

# Framework for optimal met-ocean sensor placement in offshore wind farms

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Deepwind 2020 15 Jan 2020, Trondheim **Project partners** 





# Innovate UK

15 Jan 2020

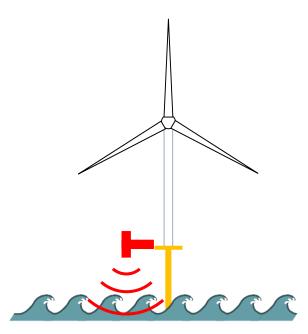
Erik Salo - Framework for optimal met-ocean sensor placement in offshore wind farms - Deepwind 2020



#### Point measurement of wave height

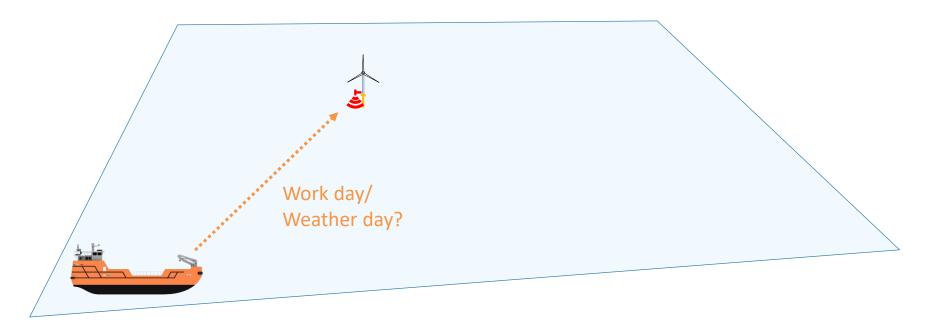
- Downward-facing wave radar
- Real-time data
- H<sub>s</sub> ≈ turbine access

- Where best to place sensors?
- What are the conditions at other, sensorless turbines?





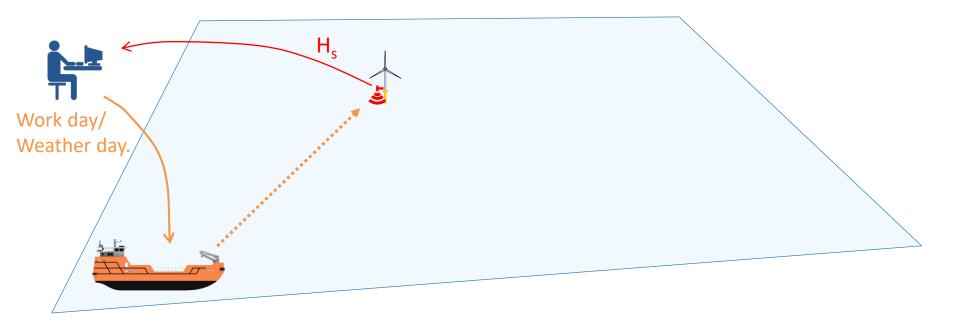
Sensor data - local conditions



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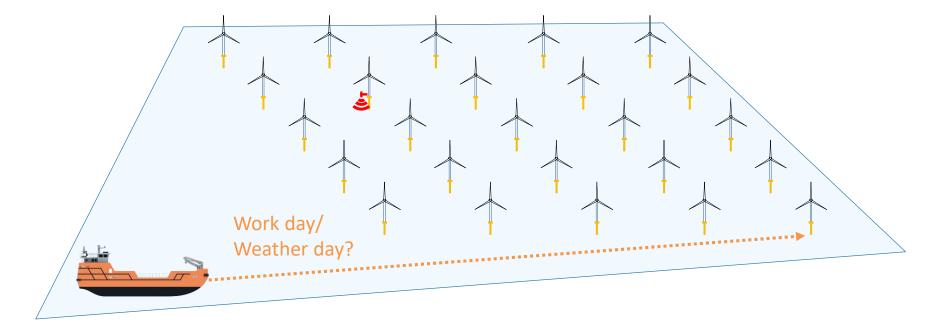
Marine coordinator uses sensor data directly



