



EERA DEEPWIND 2020

“Are seakeeping simulations useful for the planning of offshore wind O&M?”

Sebastien GUEYDON, 16 January 2020

Outline



- **Intro: SPOWTT**
- Objective & methodology
- Ship motion numerical assessment
- Onboard measurements
- Summary

About SPOWTT



improving **S**afety and **P**roductivity of **O**ffshore **W**ind **T**echnician **T**ransits



Sea State



Ship Motions



Motion Sickness,
Productivity,
Safety

CTV = crew
transfer vessel

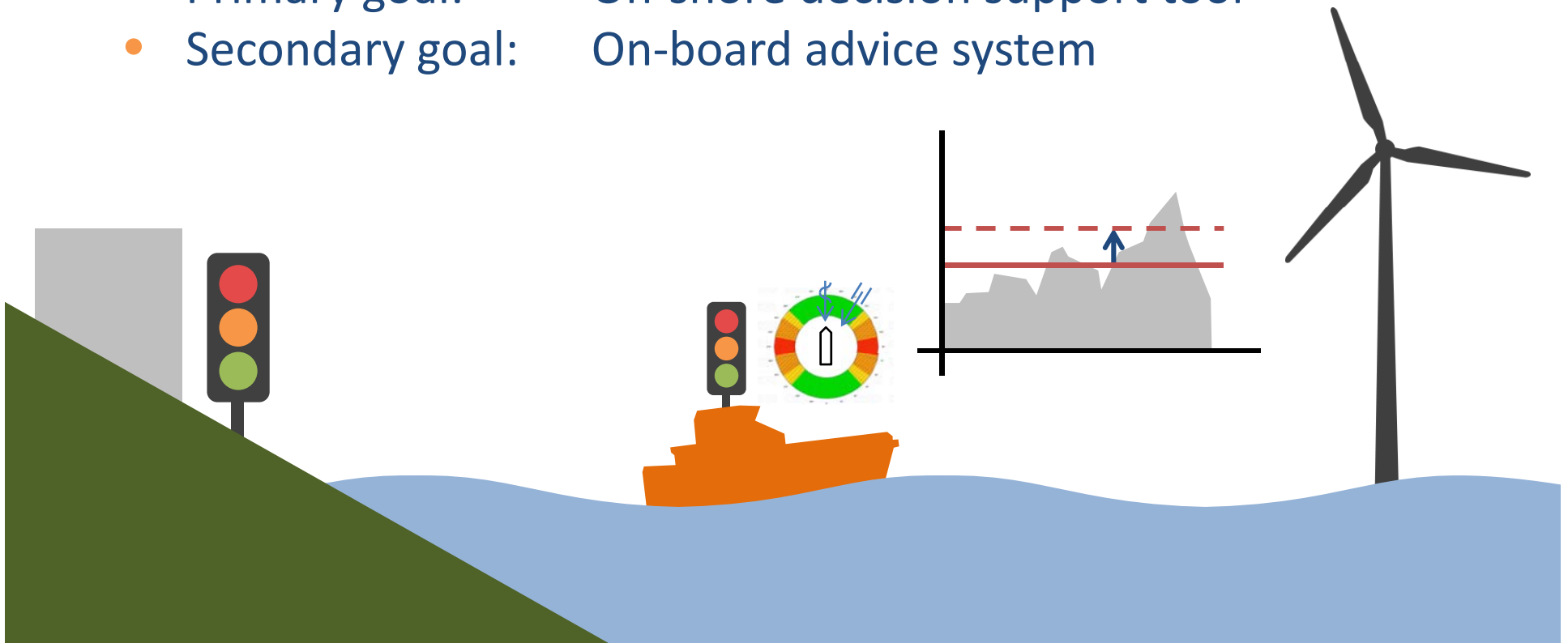
SPOWTT: Project consortium



Project goals



- Primary goal: On-shore decision support tool
- Secondary goal: On-board advice system



Examples CTV



Types:
Monohull
Catamaran
Swath

CATAMARANS POPULAR AMONG CTVs



Outline

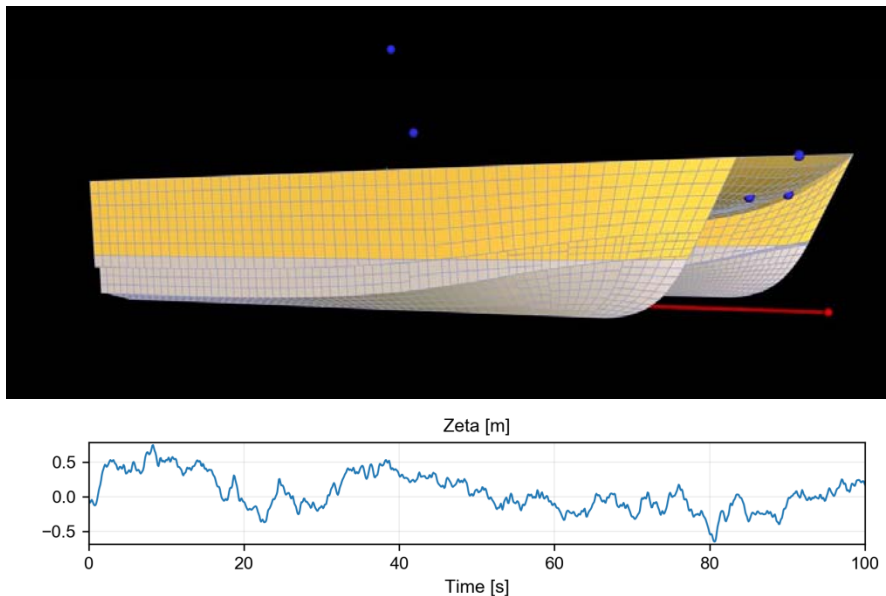


- Intro: SPOWTT
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Are seakeeping simulations useful for the planning of O&M?

- Objective: “Validation” of calculated vessel motion data against full scale motion measurement data.

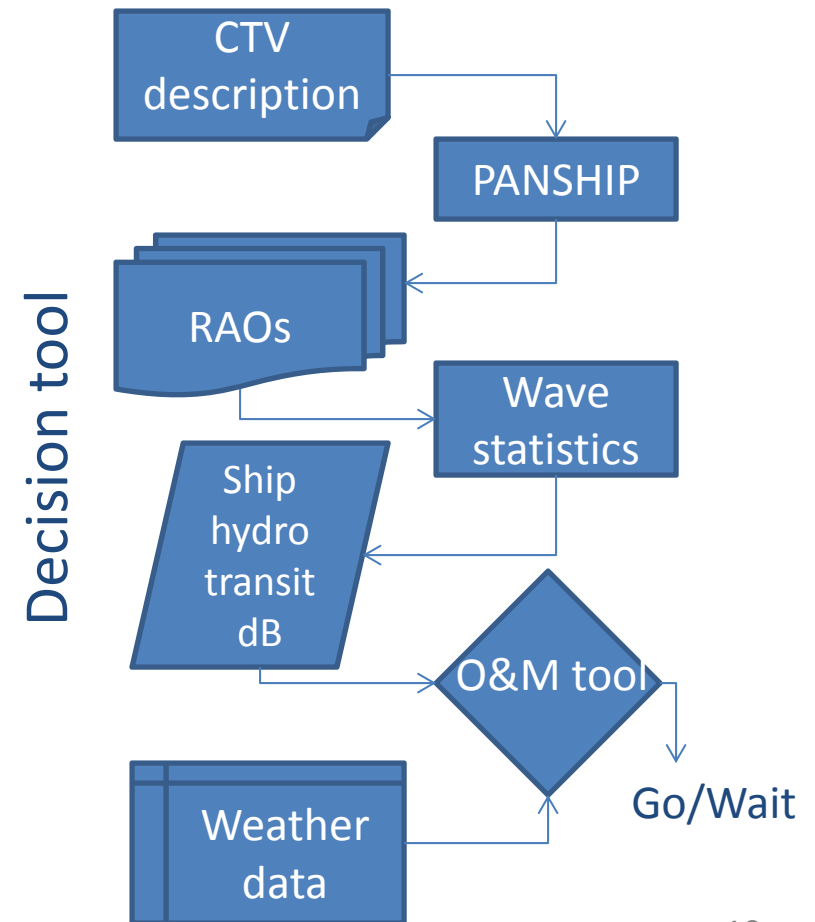
Ship motion simulation code Real measurement on CTVs



How can seakeeping simulations be used for the planning of O&M?



