



Laura Voltà, Development Engineer, DTU

Self-Alignment on Single Point Moored downwind Floater – The PivotBuoy® Concept

By Albert M. Urbán, Laura Voltà, Rocío Torres and W. H. Lio

- Floating Wind Turbines Market Perspectives
- PivotBuoy® Concept
- PivotBuoy Project
- Dynamics Single Point Moored Platforms
- Future Work
- Conclusions

Floating Wind Turbines – Market perspectives

- Operating, under (Pre)-construction and awarded floating wind projects
 - Windfloat demonstrator (2MW) Hywind Scottland (30MW) Maine Aqua Ventus I (12MW) Nedo demonstrator (4.4 and 3MW) Kincardine (50MW) Leucate (24MW)

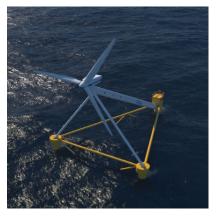


https://www.equinor.com/en/what-we-do/floatingwind/hywind-scotland.html



https://www.principlepowerinc.com/ en/windfloat

- Innovation in Floating Wind Turbines
 - Ability to harness energy at deep water depths
 - Cost efficient solutions
- Among different solutions: Single Point Moored Platforms (SPM)





http://www.x1wind.com

https://saitec-offshore.com/projects/

DTU

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PivotBuoy® Concept

- PivotBuoy Platform developed by X1Wind brings to the table:
 - Single Point Moored connection integrating anchoring, mooring and electrical in a unique point
 - Wind self-orienting system
 - Easy manufacturing, towing and platform installation
 - Downwind concept, which allows increase of blade flexibility and bending
- Brief introduction: images are worth more than words...



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- H2020 funded project to validate the PivotBuoy® system
- Prototype to be tested at PLOCAN in a real environment
- System under construction, installation in coming months
- **Consortium:** 9 industrial + R&D partners





- PLOCAN test site (Spain)

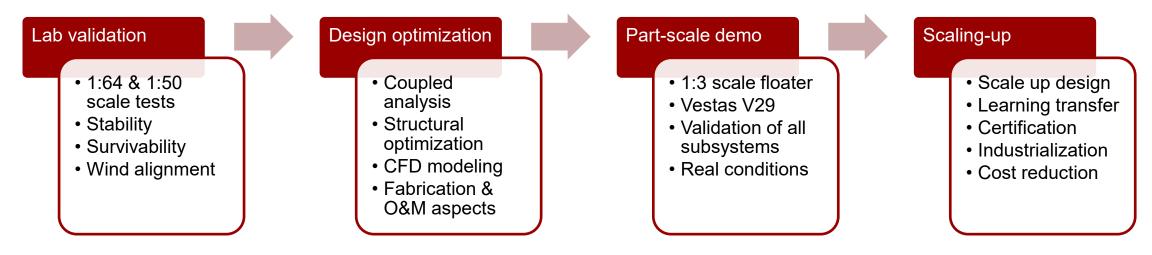
- X30 platform (1:3 scale)
- 50m water depth
- 3 tensioned moorings + GBS
- Vestas V29 + ABB converter
- 20kV cable connection



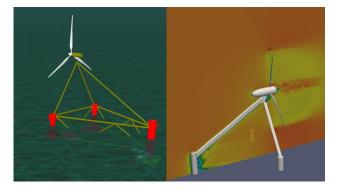
This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement N°815159

https://pivotbuoy.eu/













- Manufacturing at DEGIMA facilities has finished
- Assembly on-going, ready to be deployed in the next months





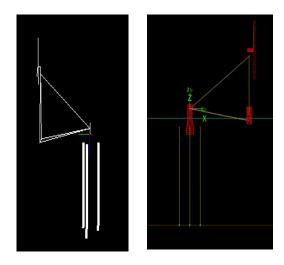


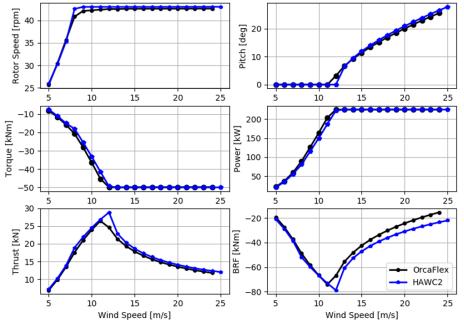


• DTU's role in the project:

HAWC(Stab)2 - A state-of-the-art framework for multiphysics/fidelity frequency and time domain analysis

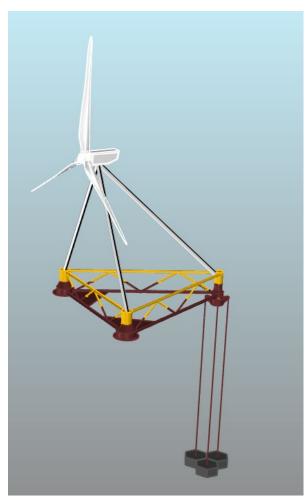
- Set-up and calibration of different numerical models
- Simulation results for PLOCAN 1:3 part-scale prototype
- Full-scale PivotBuoy System Simulation
- Calibration of the numerical models with experimental data
- Comparison between numerical and experimental data



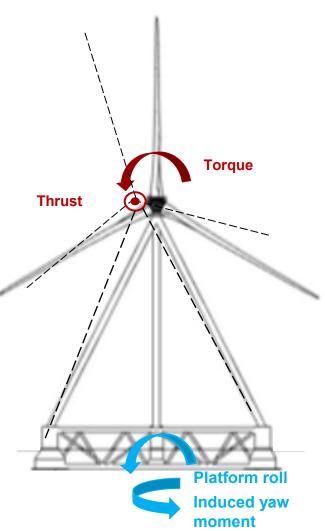


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- Platform Modelling
 - Preliminary Full Scale design
 - Hub Height 140m
 - 15MW Reference Wind Turbine
 - Downwind adaptation & No tilt 240m Rotor
 - Frictionless Spherical Bearing
 - Free Rotation TLP Floater 3DOF
 - Aerodynamic Drag Included for all elements
 - Improves Self-alignment platform
- Software: HAWC2 & Hydrodynamics based on Morison's approach



- Free yawing platform
- Generator torque causes a platform roll motion
- Thrust force is no longer aligned with the pivoting point
- Yaw moment induced by the platform roll angle and the thrust force
- Considerations
 - In HAWC2, bearing is frictionless
 - Roll and pitch motion depend on platform stiffness

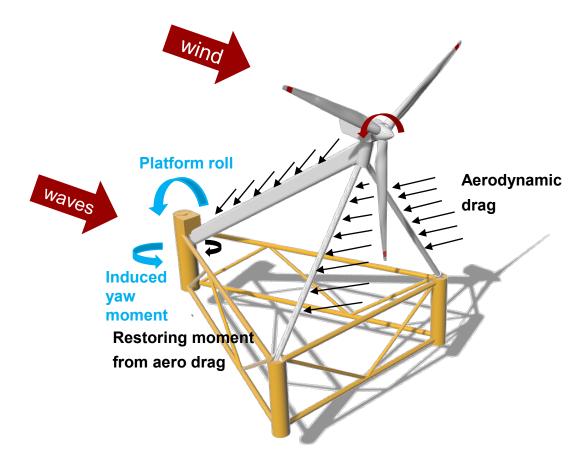


- Under wind and waves aligned:
 - Aerodynamic drag acting as a restoring force, balances the yaw moment induced by the platform roll

Mz_{thrust} (roll, pitch, yaw) + Mz_{aero drag} (yaw) + Mz_{downwind aero} (yaw) = 0

Platform-wind missalignment = yaw

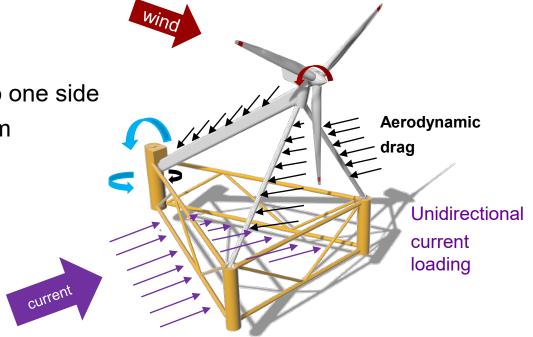
- Platform misalignments are very small



• What happens if you have misaligned forces ?