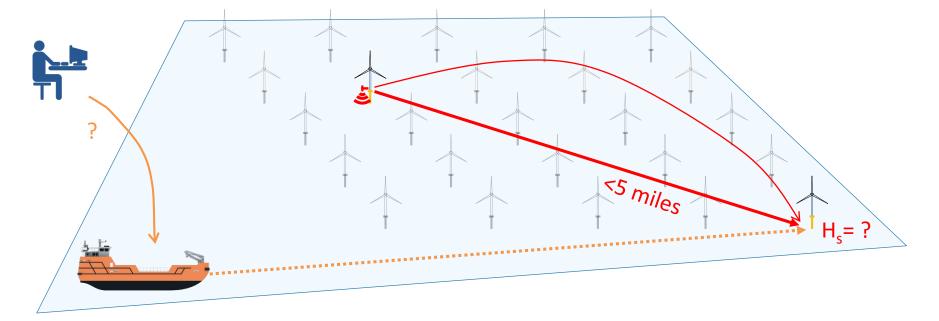


Without local sensor data





How to assess the conditions 'out there'? Forecast is often inaccurate on a very local scale





University of Strathclvde

Engineering

#### Spatial sensor coverage

How far from a point measurement can we extrapolate?

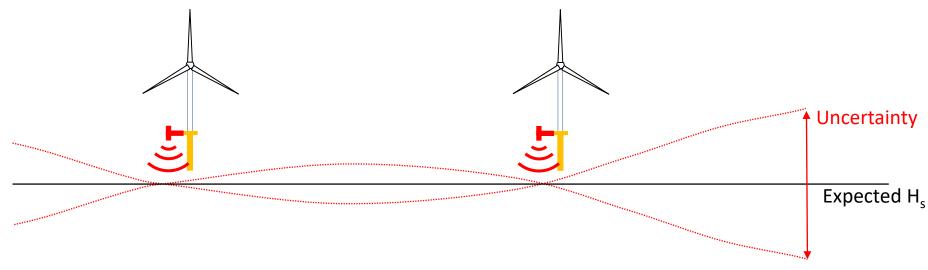




Expected H<sub>s</sub>

### Spatial sensor coverage

How far from a point measurement can we extrapolate? Uncertainty estimated using a Gaussian process

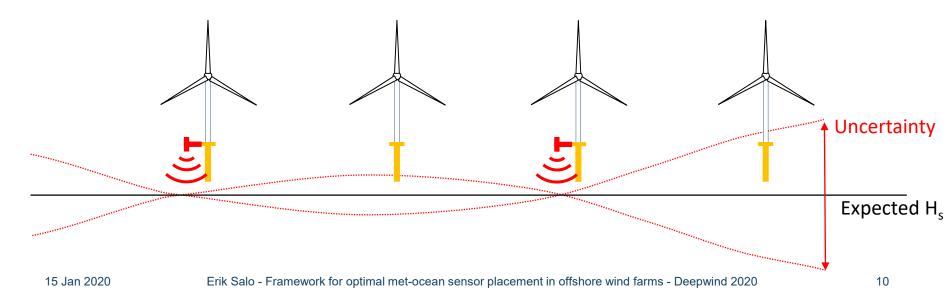




# Spatial sensor coverage

How far from a point measurement can we extrapolate? Uncertainty estimated using a Gaussian process:

- Low at turbine locations
- Higher as distance increases

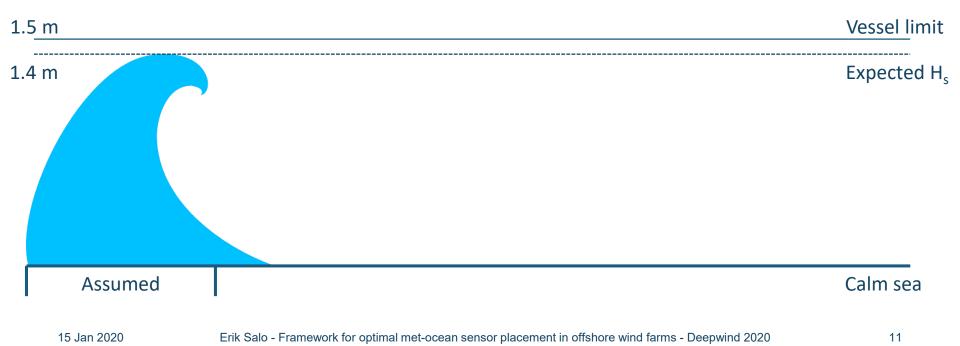




#### Scale of uncertainty

Wave height estimates in marginal conditions (95% confidence)

