	2.000,00	[USD/ton]
Mooring Synthetic	Acquisition	2.800,00	[USD/MBL _{ton} · m]
Anchors	Acquisition	DEA: 100; VLA: 120; SPA: 150	[USD/kN/un]

Optimization Framework (3/6)



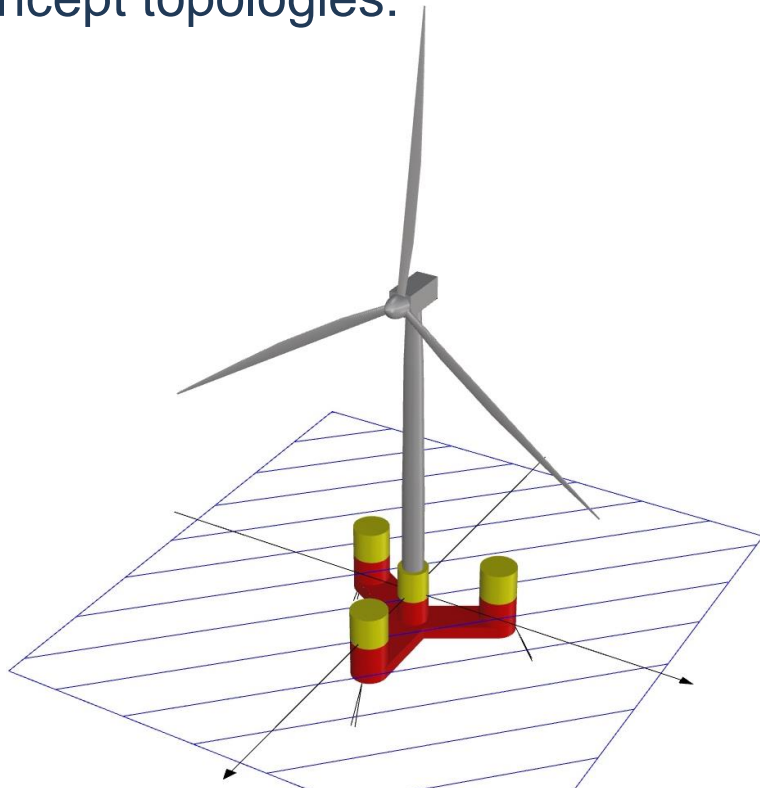
$p(a)$: empirical probability function of occurrence of accelerations

$L(a)$: distribution discriminating the lowest values of acceleration

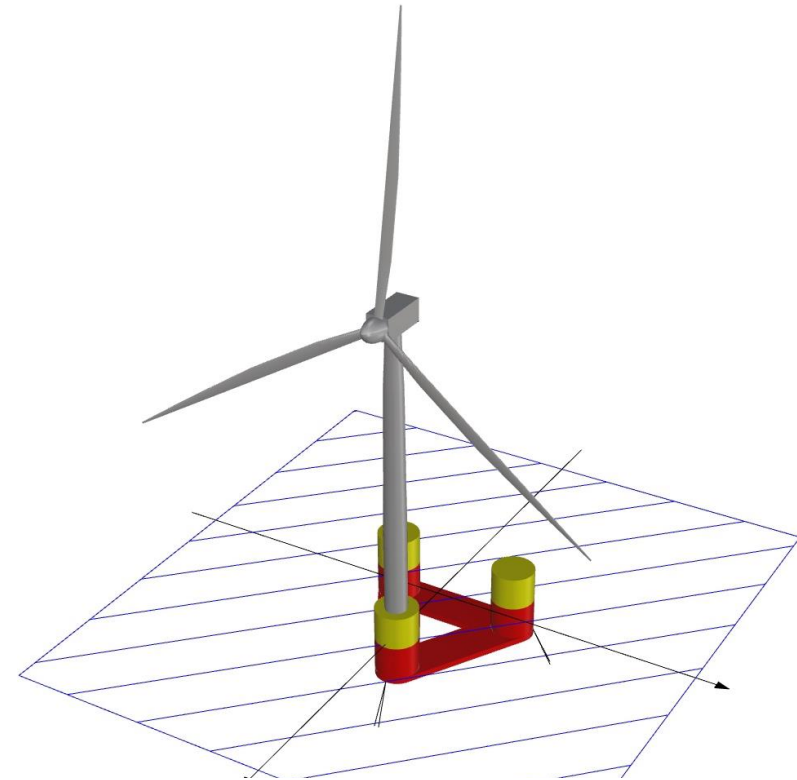
$w(a)$: weights for each acceleration

Optimization Framework (4/6)

Hull concept topologies:



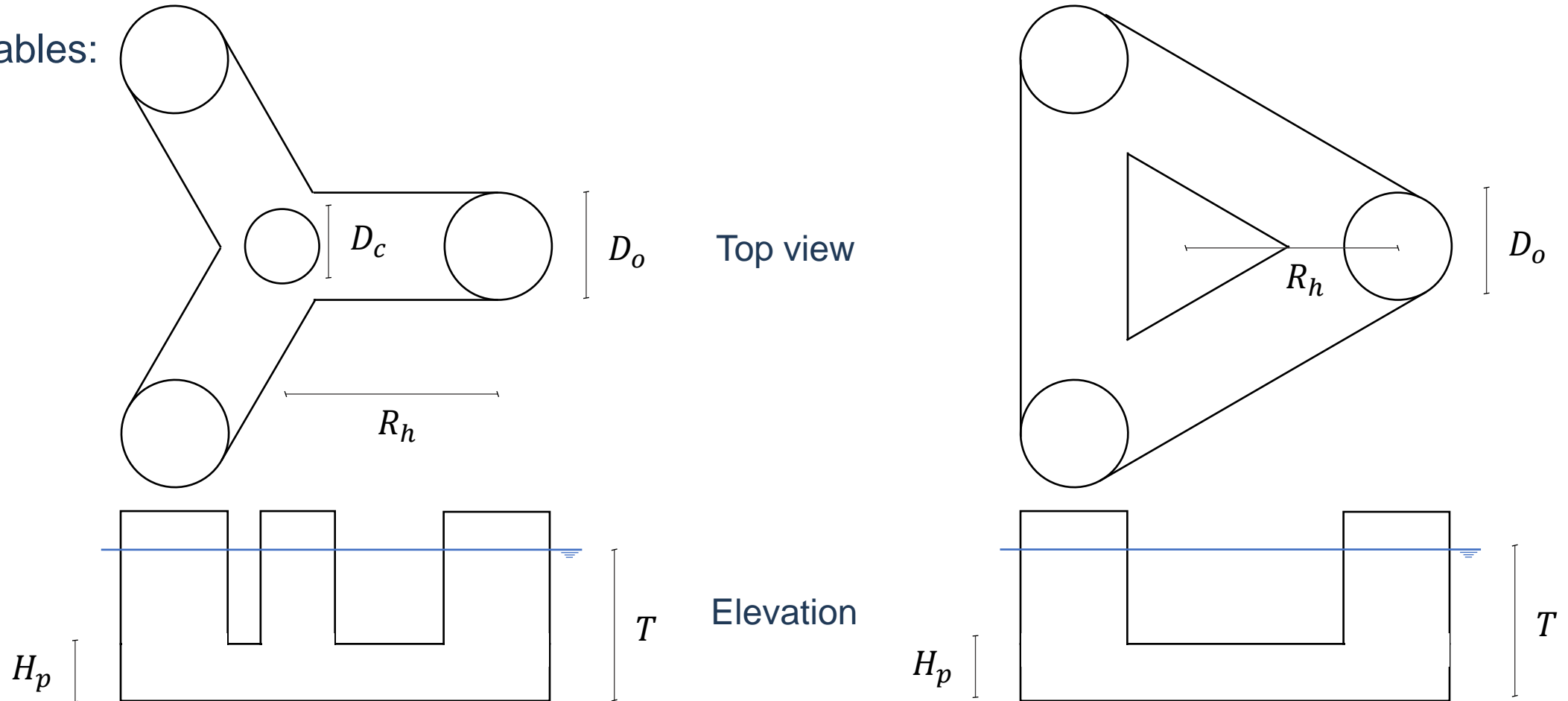
FOWTC



FOWTO

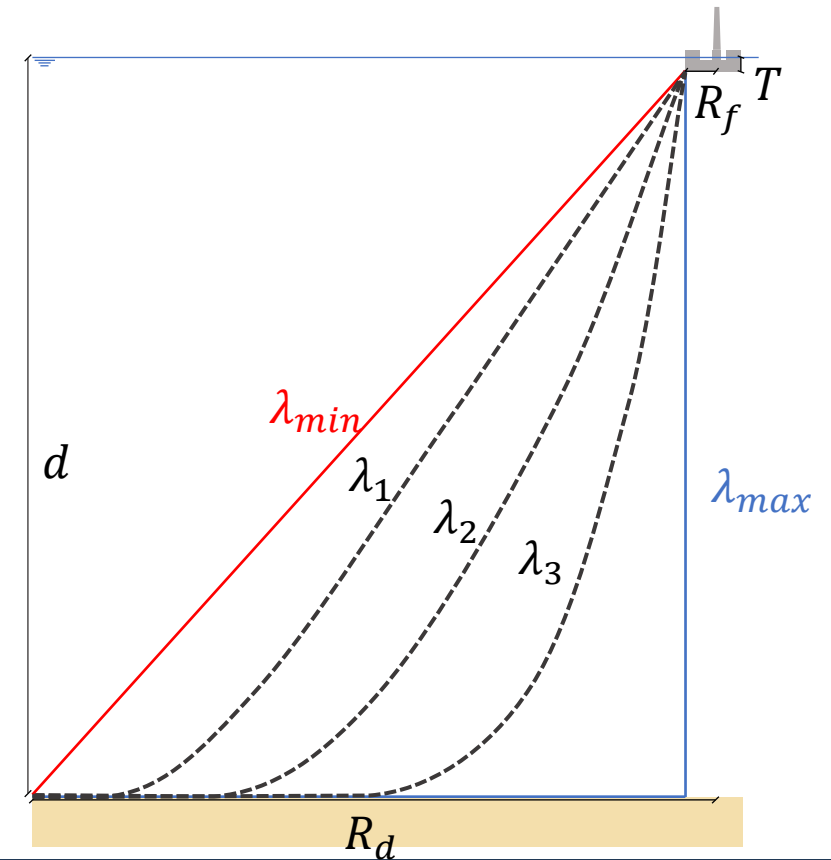
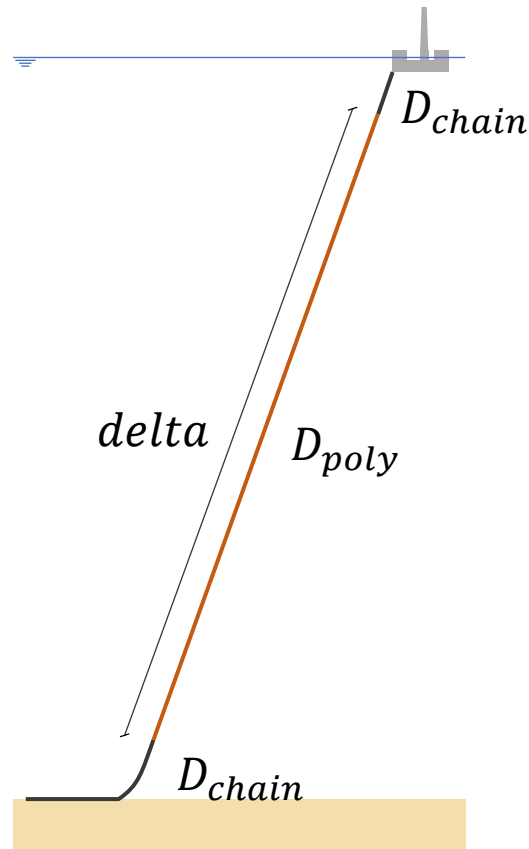
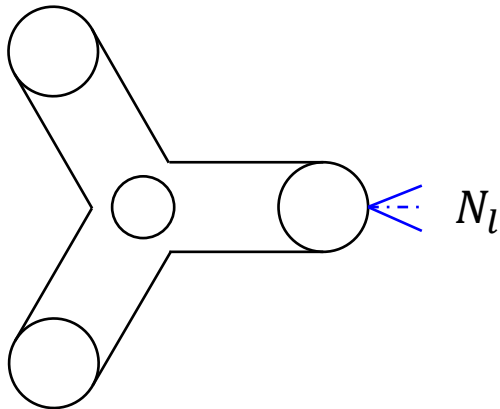
Optimization Framework (5/6)

Hull variables:



Optimization Framework (6/6)

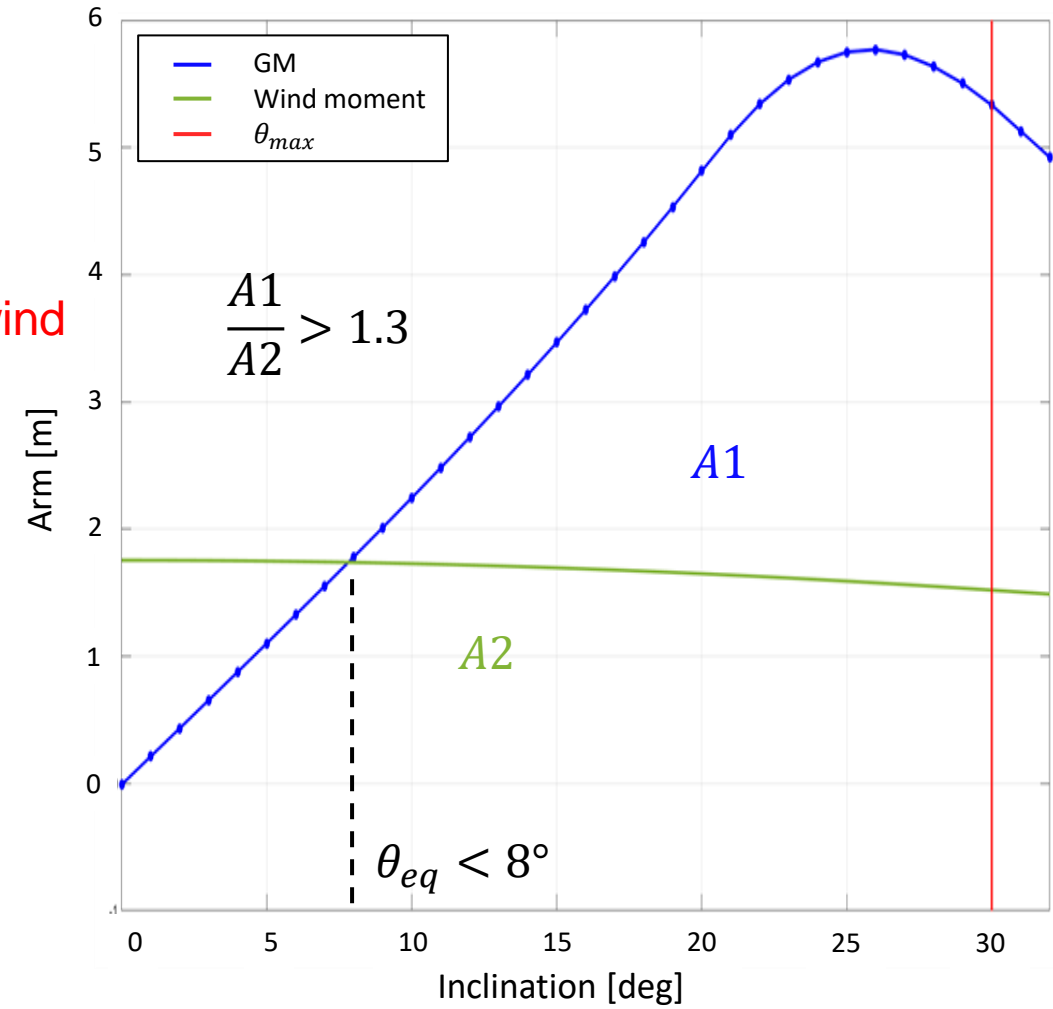
Mooring system variables:



Optimization Framework (7/7)

Constraints and Criteria:

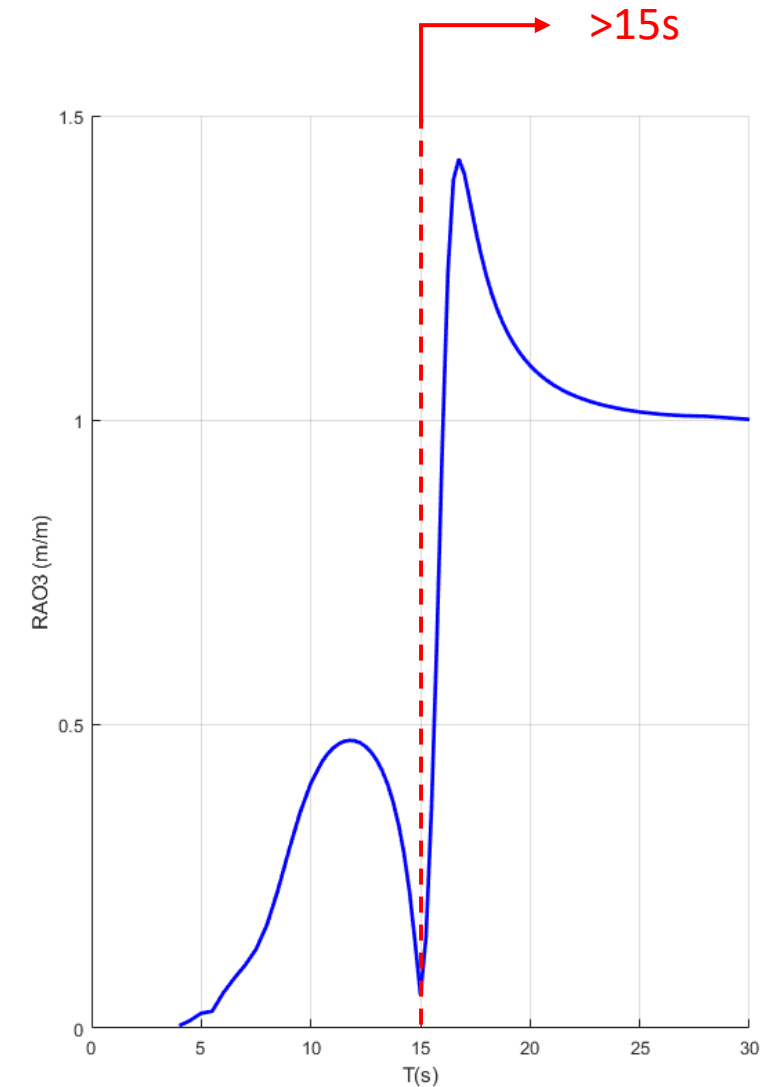
- Intact stability and maximum heeling angle due to wind
- Heave period
- Bending stress
- Maximum offset
- Mooring lines safety factor



Optimization Framework (7/7)

Constraints and Criteria:

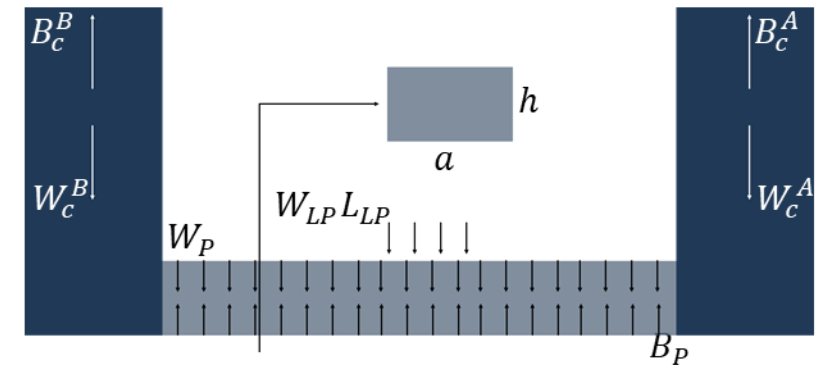
- Intact stability and maximum heeling angle due to wind
- **Heave period**
- Bending stress
- Maximum offset
- Mooring lines safety factor



Optimization Framework (7/7)

Constraints and Criteria:

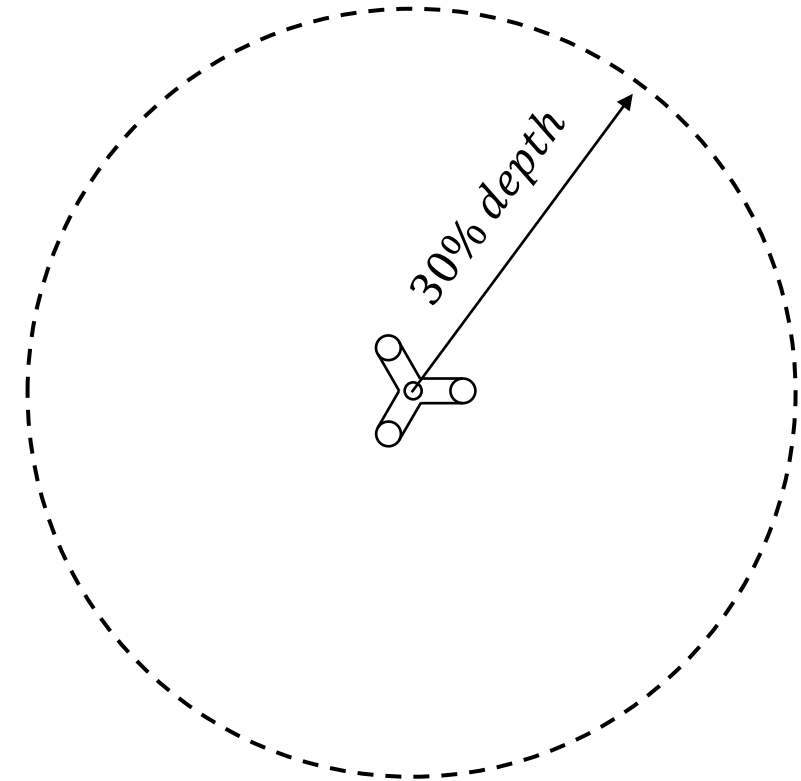
- Intact stability and maximum heeling angle due to wind
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- Maximum offset
- Mooring lines safety factor



Optimization Framework (7/7)

Constraints and Criteria:

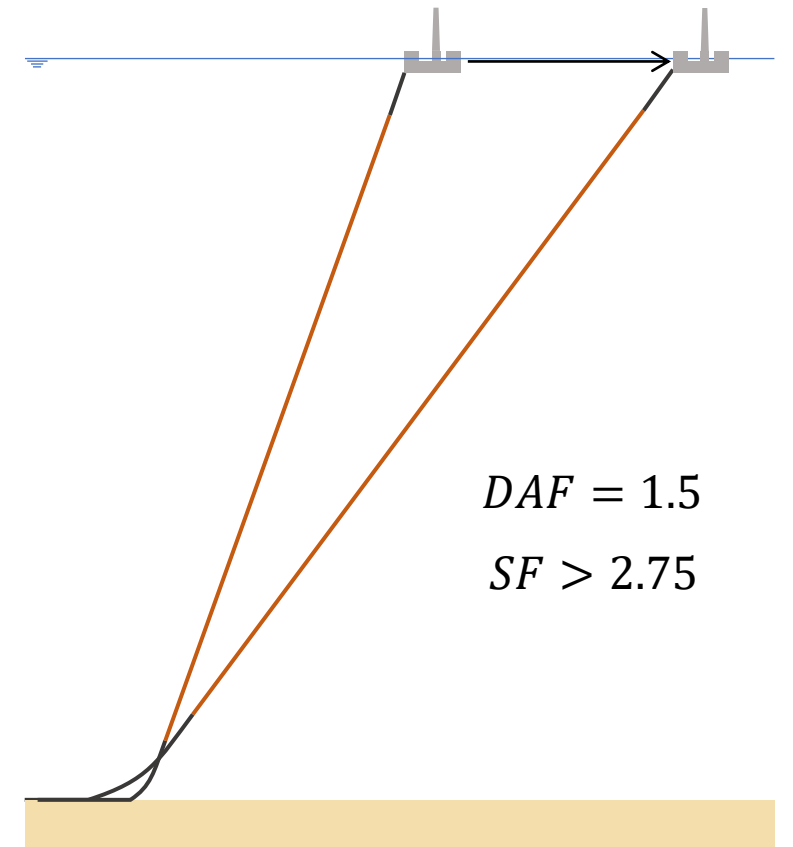
- Intact stability and maximum heeling angle due to wind
- Heave period
- Bending stress
- **Maximum offset**
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Optimization Framework (7/7)

Constraints and Criteria:

- Intact stability and maximum heeling angle due to wind
- Heave period
- Bending stress
- Maximum offset
- **Mooring lines safety factor**

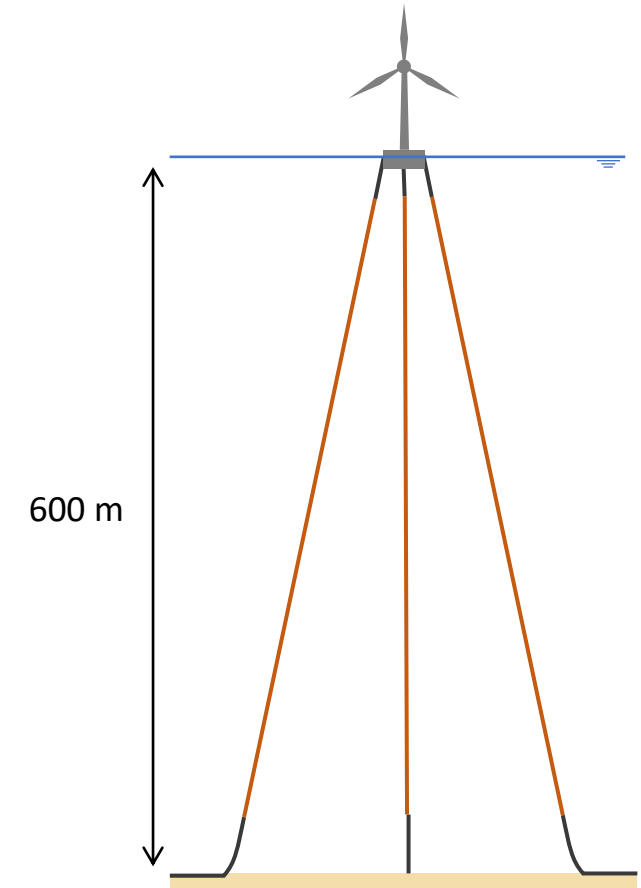
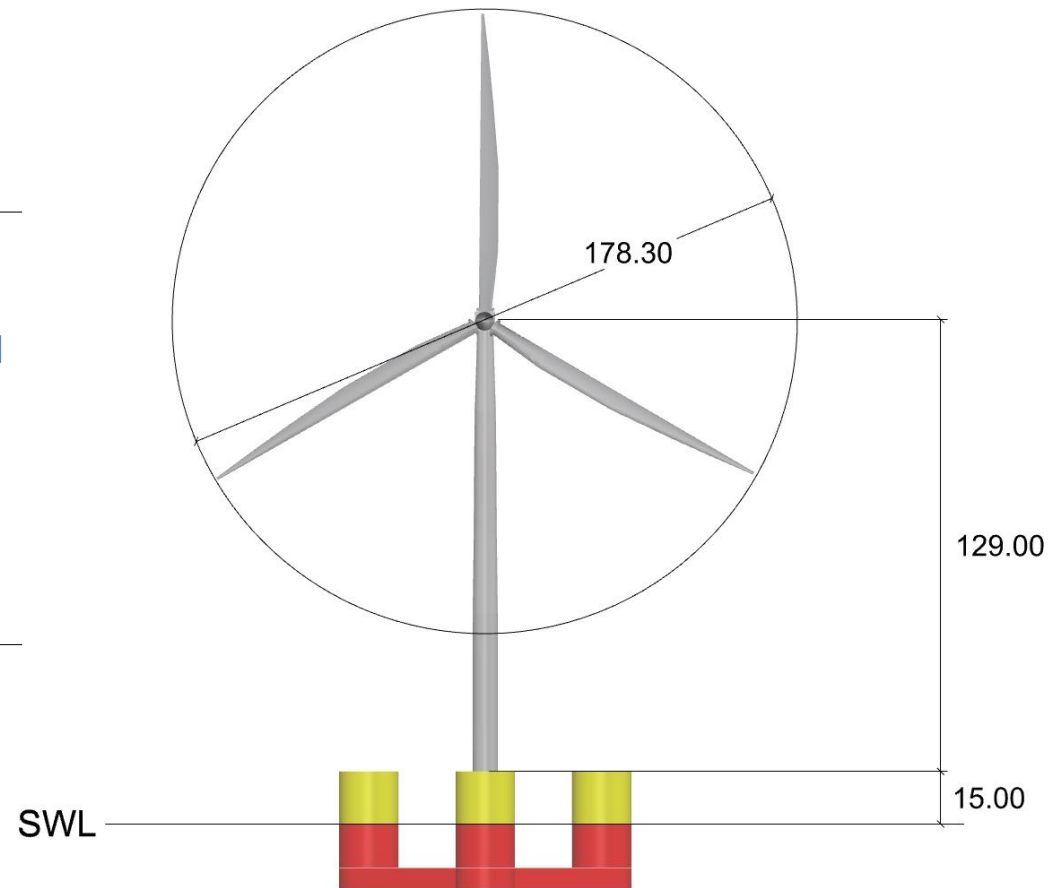


