



An introduction of image processing methods to the wake detection

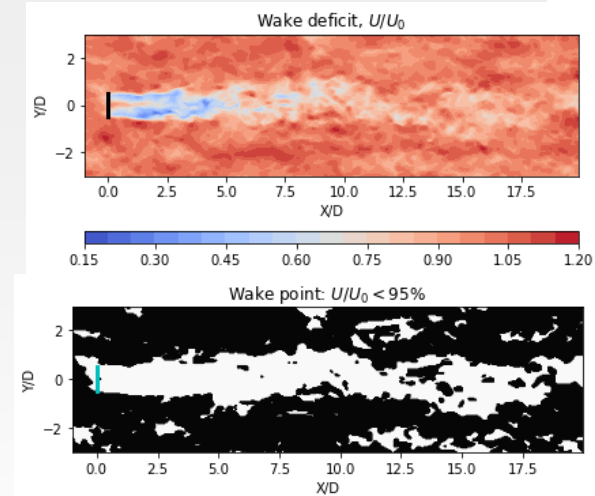
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Introduction

- Wake detection: define the wake shape and centerline.
- Wake detection is particularly important for:
 - wake meandering (instantaneous wake shape evolution),
 - yaw deflection (wake centerline).
- **Quick detection:** wake deficit $U/U_0 < 95\%$ – wake [1].
 - Needs additional cleaning.
 - Not automatic, may require threshold adjustment.





Gaussian wake detection methods

- **1D Gaussian distribution fit to the wake profile**
 - $f(y) = U_0 \exp\left(-\frac{(y-\mu_y)^2}{2\sigma_y^2}\right)$
 - Wake center — mean value μ_y .
 - Wake width — $\mu_y \pm 2 \ln 2 \cdot \sigma_y$ (95% confidence interval)
- Alternatives:
 - **2D Gaussian distribution fit to the cross-section,**
 - or **center of the rotor-sized area** with the minimum power potential [2].
- **Cons:**
 - Strong discrepancy in the instantaneous far wake.
 - Needs enough data points for the fit.

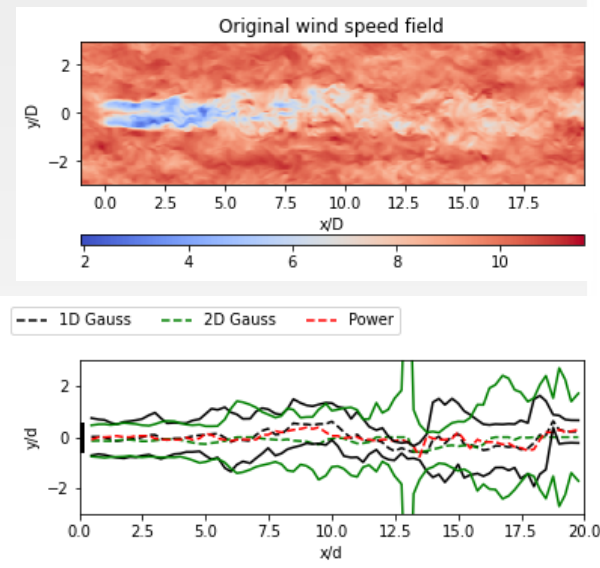
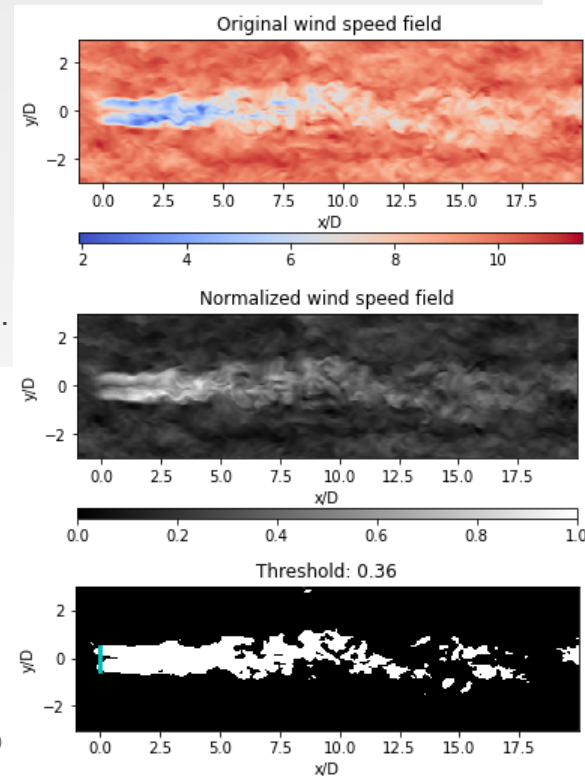
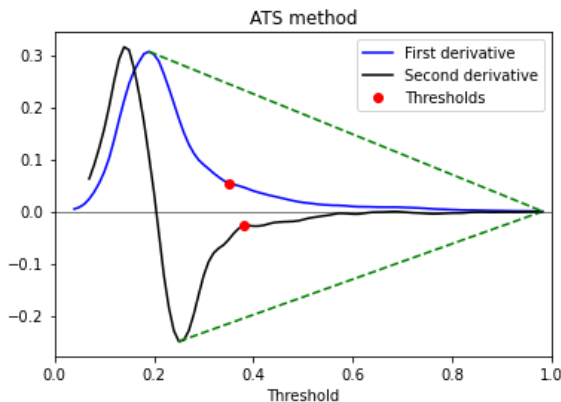
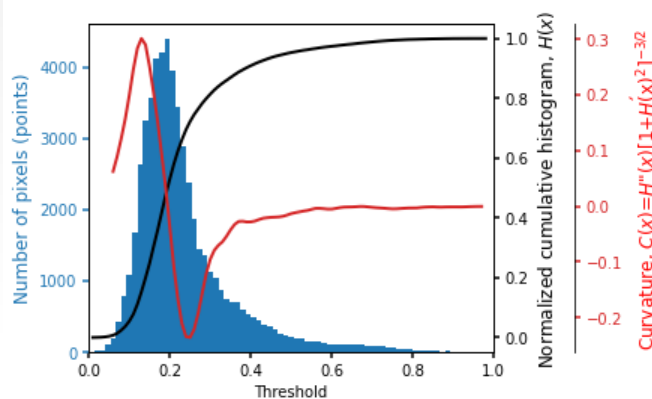