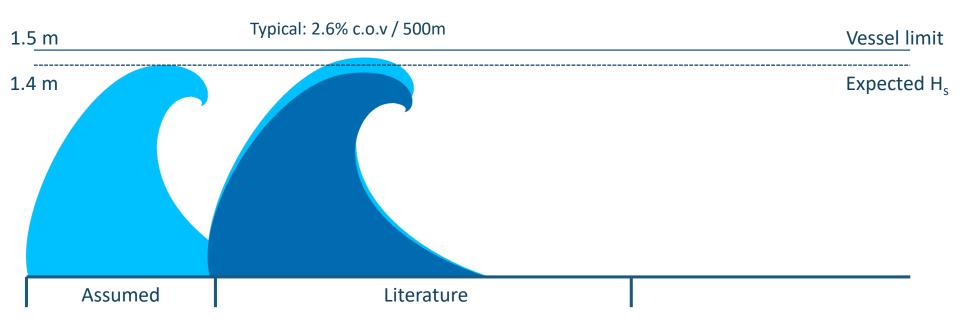




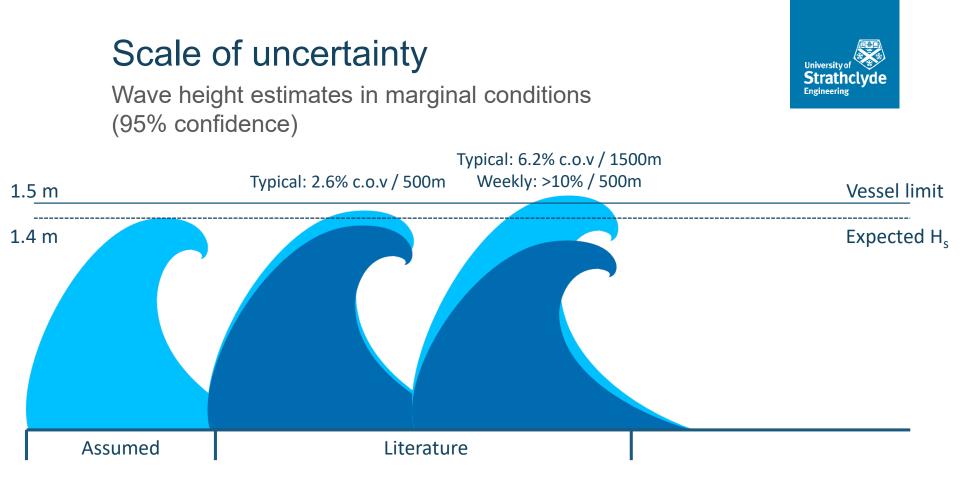
#### Scale of uncertainty

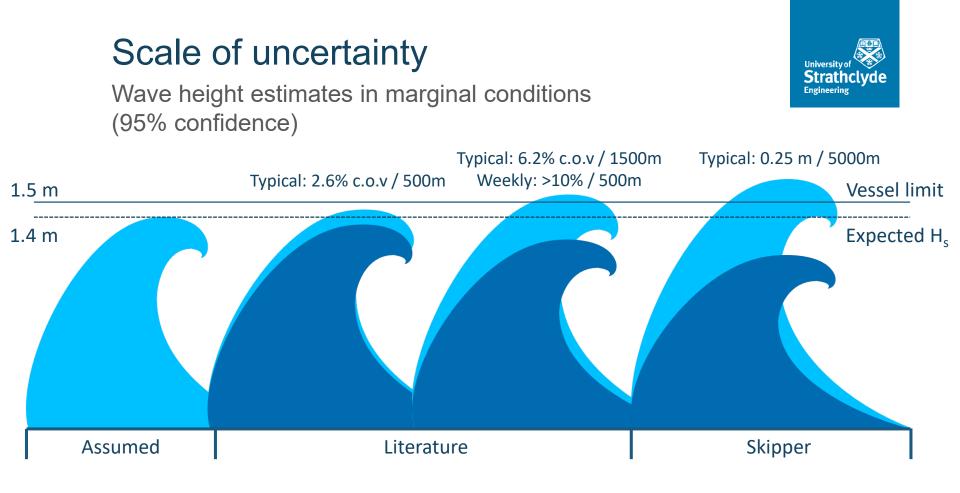
Wave height estimates in marginal conditions (95% confidence)





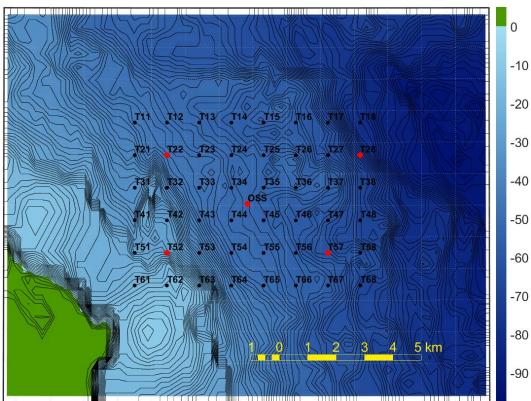
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#### Example case