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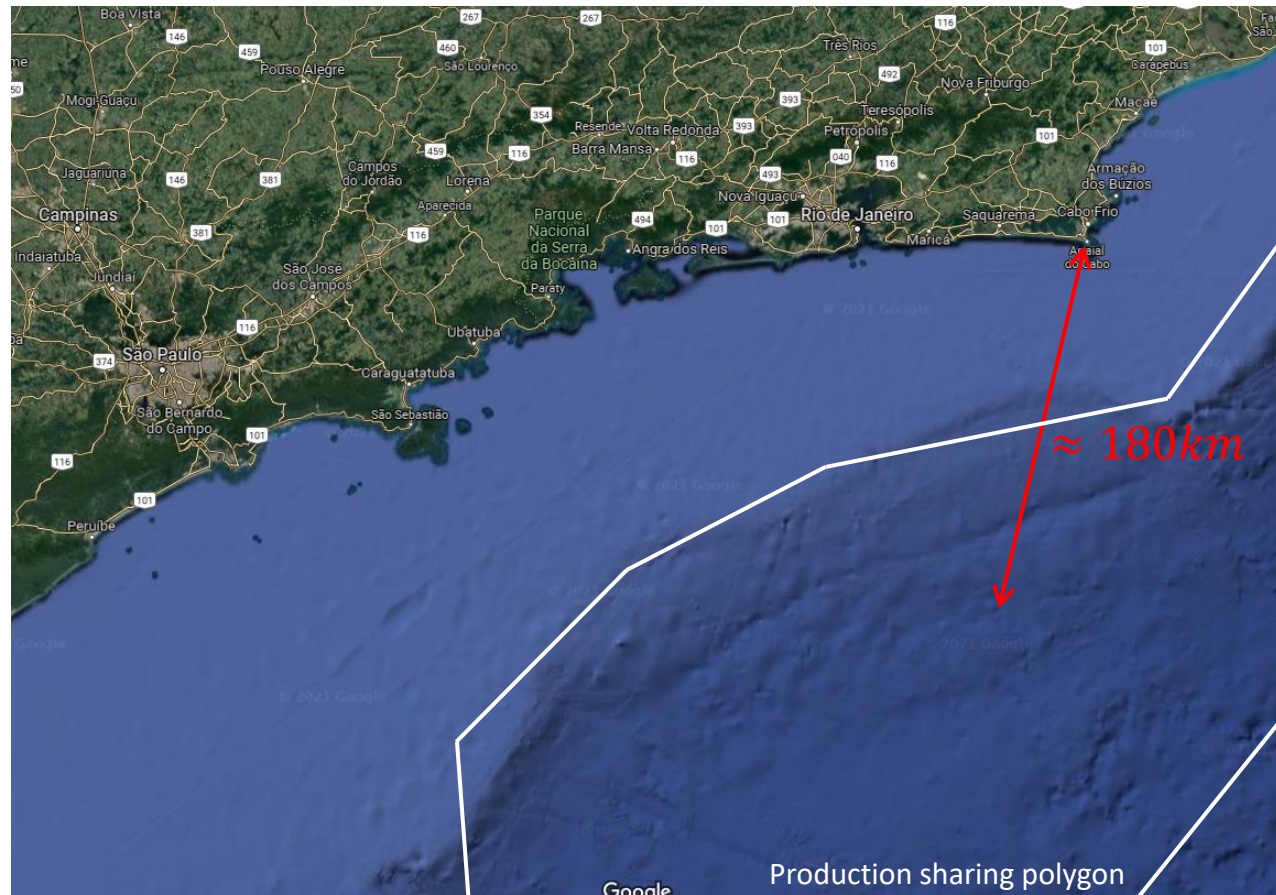
Case study: Wind turbine and depth

Parameter	Value	Units
Cut-in wind speed	4	[m/s]
Cut-out wind speed	25	[m/s]
Rated wind speed	11.4	[m/s]
Rated power	10	[MW]
Rotor speeds	6 – 9.6	[rpm]
Number of blades	3	[-]
Rotor diameter	178.3	[m]
Hub diameter	5.6	[m]
Hub height	129	[m]
Rotor mass	227,962	[kg]
Nacelle mass	446,036	[kg]

Specifications of the DTU
10MW Wind Turbine

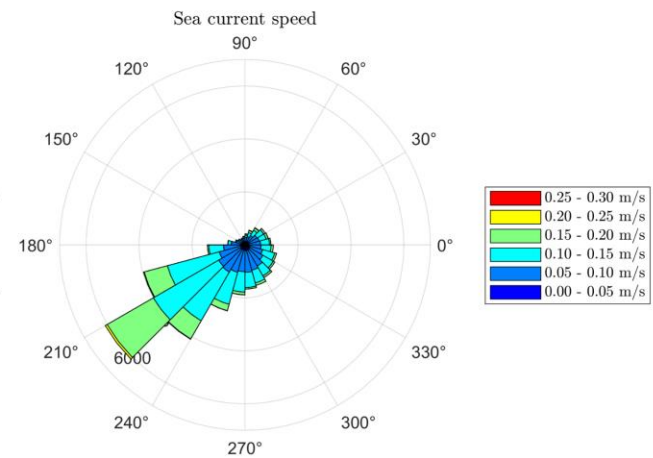
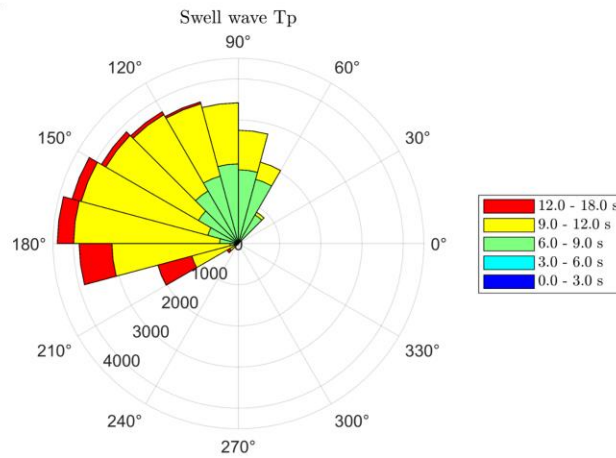
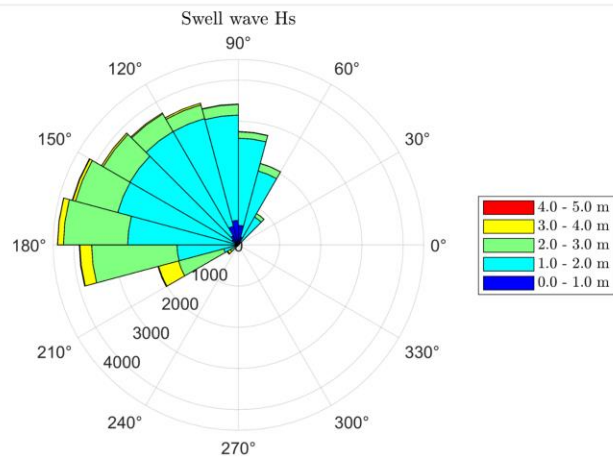
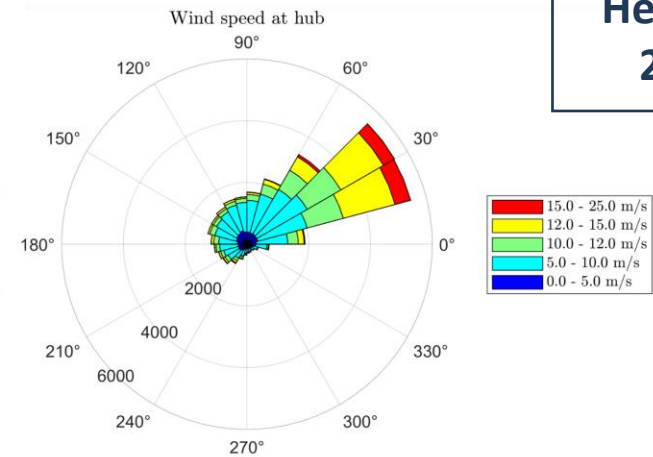
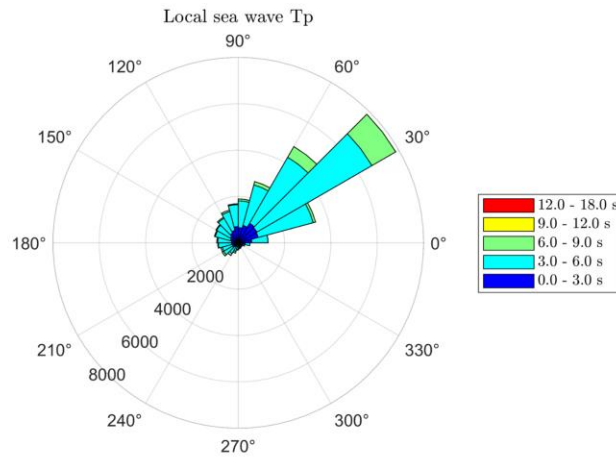
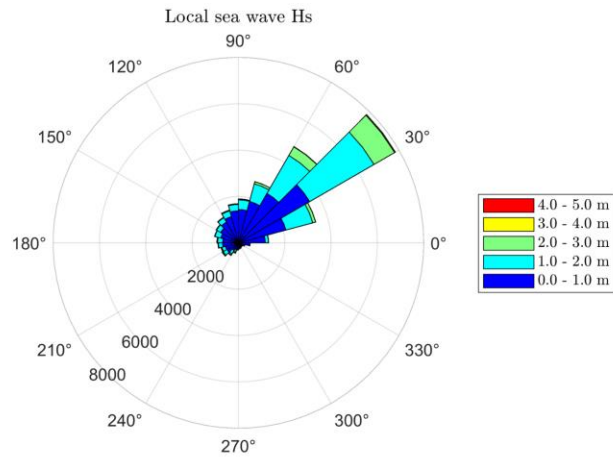