Image processing method

- **Automatic method** – Adaptive Thresholding Segmentation (ATS) [3].
- **Source data:** large-eddy simulation of a single wake.
 - gray scale image (no wind speed data),
 - or original wind speed data normalized to range [0,1]
- The threshold separates group of wake pixels in the histogram tail from the free-flow pixels.
- **Threshold** – maximum curvature of the normalized cumulative histogram.



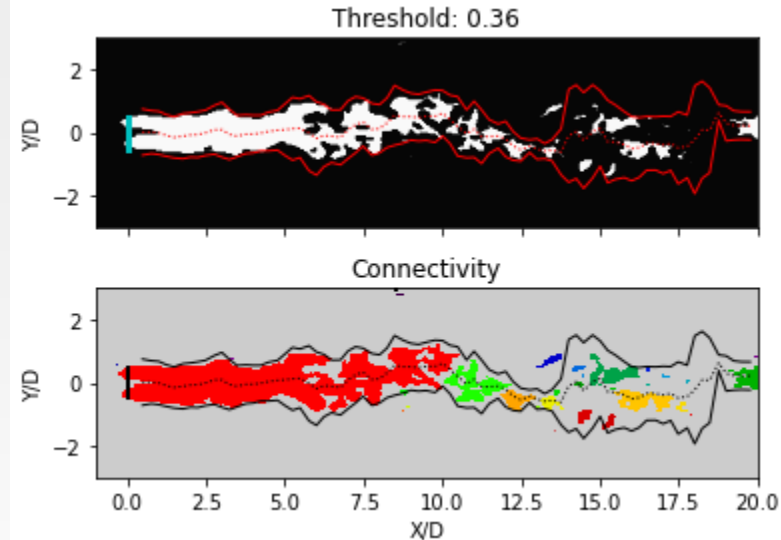


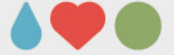
Comparison vs. 1D Gaussian fit

- The methods agree well on the near wake.
- The wake detected using ATS image processing method lies mostly within Gaussian wake borders.
- ATS method detects separate structures in the far wake.