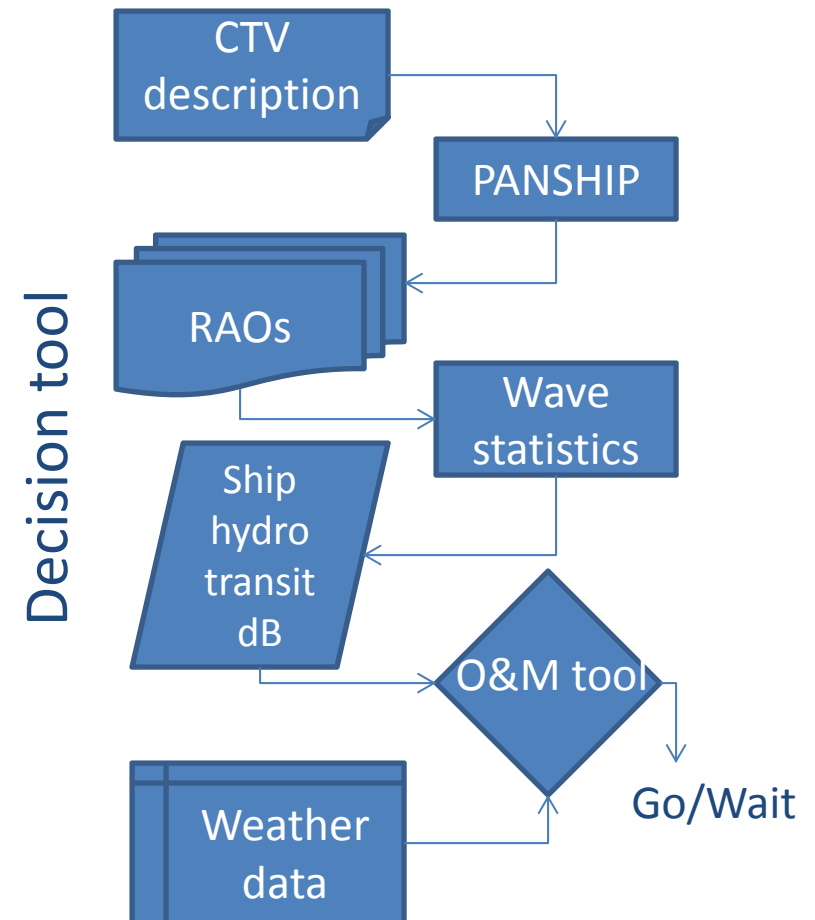
- **Operability of transit journeys is determined using a dB of motion SDAs**
SDA = Significant Double Amplitude
- SDA are calculated from motion RAOs
- RAOs are determined thanks to a ship motion simulation code: PANSHIP
- PANSHIP implements a semi-non-linear panel methods to predict hydrodynamic loads on fast ships
 - Accounting for lifting devices (foil/trim flap)



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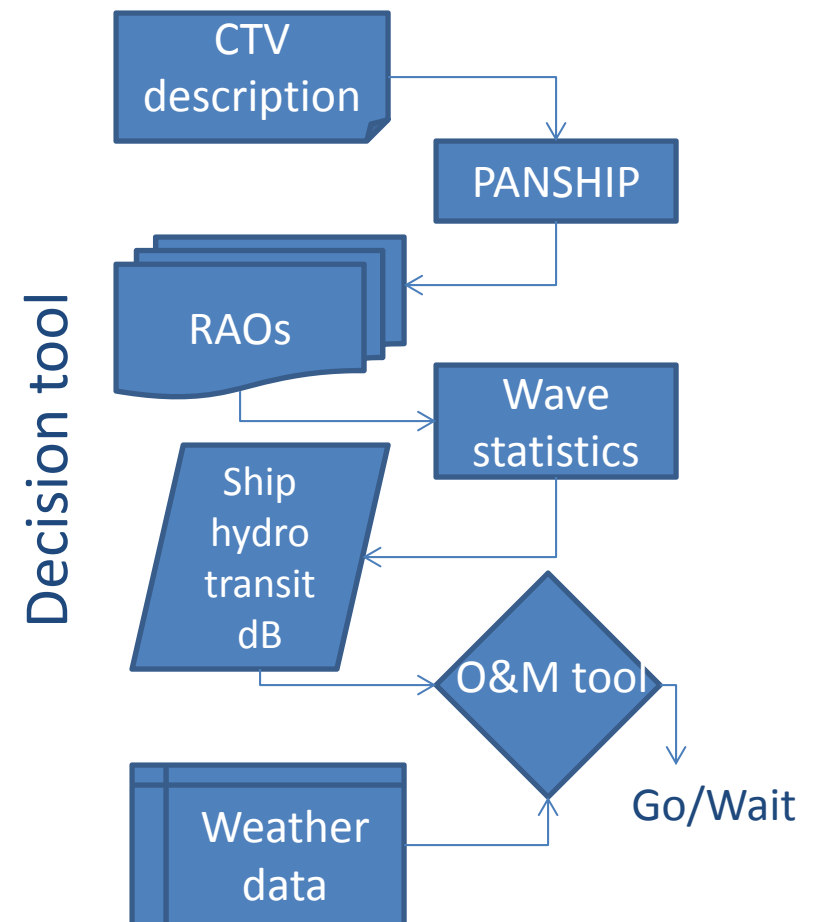
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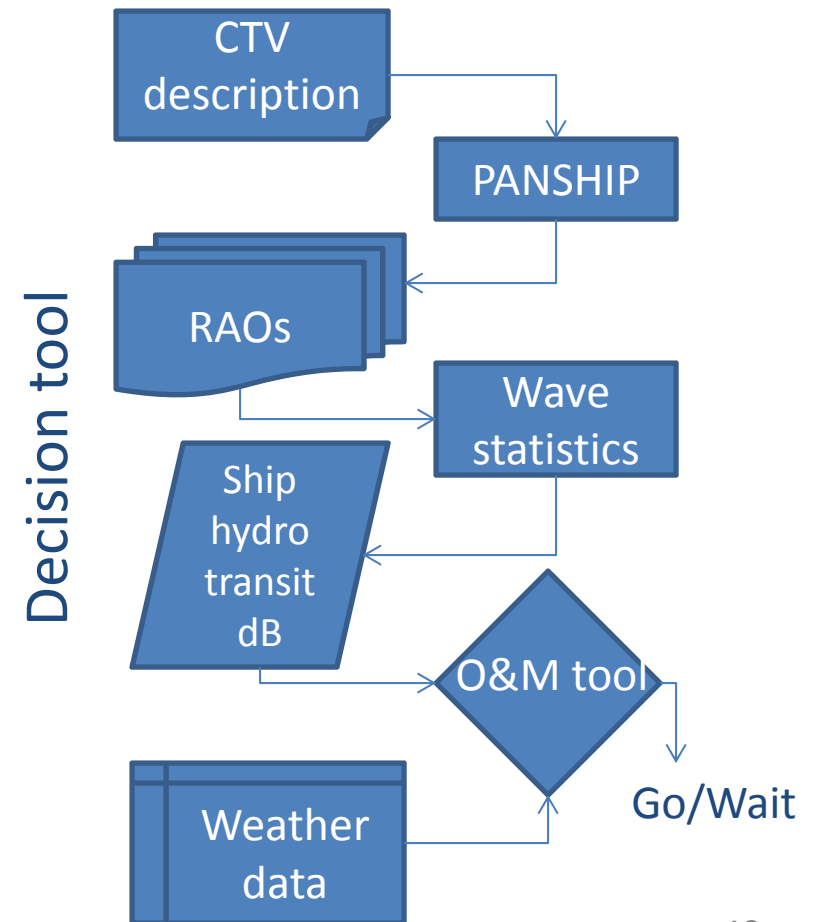
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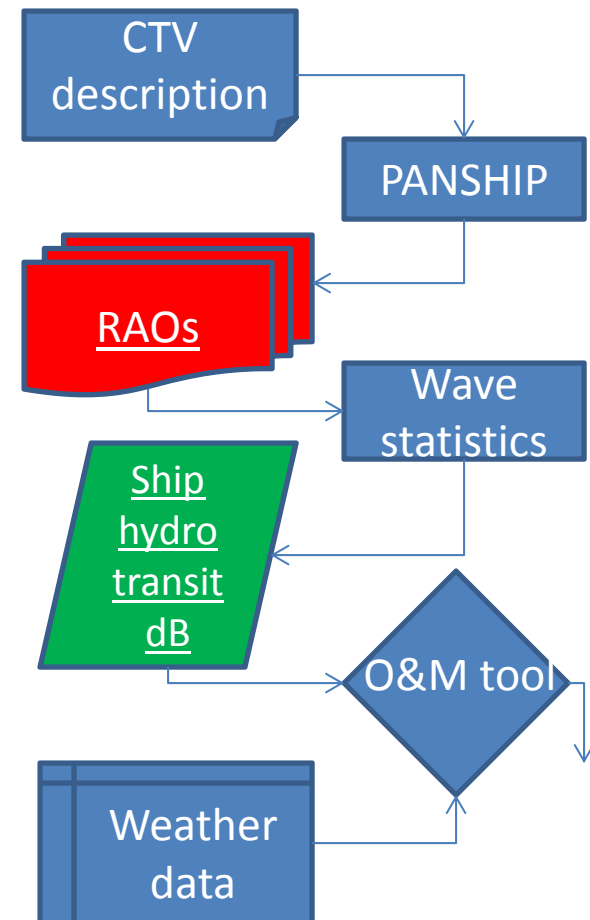