Case study: Location



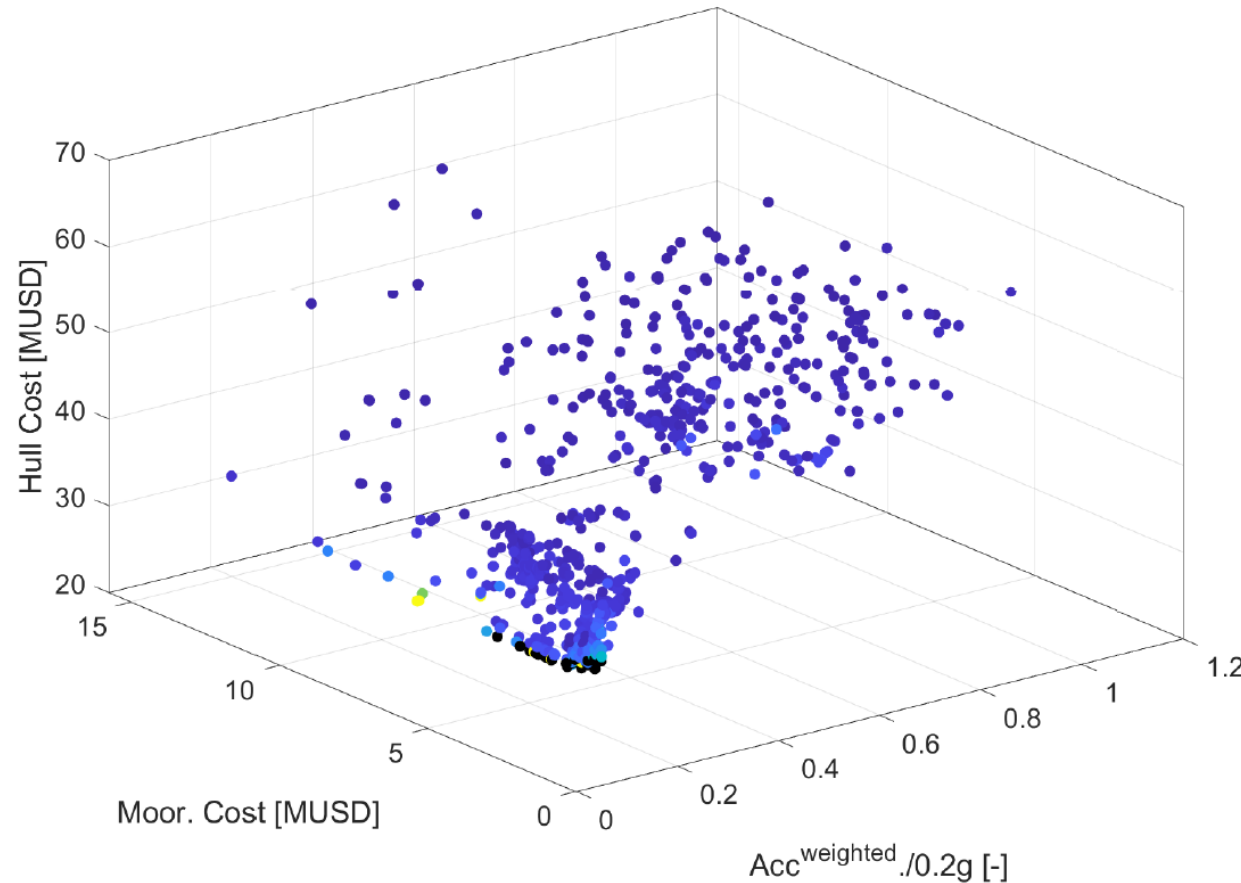
Case study: Metocean

**Heading:
25.7°**



35,065 environmental conditions (12 years/3h-long)

Case study: FOWTC multi-objective optimization (1/4)

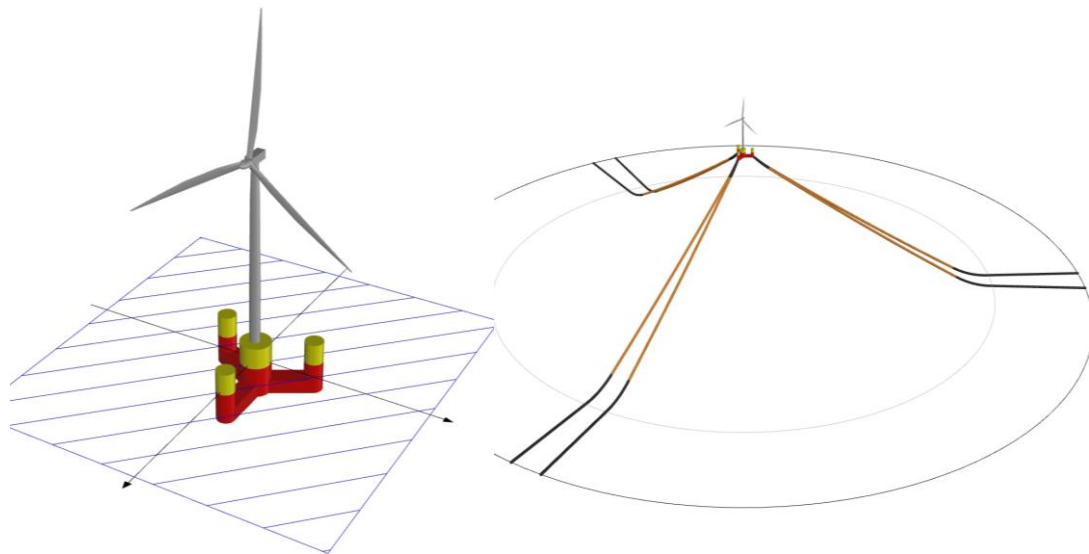


Pareto front: 25 concepts
Costs: 30.8 – 33.3 MUSD
Accelerations: 0.14 – 0.16

Case study: FOWTC multi-objective optimization (2/4)