Example case study: wave current

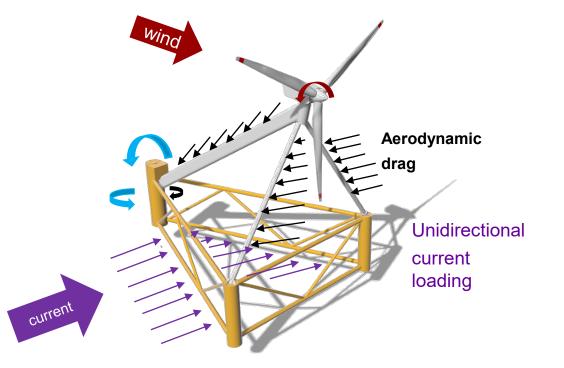
- New Force Diagram. Constant loading to one side
- The turbine will find a different equilibrium
 - wind speed
 - wave condition
 - current velocity and profile
 - Current angle ß
 - roll-yaw platform stiffnes



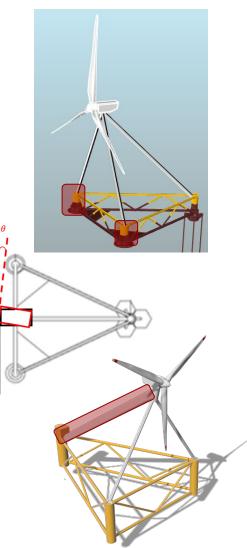
Example case study: wave current

 Mz_{thrust} (roll, pitch, yaw) + $Mz_{aero drag}$ (yaw) + $Mz_{current}$ (yaw- β) + $Mz_{downwind aero}$ (yaw) = 0

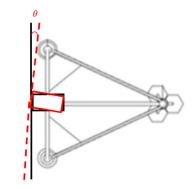
ß: current angle, yaw- $\beta \neq 0$ Platform-wind Missalignment $\neq 0$



- What can be done to increase Power production ?
 - Passive Solutions
 - Design Asymmetry on Buoys based on nominal turbine torque
 - Constant yaw turbine Misalignment to compensate the yaw-roll induced moment around the vertical axis
 - Increase passive drag elements inclusion of sails or another type of structure where huge area can be used at the expense of mass



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- What can be done to increase Power production ?
 - Active Solutions
 - Individual Pitch Control to generate an aerodynamic yaw moment to actively compensate the roll-yaw platform moment.
 - Ballast Control to actively eliminate the platform roll

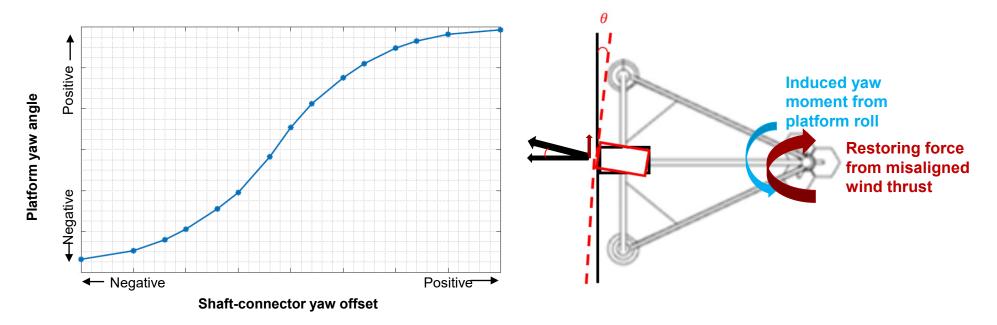


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• Passive Strategy: Constant design nacelle yaw offset

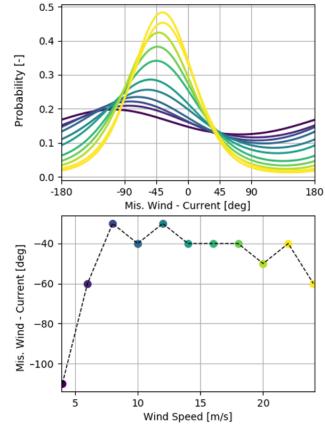
By misaligning the nacelle with respect to the pivoting point, the downwind turbine will generate an aerodynamic restoring moment