Most direct approaches

- Validation framework allowing for comparison at:

A) Frequency level

Spectral correlation of vessel motions and accelerations



Most direct approaches

- Validation framework allowing for comparison at:

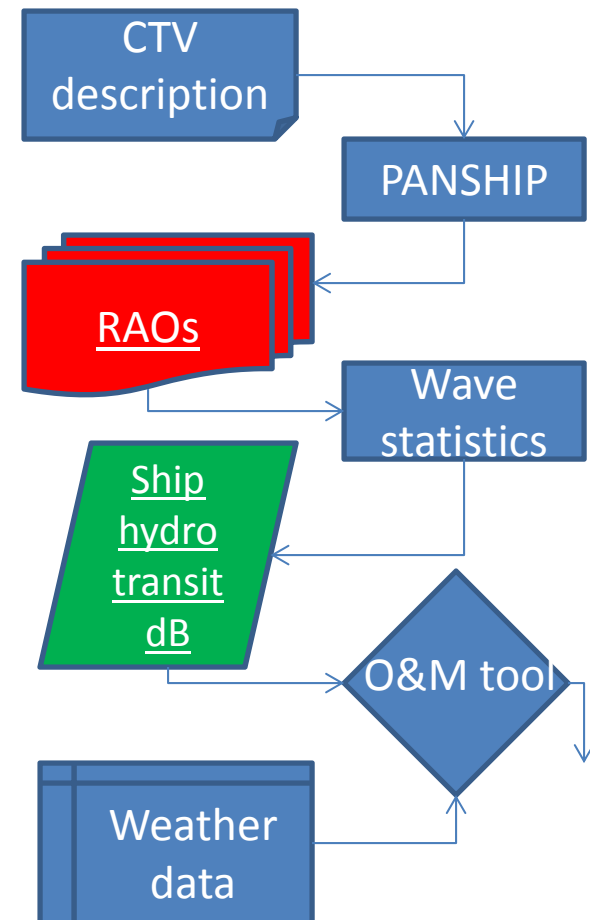
A) Frequency level

Spectral correlation of
vessel motions and
accelerations

B) Sea-state level

SDA of vessel motions
and accelerations

$$SDA = 4\sigma = 4\sqrt{m_0}$$



Most direct approaches

- Validation framework allowing for comparison at:

A) Frequency level

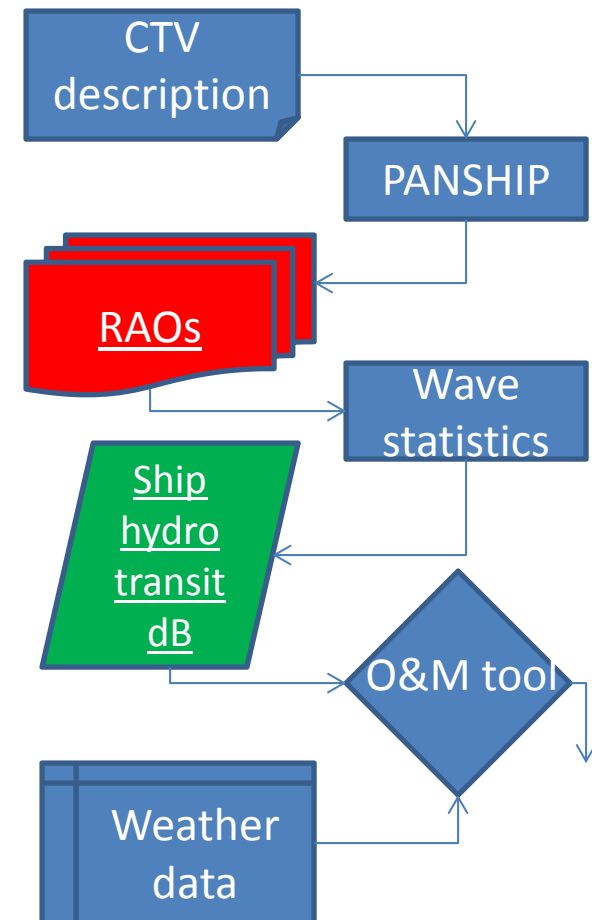
Spectral correlation of
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B) Sea-state level

SDA of vessel motions
and accelerations

- Extract measurement data set for comparison:

- ~ steady heading
- ~ steady speed
- ~ steady wave condition (also wind and current)