FOWTC-I concept

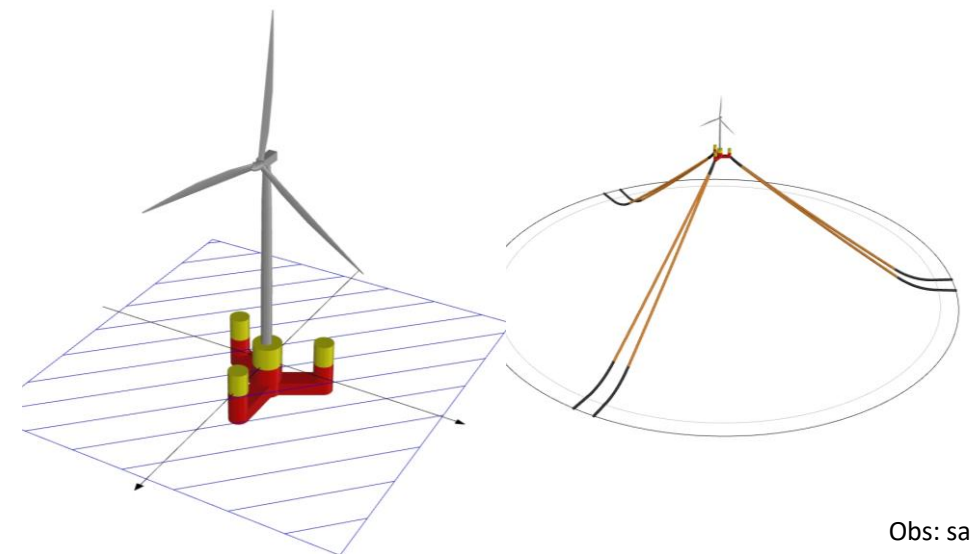
No vertical tension at the anchor



Displacement	25,850 ton
Draft	21.7 m
Mooring length	1,564.6 m

FOWTC-II concept

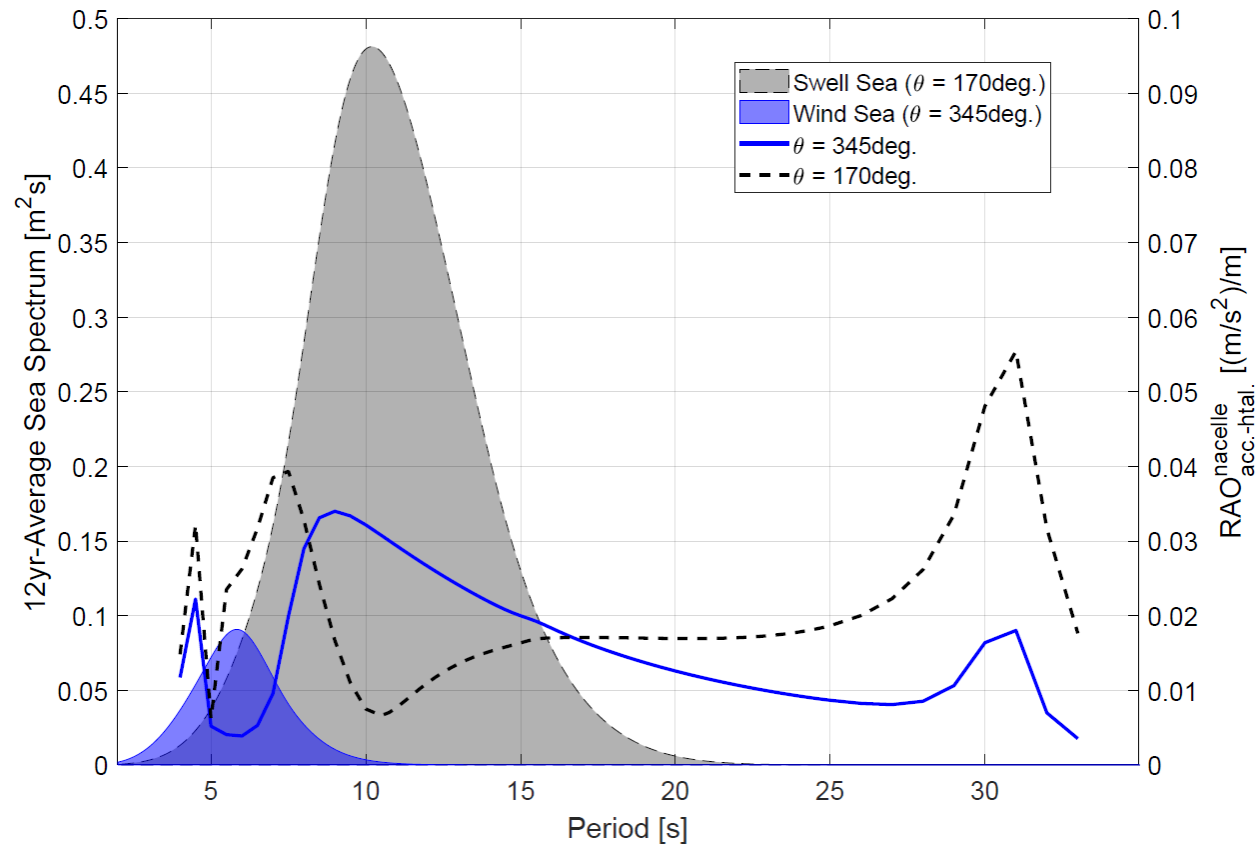
Vertical tension at the anchor



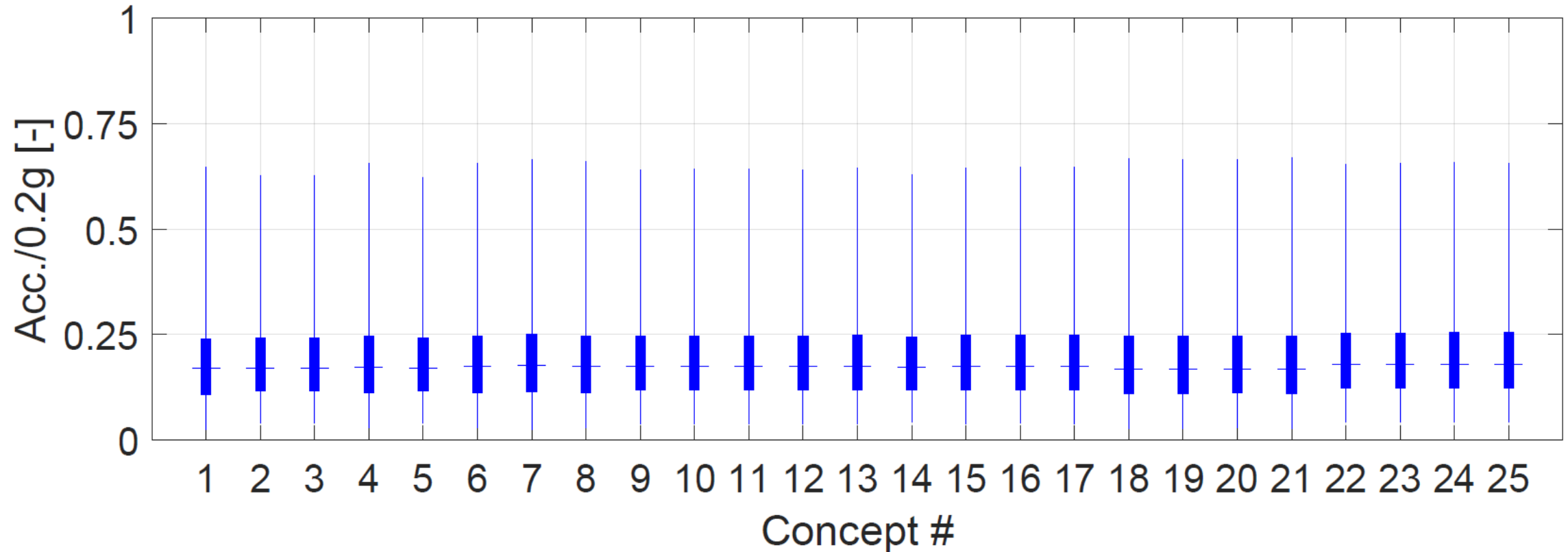
Obs: same scale

Displacement	24,681 ton
Draft	21.7 m
Mooring length	1,106.6 m

Case study: FOWTC multi-objective optimization (3/4)

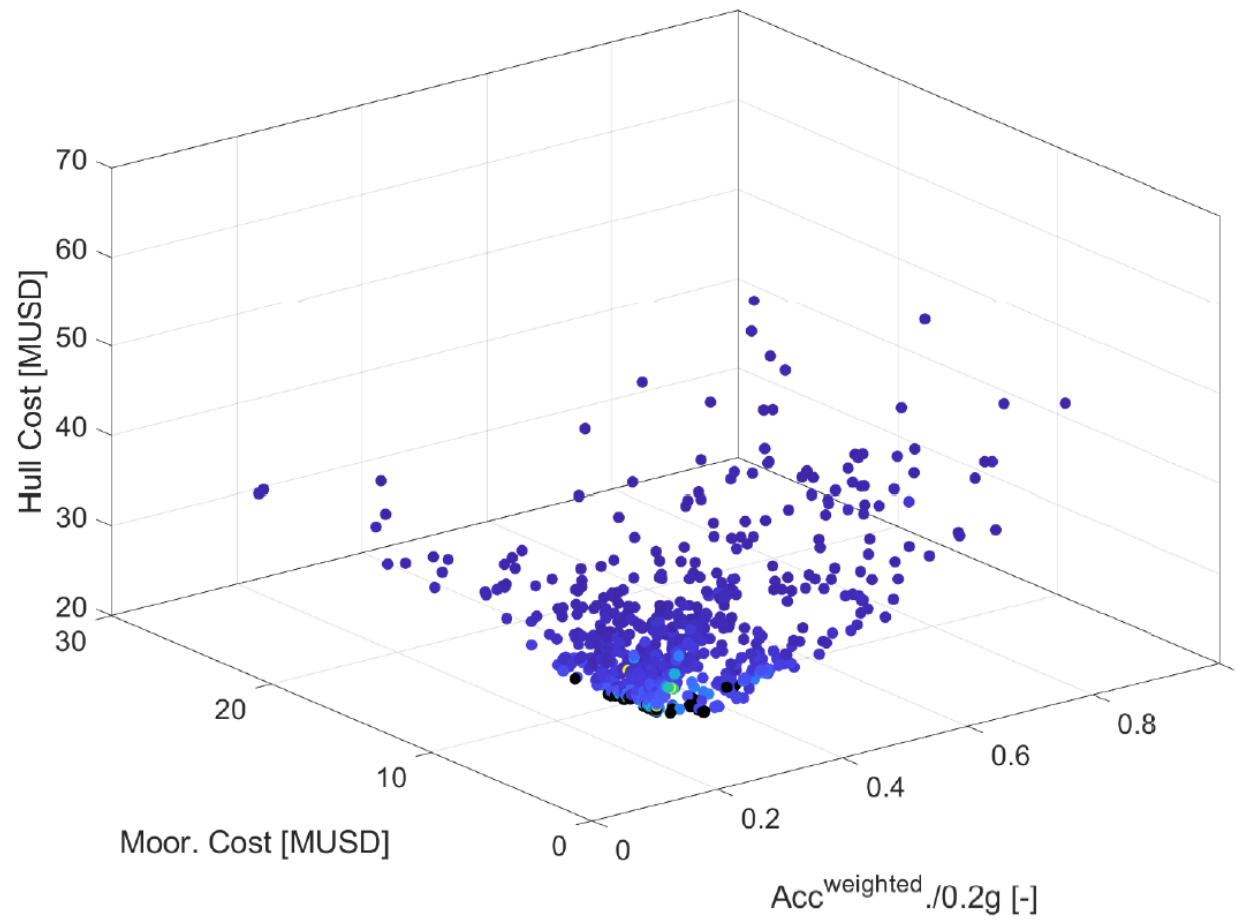


Case study: FOWTC multi-objective optimization (4/4)



Skip FOWTO results

Case study: FOWTO multi-objective optimization (1/4)