Further development:

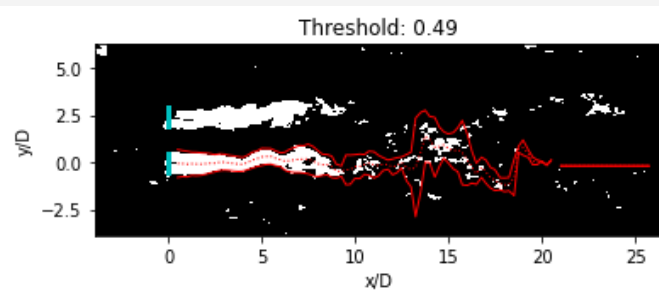
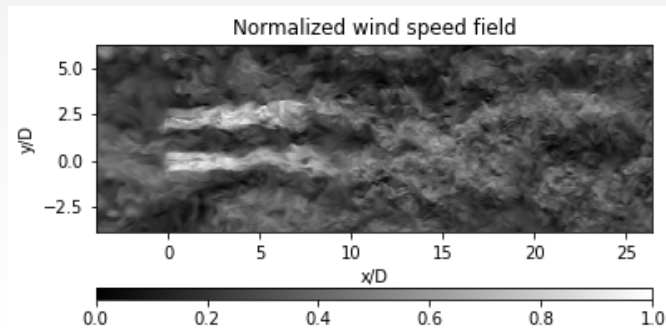
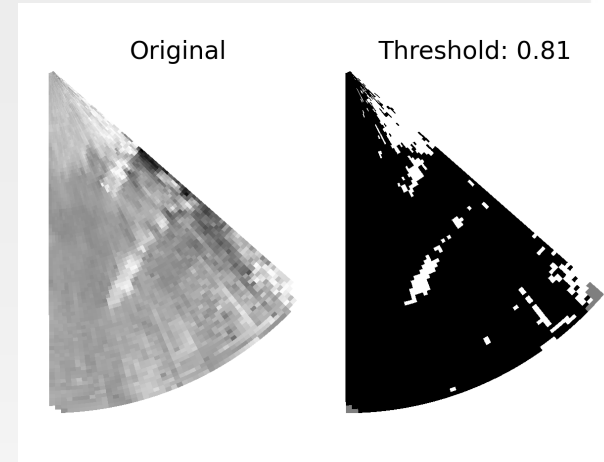
- Study the continuity of the far wake.
 - Apply individual thresholds to the near and far wake sections to improve the detection.
- **Threshold detection on the image:** similar result, but limited information on the wind speed values.





Conclusions & Outlook

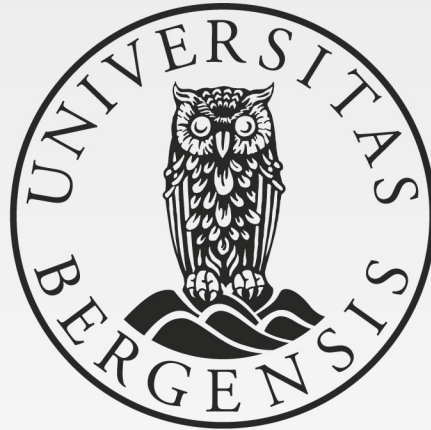
- ATS and Gaussian fit methods work well on their own.
 - Especially good detection in **the near wake**.
 - Combined, the methods can improve the result in **the far wake**.
- ATS has a potential where Gaussian distribution gets insufficient data for the fit:
 - interacting wakes,
 - lidar or satellite data.





References

1. España, G. *et al.* (2011) 'Spatial study of the wake meandering using modelled wind turbines in a wind tunnel', *Wind Energy*. John Wiley & Sons, Ltd, 14(7), pp. 923–937. doi: 10.1002/we.515.
2. Vollmer, L. *et al.* (2016) 'Estimating the wake deflection downstream of a wind turbine in different atmospheric stabilities: An LES study', *Wind Energy Science Discussions*, pp. 1–23. doi: 10.5194/wes-2016-4.
3. Bakhoday-Paskyabi, M., Reuder, J. and Flügge, M. (2016) 'Automated measurements of whitecaps on the ocean surface from a buoy-mounted camera', *Methods in Oceanography*. Elsevier B.V., 17, pp. 14–31. doi: 10.1016/j.mio.2016.05.002.



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