Outline

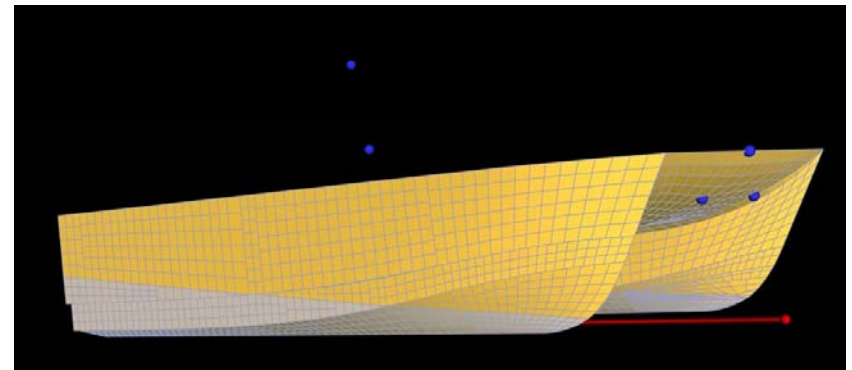
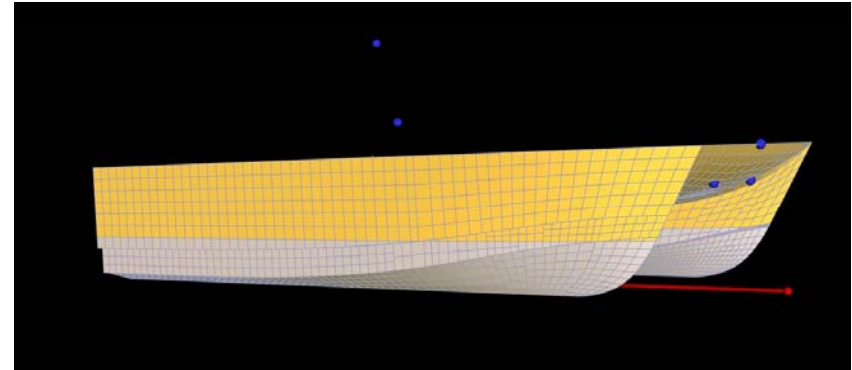


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- **Ship motion numerical assessment**
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Ship motion numerical assessment



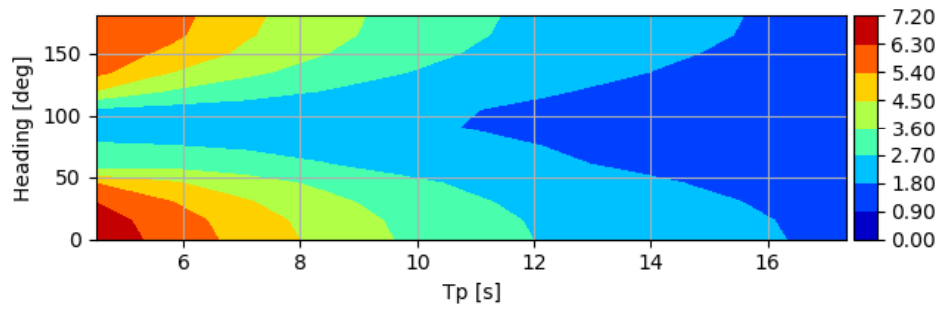
- RAO database calculated for 6 CTV with PANSHIP
- Assumptions:
 - Linear ship motions
 - Hull lines taken from general arrangement
 - GM, draft received from BMO
 - Radii of inertia estimated
 - No trim flap + trim flap with fixed angles



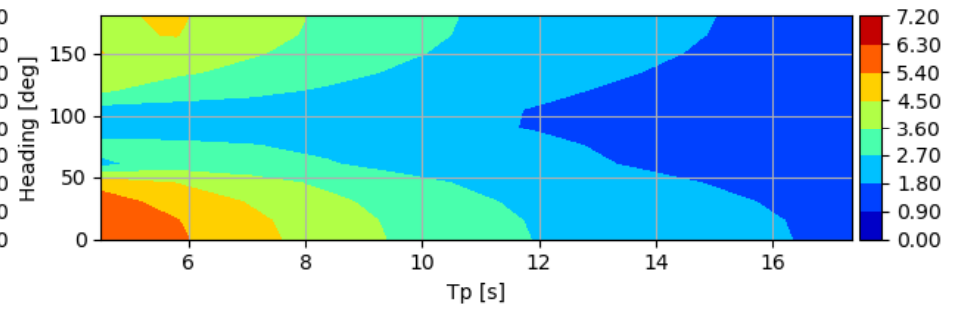
SDA pitch in $H_s=1\text{m}$ @ $V_s=25\text{kn}$



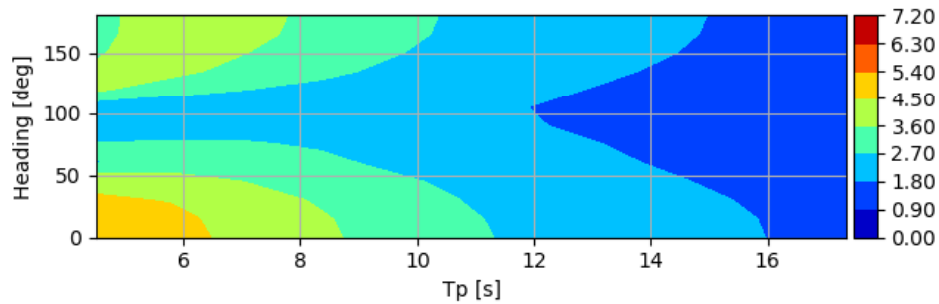
Cat loa~13m $H_s: 1.0\text{m}$
SDA_pitch_motion [deg]



Cat loa~15m $H_s: 1.0\text{m}$
SDA_pitch_motion [deg]



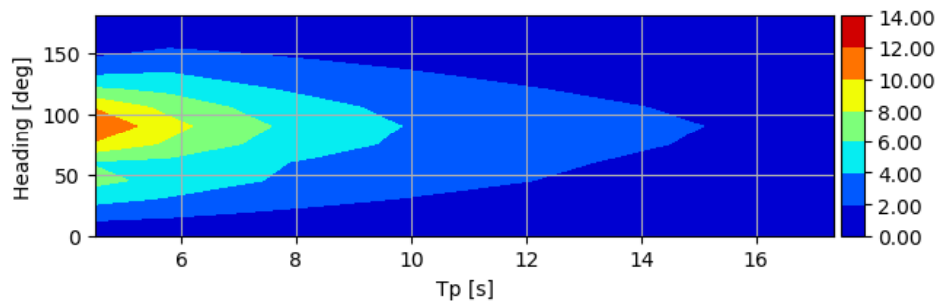
Cat loa~20m (TF=2deg) $H_s: 1.0\text{m}$
SDA_pitch_motion [deg]



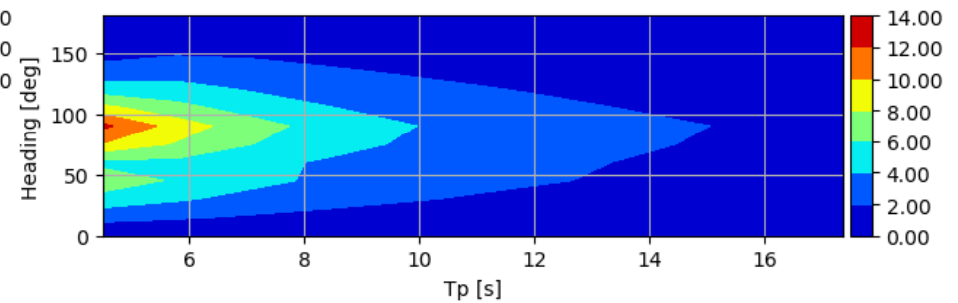
SDA roll in $H_s=1\text{m}$ @ $V_s=25\text{kn}$



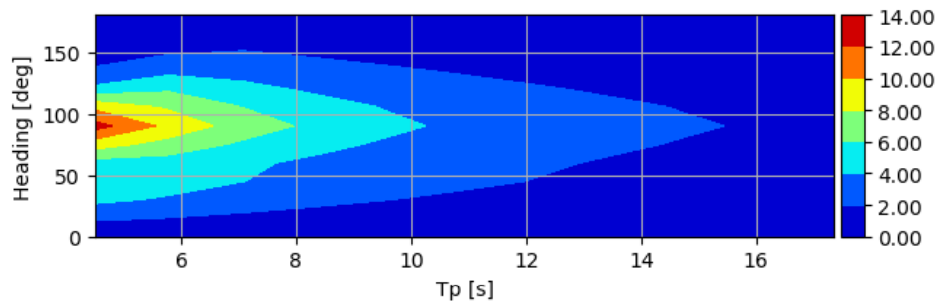
Cat loa~13m $H_s: 1.0\text{m}$
SDA_roll_motion [deg]