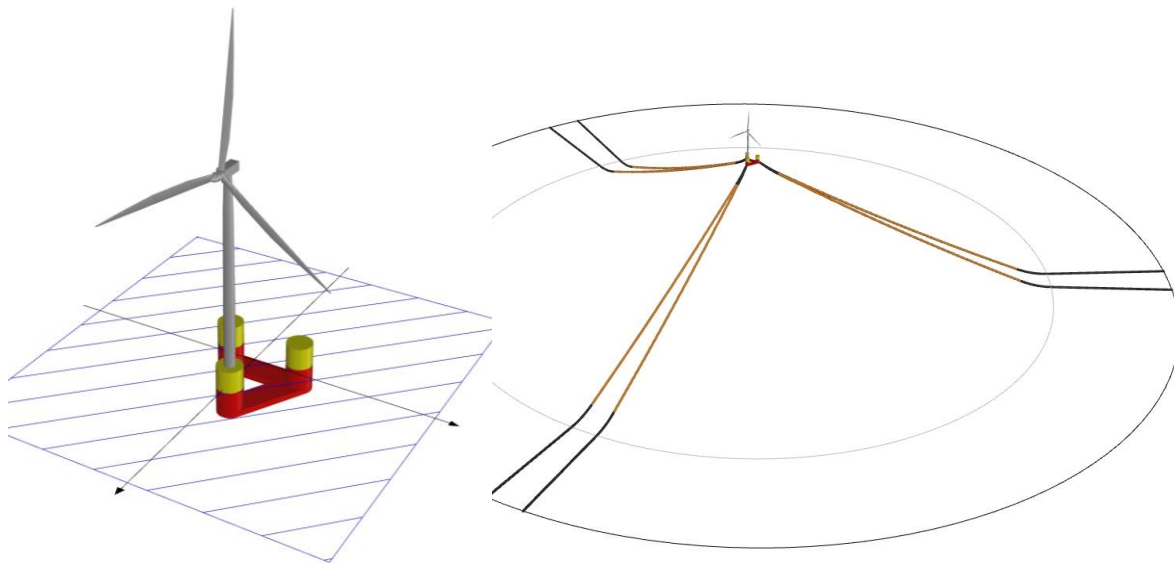


Pareto front: 23 concepts
Costs: 26 – 28 MUSD
Accelerations: 0.15 – 0.40

Case study: FOWTO multi-objective optimization (2/4)

FOWTO-I concept

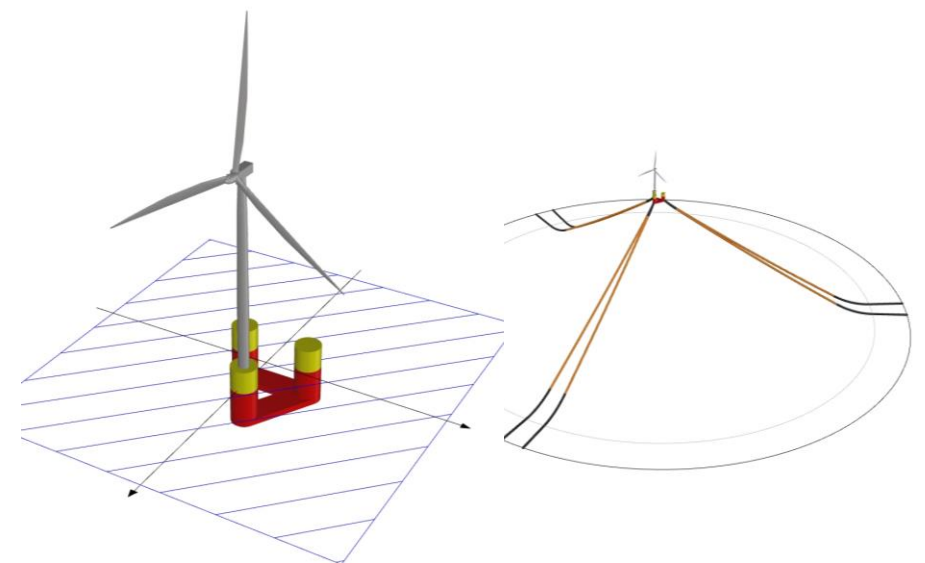
No vertical tension at the anchor



Displacement	18,919 ton
Draft	18.4 m
Mooring length	1,935.0 m

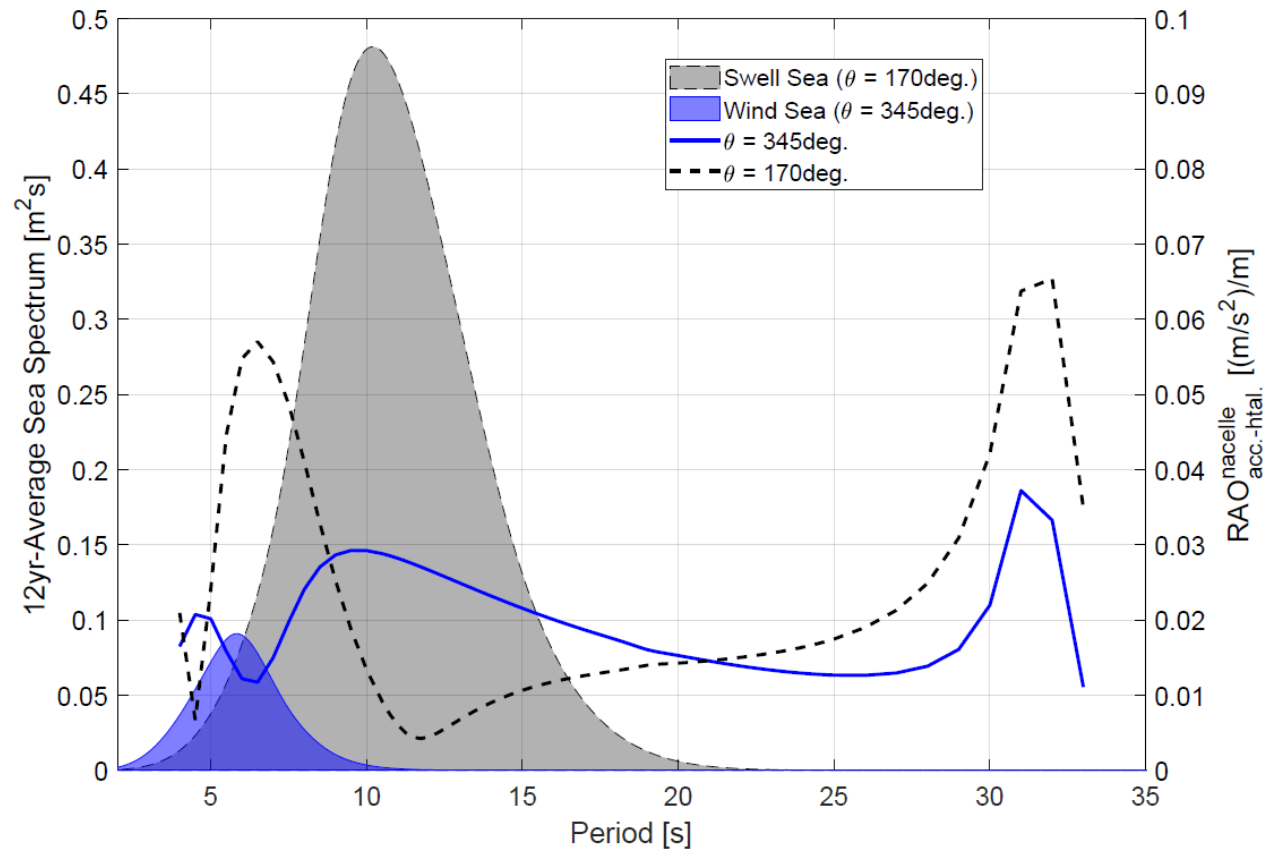
FOWTO-II concept

Vertical tension at the anchor

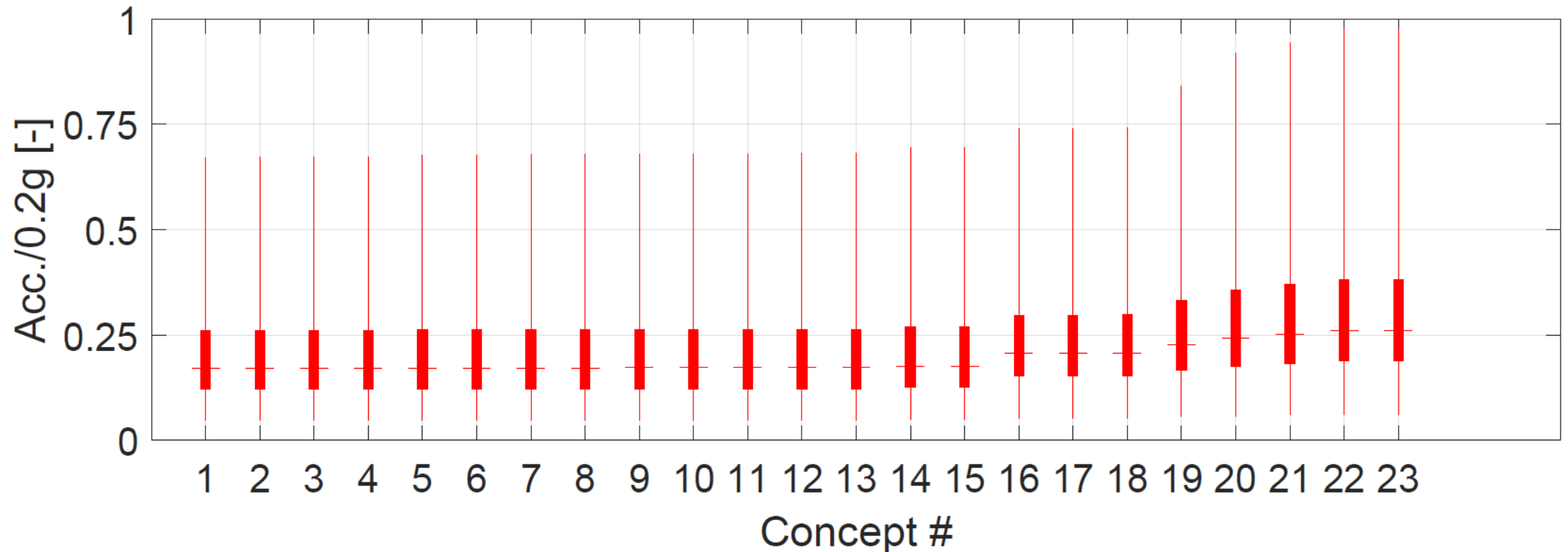


Displacement	22,828 ton
Draft	24.9 m
Mooring length	1,320.9 m

Case study: FOWTO multi-objective optimization (3/4)