- Passive Strategy: Constant design nacelle yaw offset
 - But, can we optimize for all the cross aligned cases?
 - Multi-dimension problem
 - AEP needs to be optimized for a given site. Find the yaw offset that optimizes power

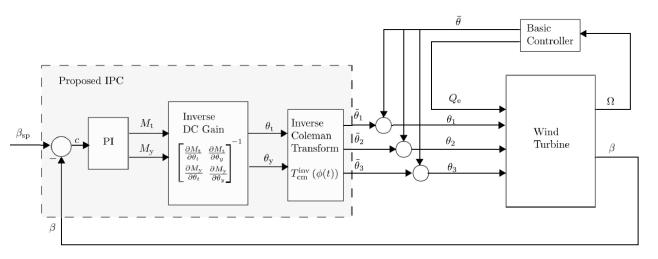
<u>Advantages</u>: passive strategy which does not require actuator, no increased blade-pitch activity

<u>Disadvantages</u>: Site-specific dependent, uneven weight loading, additional axial loading on the connector, fatigue increase on axial elements



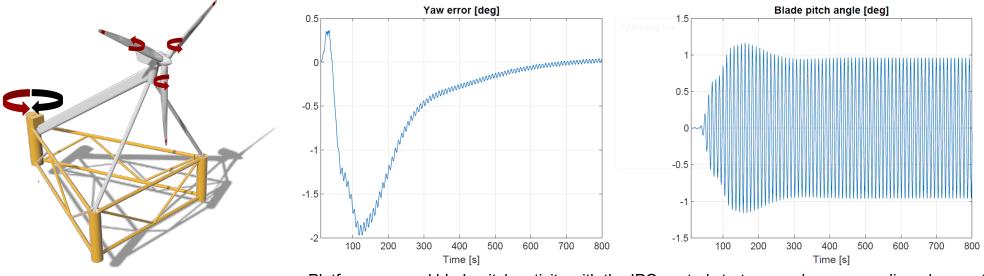
Example of site-specific wind-wave misalignment analysis

- Active strategy: Individual Pitch Control
 - Traditional IPC is designed to alleviate (among others) shear contribution on the turbine
 - In this study, the IPC is changed to create a restoring moment around vertical axis
 - Open source DTU WEC is used
 - Yaw error becomes the driver of the IPC signal



- . Input signal: yaw error
- 2. Low pass filter and notch filter
- 3. PID controller
- 4. Apply coupling (inverse Jacobian) matrix
- 5. Transform pitch amplitude in MBC to pitch action in rotating blade coordinates
- 6. IPC action is added on top of the collective pitch set-point of the DTU WEC

• Active strategy: Individual Pitch Control



Platform yaw and blade pitch activity with the IPC control strategy, under a cross-aligned current

<u>Advantages</u>: can be used and is valid for all the sites – principle holds <u>Disadvantages</u>: increased loading (specially fatigue) on blades, increased pitch activity

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Future work

- Detailed explanation of concepts presented here. Numerical results of specific first test cases
- Expand the analysis and modelling. Evaluate more realistic cases
- Explore together with the consortium different approaches for enhanced alignment
- Test side PLOCAN analyze measured results to verify our assumptions

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Conclusions

- X1 platform is platform concept which holds a downwind turbine and presents an innovative Single Point Moored connection
- SPM platforms are interesting concepts and challenging to model
 - Alignment under misaligned loading can be improved in passive and active ways
 - Static yaw offset and Individual pitch control strategies are studied
 - Between 1 and 2 % increase in power under aligned 8 m/s steady wind, regular waves, and 0.4 m/s 30 deg current missalignement
- Floating is the future and is here! Future work will be carried out to expand the current study



Thank you!

Laura Voltà, Development Engineer, DTU Iviro@dtu.dk

amur@dtu.dk wali@dtu.dk carlos.casanovas@x1wind.com rocio.torres@x1wind.com