Cat loa~15m $H_s: 1.0\text{m}$
SDA_roll_motion [deg]



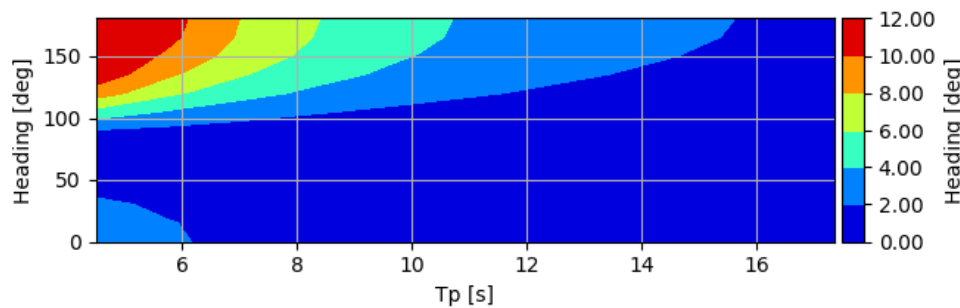
Cat loa~20m (TF=2deg) $H_s: 1.0\text{m}$
SDA_roll_motion [deg]



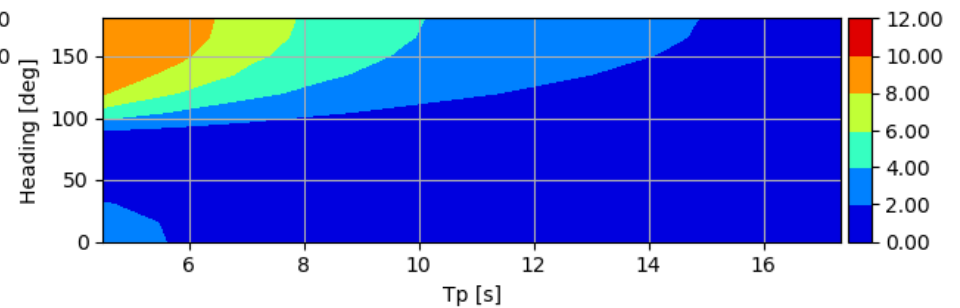
SDA vertical acceleration in Hs=1m @ Vs=25kn



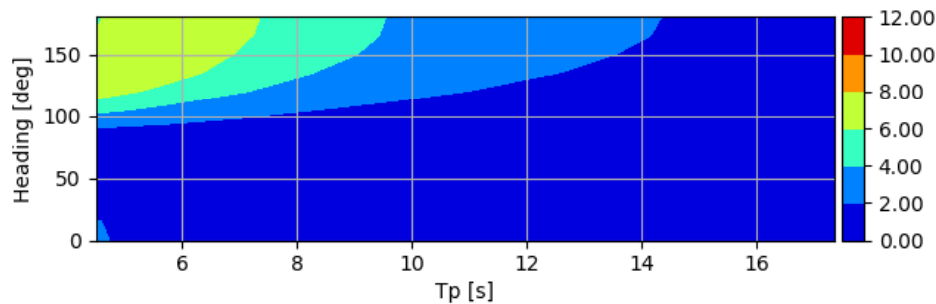
Cat loa~13m Hs: 1.0m
SDA_VerticalAcceleration [m/s²]



Cat loa~15m Hs: 1.0m
SDA_VerticalAcceleration [m/s²]



Cat loa~20m (TF=2deg) Hs: 1.0m
SDA_VerticalAcceleration [m/s²]

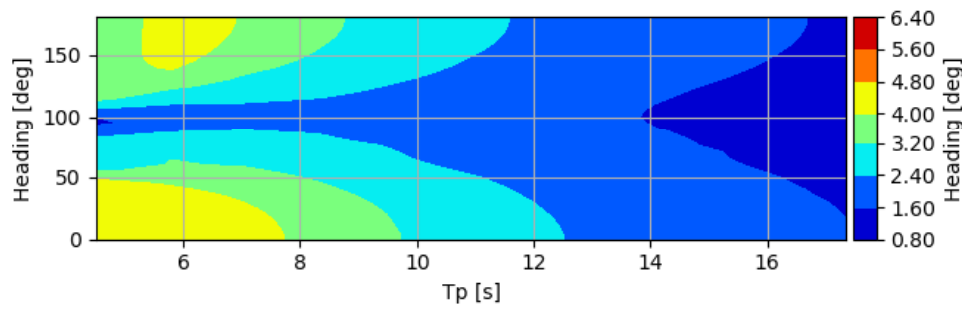


@Crew seats
Nordforsk: 11 m/s²

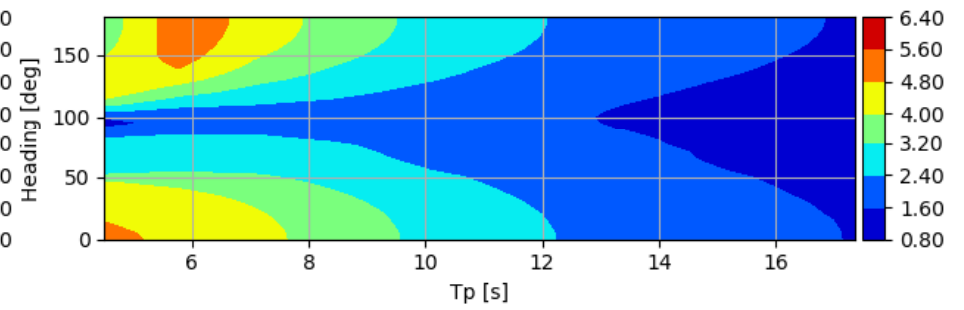
Effect of trim flap angle on pitch



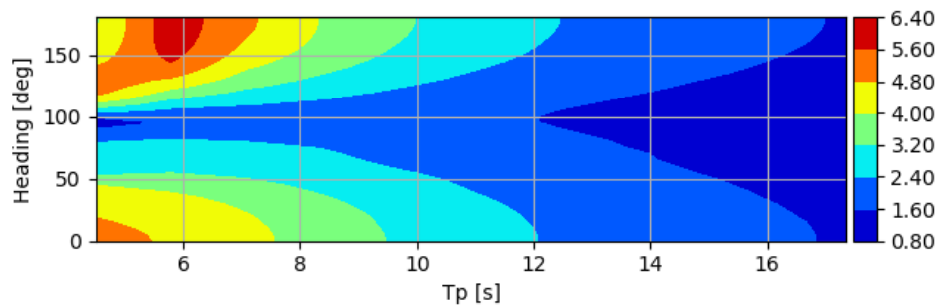
Cat loa~20m(TF=2deg) Hs: 1.0m
SDA_pitch_motion [deg]



Cat loa~20m(TF=4deg) Hs: 1.0m
SDA_pitch_motion [deg]



Cat loa~20m(TF=6deg) Hs: 1.0m
SDA_pitch_motion [deg]



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Explore and analyze measurements prior to validation