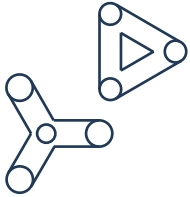


Case study: FOWTC multi-objective optimization (4/4)

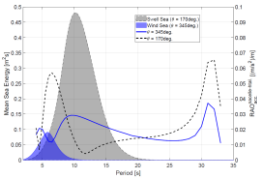


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Conclusions



FOWT **site-specific optimization** for **two topologies** of semisubmersible platforms, using a 10MW wind turbine

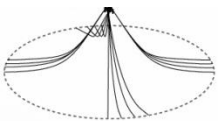


Pareto fronts show a clear trend **to minimize the nacelle's acceleration responses within the frequency range featured the largest (wind and swell) sea energy**



Optimization results show **trade-off between** the maximum **horizontal accelerations** and the **costs** of the hull and mooring systems

- Largest hulls are characterized with robust mooring systems and small accelerations



Mooring system robustness is conditioned by **diameter and number of lines per column**

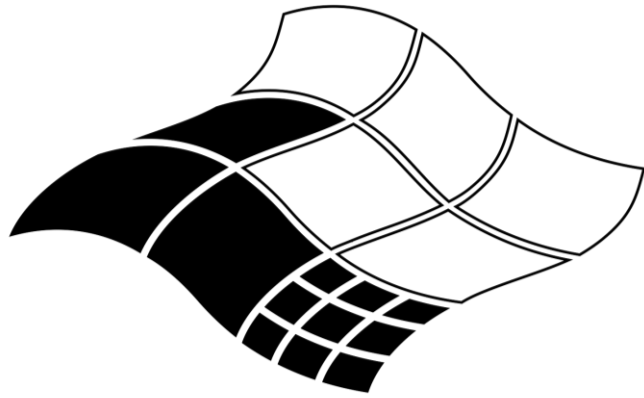
- **Different combinations** may result in systems with **similar safety factors** → not-fit results
- Inclusion of **mooring installation costs** may help to **overcome this problem**

Thank you!

Acknowledgments



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Agência
Nacional do
Petróleo

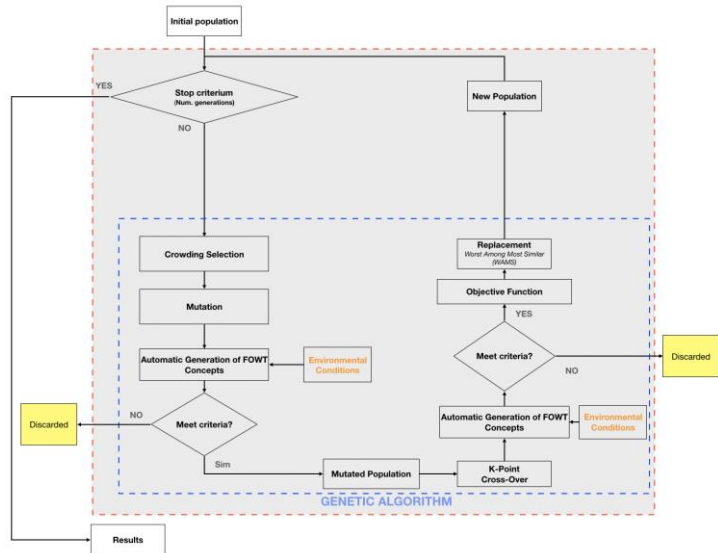


Tanque de
Provas Numérico da USP
Numerical Offshore Tank

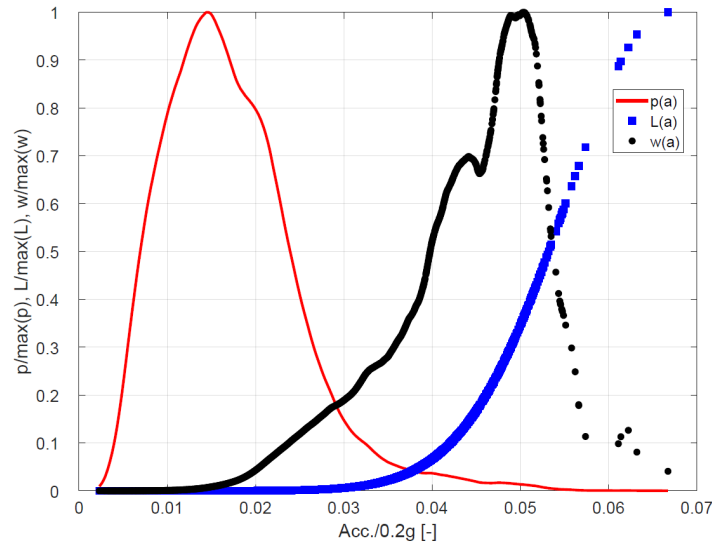


**Universidade
de São Paulo**

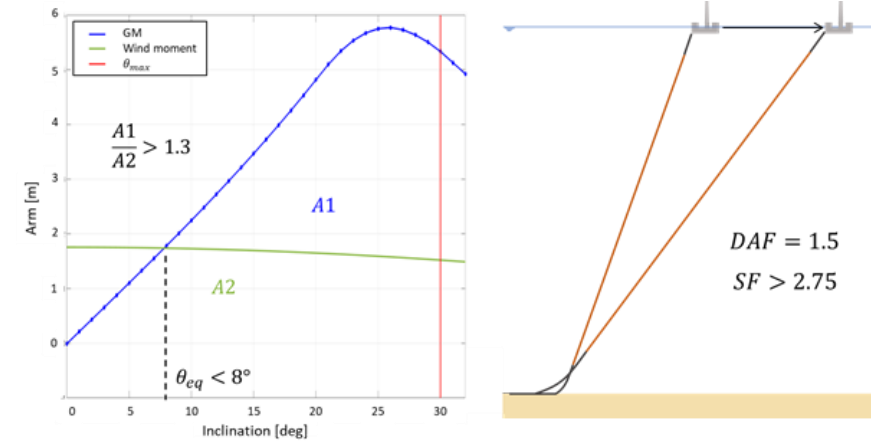
Optimization Framework



Weighting Function



Restrictions



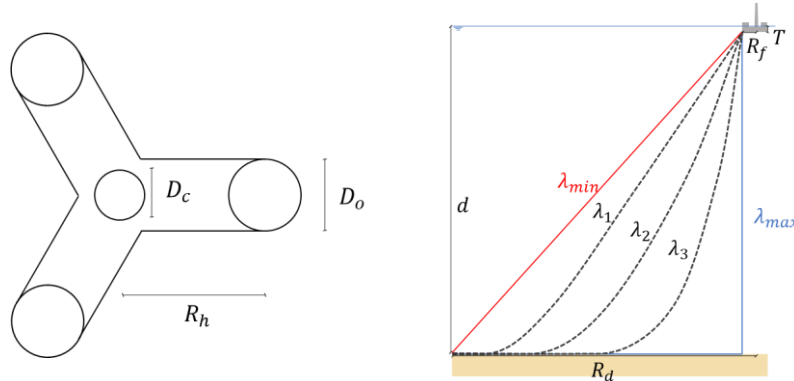
Cost function

Performance evaluation:
Weighted nacelle horizontal acceleration

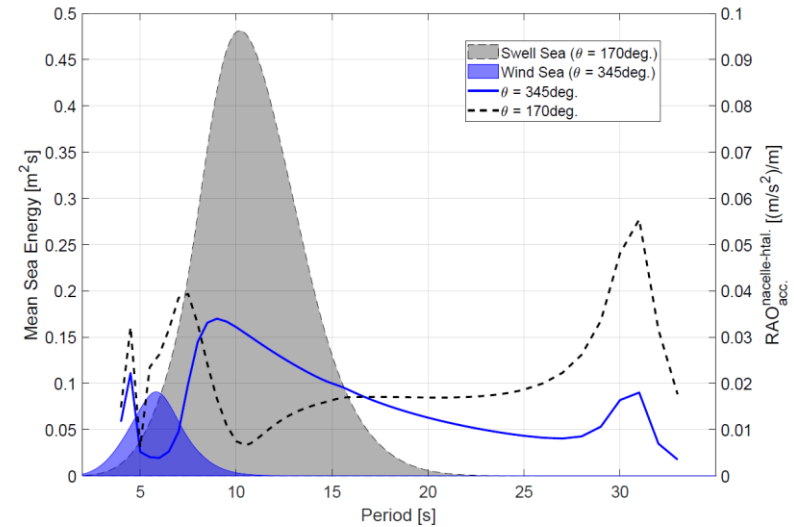
$$\min\{F\} = \min \left\{ \text{Cost}_{CAPEX}^{\text{hull}}, \text{Cost}_{CAPEX}^{\text{mooring}}, \sum_{i=1}^N \left(w_i \cdot \frac{a_i}{0.2g} \right) \right\}$$

Cost model:
Bjerkseter and Agotnes (2013)
and Karimi et al. (2017)

Optimization Framework



accelerations RAOS x Mean Sea Energy



Concepts accelerations

