Preliminary Sizing and Optimization of Semisubmersible Substructures for Future Generation Offshore Wind Turbines

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Introduction

- · Large wind turbines and floating foundations are expected to give lower costs
- Existing reference designs constitute a good starting point, but simple upscaling may give unfeasible or overly conservative designs
- Previous studies:
 - Theoretical upscaling of the substructure geometry with some constrained dimensions and checking the static and dynamic behavior of the upscaled design
 - Parametric studies considering dynamic behavior of the substructure (using diffraction/radiation analysis)
- · Current work:
 - 2D simplified model of a FWT considering rigid motions and tower bending
 - Preliminary sizing to support a 25 MW turbine upscaled from the IEA15MW RWT
 ⁽¹⁾ through a design space search using two reference platforms

Reference designs



IEA 15 MW UMaine VolturnUS-S (2)

INO WINDMOOR 12 MW (3)

References:

- Allen, C. et al. (2020). Definition of the UMaine VoltumUS-S Reference Platform Developed for the IEA Wind 15-Megawatt Offshore Reference Wind Turbine (No. NREL/TP-5000-76773). National Renewable Energy Lab.(NREL), Golden, CO (United States).
- (2) Gaertner, E. et al. (2020). IEA wind TCP task 37: definition of the IEA 15-megawatt offshore reference wind turbine (No. NREL/TP-5000-75698). National Renewable Energy Lab. (NREL), Golden, CO (United States)
- (3) Silva de Souza et al. (2021). Definition of the INO WINDMOOR 12 MW base case floating wind turbine.



Simplified model

Modelling assumptions:

- Only surge, heave, pitch and tower fore-aft bending
- Added mass calculated using strip theory with 2D coefficients
- Mooring stiffness based on 18 m surge offset under rated thrust

Outputs:

- Natural periods from the global stiffness and mass matrices
- Static pitch under maximum thrust:

 $\begin{bmatrix} C_{11} & C_{15} \\ C_{51} & C_{55} \end{bmatrix} \begin{bmatrix} \eta_1 \\ \eta_5 \end{bmatrix} = \begin{bmatrix} F_{thrust} \\ F_{thrust} h_{hub} - m_{RNA} x_{RNA} g - F_{v1} x_1 + 2F_{v2} x_2 \end{bmatrix}$

- F_{v1}, F_{v2} : vertical tension in the fwd and aft mooring lines at 18 m platform surge offset
- (obtained from OpenFAST and theoretically upscaled)
- x_1, x_2 : the longitudinal distances of fwd and aft fairleads from geometric center







- Constant steel thickness across all structural members (back-calculated from UMaine platform as 4.6 cm and upscaled)
- Fixed ballast (ρ = 2650 kg/m3) in side-columns (aft columns for the peripheral design) and seawater ballast in pontoons
 Constraints:
- Maximum hull dimension 120 m
- Stiff-stiff tower (on the floater): $T_{towFA1} < 60/3P$

- Natural periods for rigid body motions larger than 20 s
- Mean pitch at rated wind speed below 30°



Design space exploration

- **Objective:** Find feasible designs with minimum steel mass at various max. allowable static pitch angles
- Theoretically upscaled designs
 - have over-conservative static pitch angle
 - may violate the stiff-stiff tower requirement
- A small increase in the max. static pitch angle results in:
 - Significant decrease in steel mass
 - Stiffer tower
- 6 design points for each concept at different static pitch angles were selected for coupled simulations along with the upscaled designs



Simplified model verification

- Decay tests for the selected designs performed using OpenFAST
- · Good agreement with the simplified model
- Discrepancies may be a result of the following:
 - Accuracy of added mass estimation
 - Using a linear mooring stiffness matrix in the simplified model
- More results from the coupled analyses for the turbine's performance in different environmental states will be available in the full publication