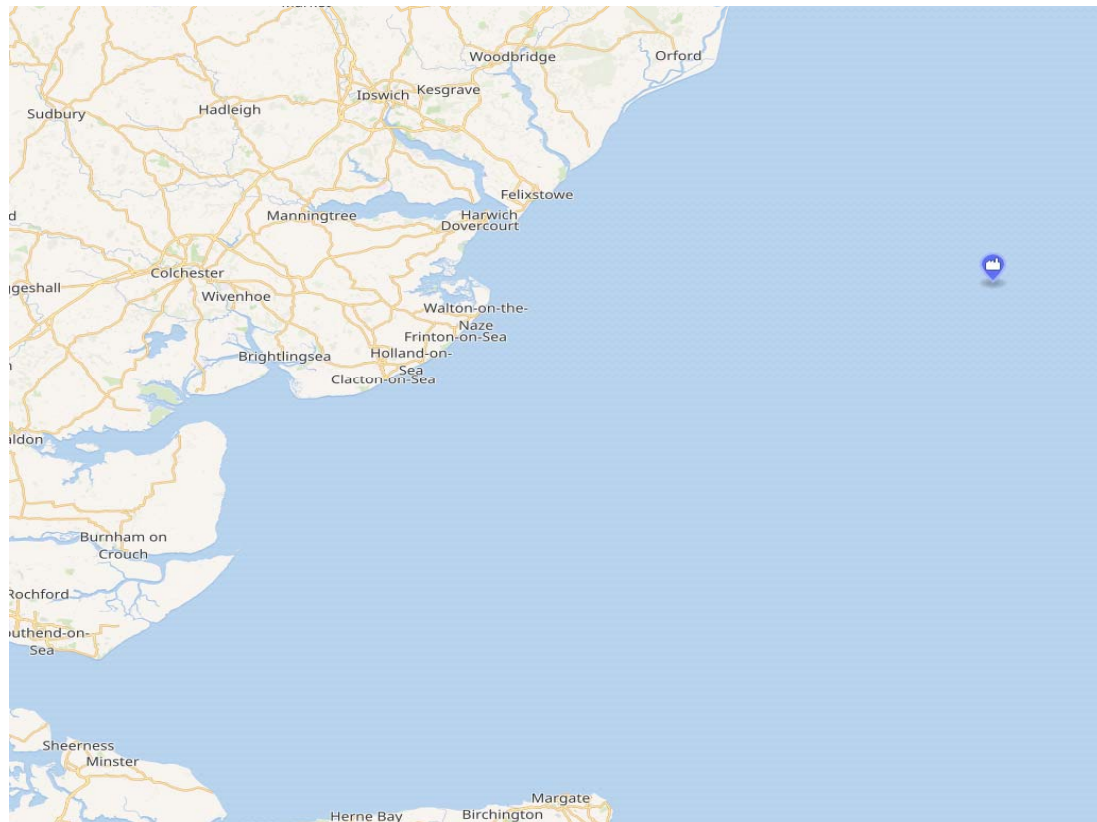
- Wave data
 - Wave buoy (not everywhere)
 - Satellite (+model(s)): Copernicus
- Vessel motion data
 - BMO data

Greater Gabbard

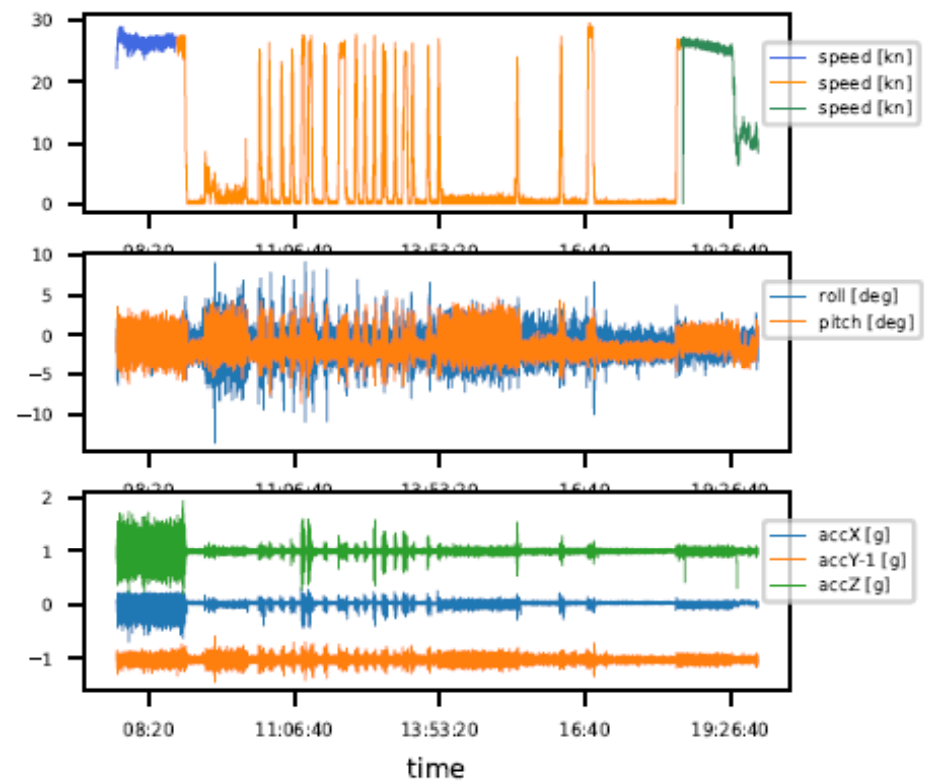
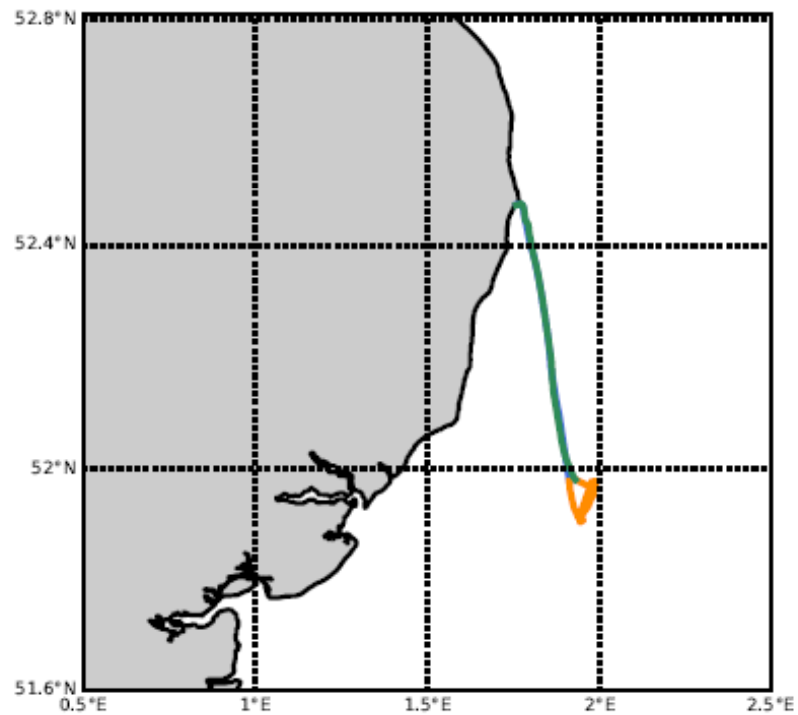


Greater Gabbard

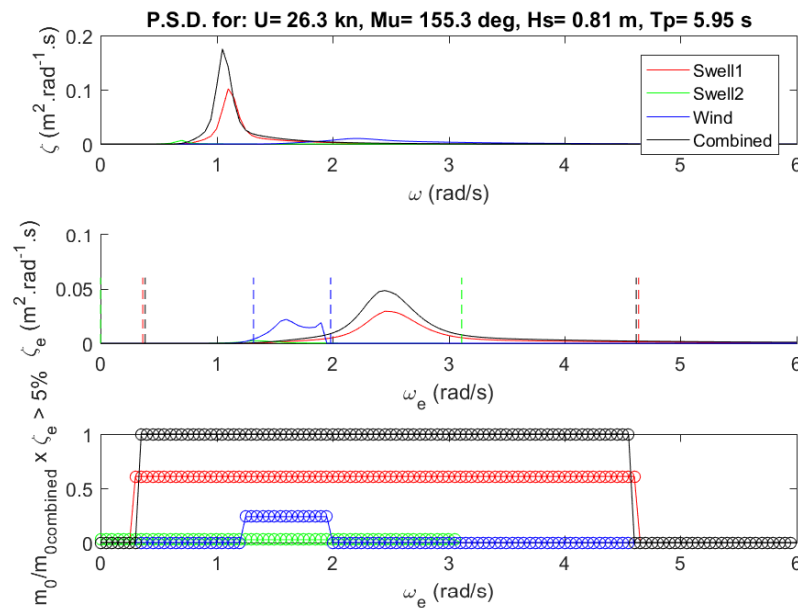
 <p>Location of Greater Gabbard wind farm in the North Sea</p>	
Country	England
Location	Inner Gabbard and The Galloper banks North Sea Suffolk Coast
Coordinates	 51°52′48″N 1°56′24″E
Status	Operational
Commission date	2012
Owner(s)	Scottish and Southern RWE Npower Renewables
Wind farm	
Type	Offshore
Distance from shore	23 km (14 mi)
Power generation	
Units operational	140
Make and model	Siemens Wind Power: SWT3.6–107
Nameplate capacity	504 MW
Annual net output	1,800 GW·h (2013) ^[1]
External links	
Commons	Related media on Commons
[edit on Wikidata]	



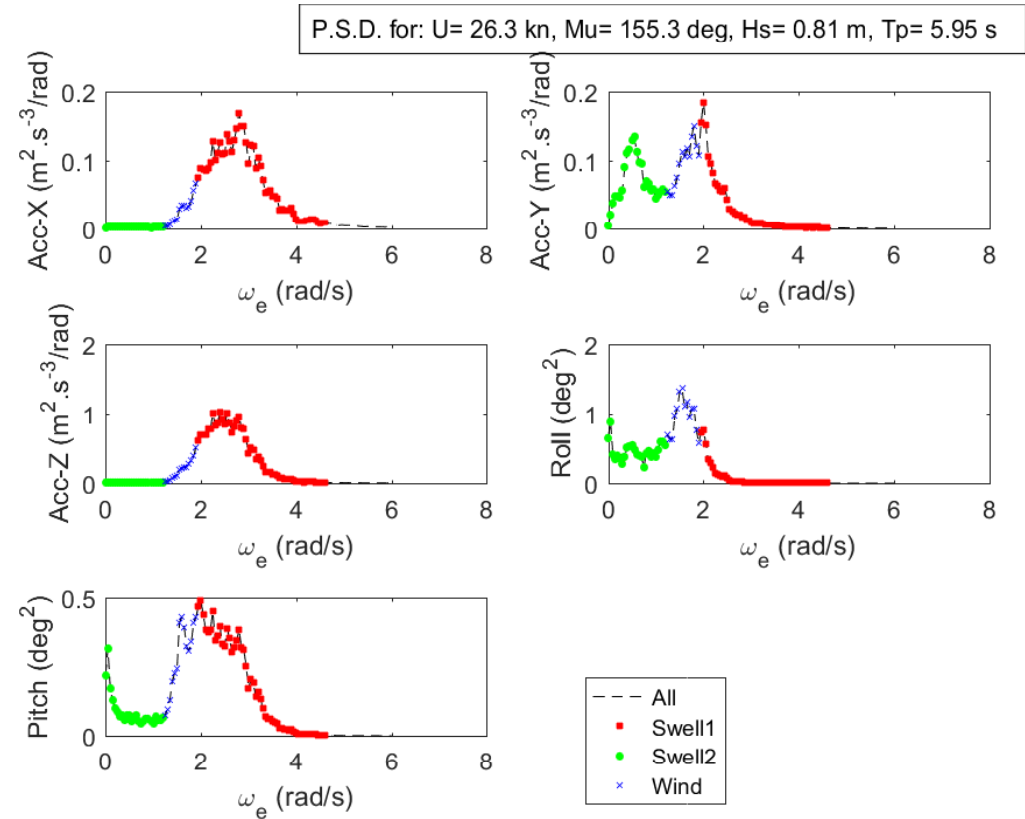
Example of vessel measurement data



Example of PSDs during transit

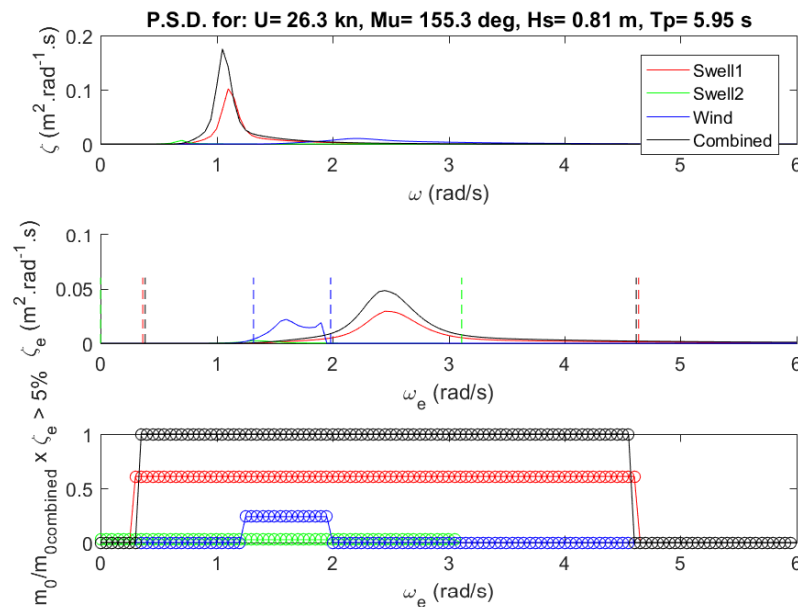


	mu_deg	Hs_m	Tp_s	m0_SI
Swell11	144.76	0.63252	5.6775	0.023753
Swell12	177.54	0.12757	9.1185	0.0010117
Wind	275.36	0.41259	2.8567	0.009289
Combined	155.28	0.81012	5.9503	0.038997

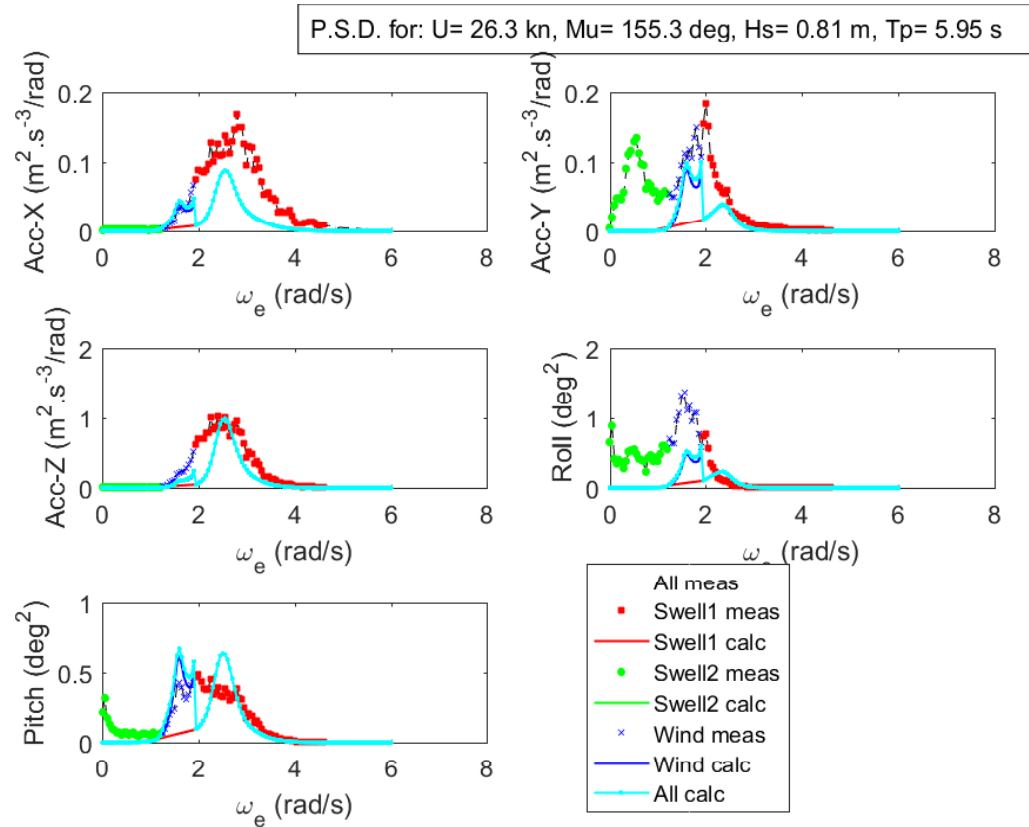


WAFO: <http://www.maths.lth.se/matstat/wafo>

Example of PSDs during transit with simulation results



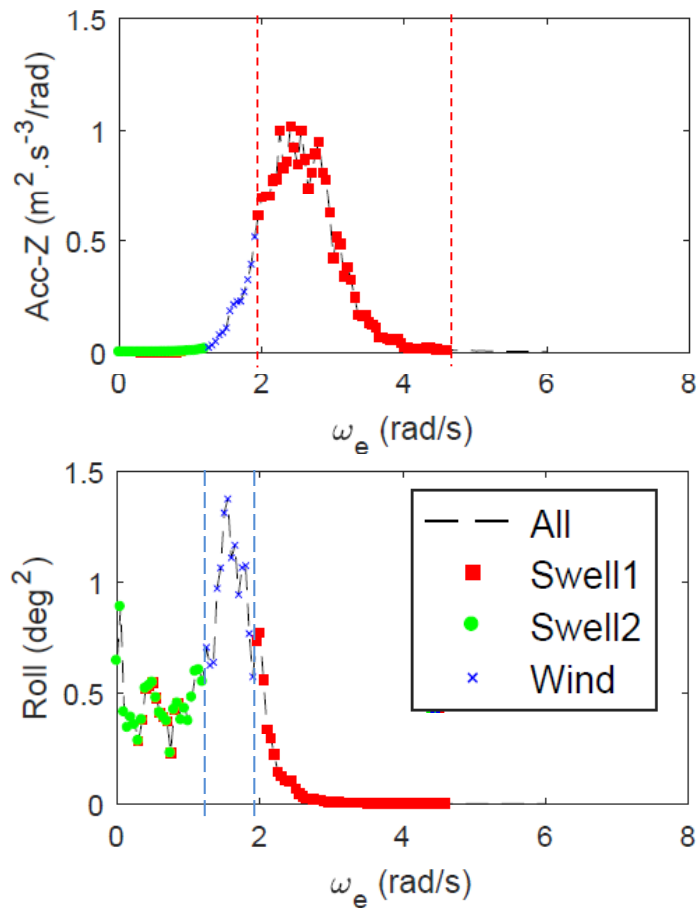
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PSD of vertical acceleration and PSD of roll

P.S.D. for: $U = 26.3$ kn, $Mu = 155.3$ deg, $H_s = 0.81$ m, $T_p = 5.95$ s

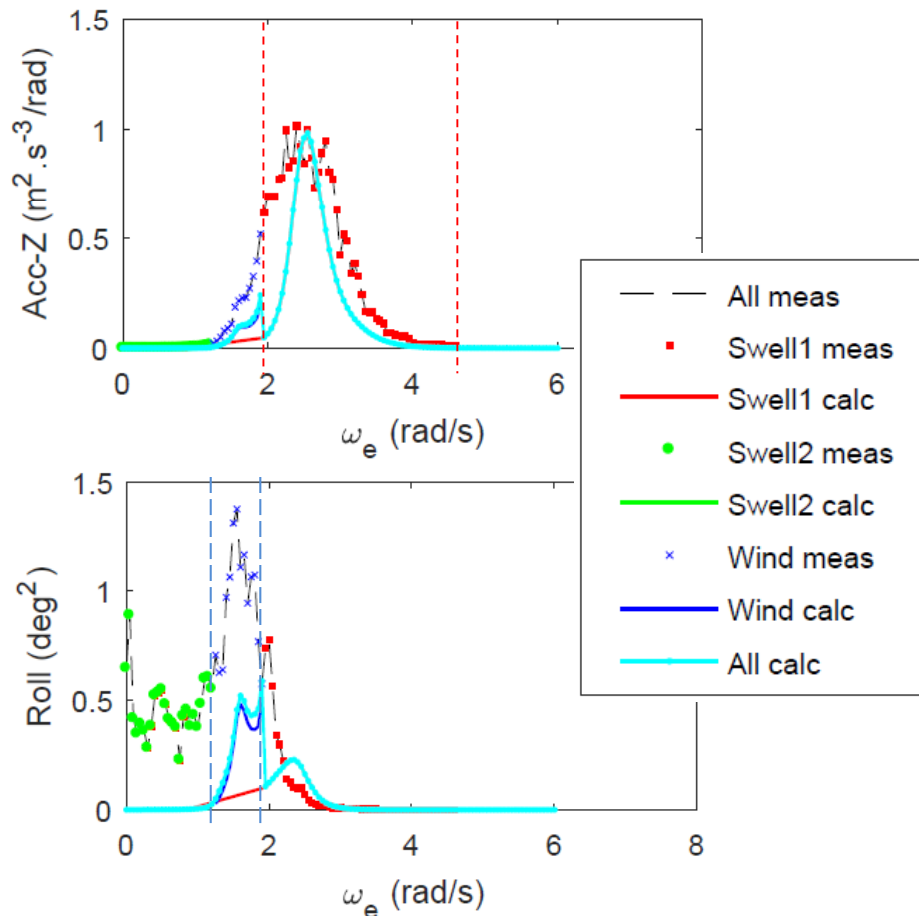


Observations:

- Importance of distinct wave components
- Peaks are generally linked to a main WF component
- Lot's happening outside the main wave component:
 - LF response (roll)

PSD of vertical acceleration and PSD of roll

P.S.D. for: $U = 26.3$ kn, $Mu = 155.3$ deg, $H_s = 0.81$ m, $T_p = 5.95$ s



+:

- Distinct wave components
- Peaks are represented (global trend is there)

-:

- Amplitude are different (wind wave)
- Different m_0 (SDA)
- What's happening outside the main wave components is disregarded
 - No LF response (or swell 2)

First lessons, some hypotheses are questionable:

- JONSWAP for small waves
- Linear assumption
- Fidelity of CTV input data

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- **Conclusions**

Conclusions



- **A lot to learn from onboard measurements**
 - Most precise definition as possible is recommended
 - Copernicus is a good start (more wave components in distinct directions)
 - Quantification of directional spreading is currently missing
- PANSHIP validation based on onboard measurements not easy
 - Hull lines, loading condition and trim flap angle not known and all have large effect on linear ship motions
 - Local weather conditions not fully known (directional spreading, current, wind)
 - Uncertainty over heading, trim flap
- Driving factor for operability not precisely known but **seakeeping tools can help** with:
 - Seasickness/fatigue of maintenance crew
 - MSI within tool boundaries

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THANK YOU!



Contributors:

- BMO team
- Gerben Spaans
- Rob Grin
- Christian Lena
- Ka Wing Lam
- Erik-Jan de Ridder
- Jorrit-Jan Serraris

- EU with Copernicus
- Lund University with WAFO