Hypothetical site in UK waters

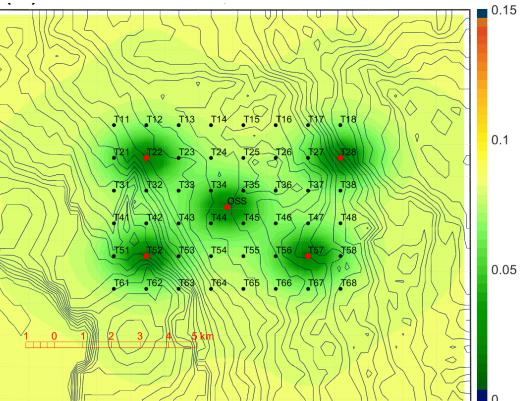




- Hypothetical site in Scotland.
- GEBCO 2019 bathymetry. Red dots represent turbines with Hs sensors.

#### Example case

#### Uncertainty modelled using Gaussian process

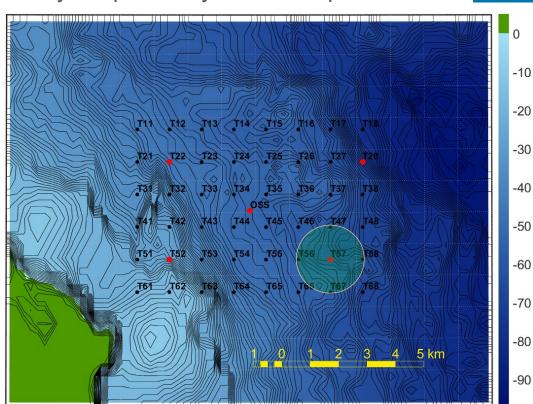




Hypothetical site in
Scotland.
GEBCO 2019 bathymetry.
Red dots represent
turbines with Hs sensors.
6% c.o.v across site.
Average of 10 model runs.

Local variations not always captured by Gaussian process

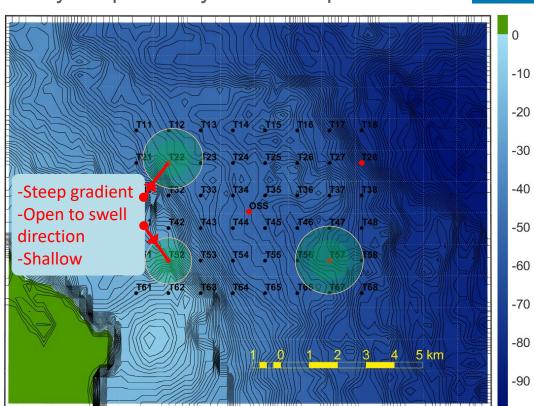
- Hs
- Swell
- Tide
- Current
- Wind
- Bathymetry





Local variations not always captured by Gaussian process

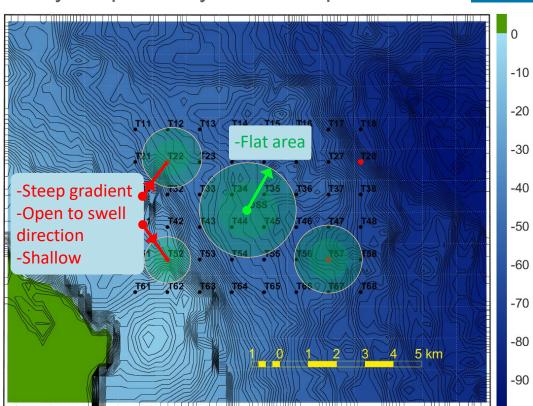
- Hs
- Swell
- Tide
- Current
- Wind
- Bathymetry





Local variations not always captured by Gaussian process

- Hs
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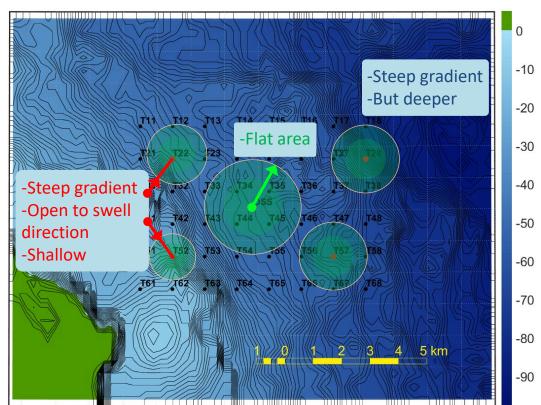


Local variations not always captured by Gaussian process

- Hs
- Swell
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- Current
- Wind

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• Bathymetry

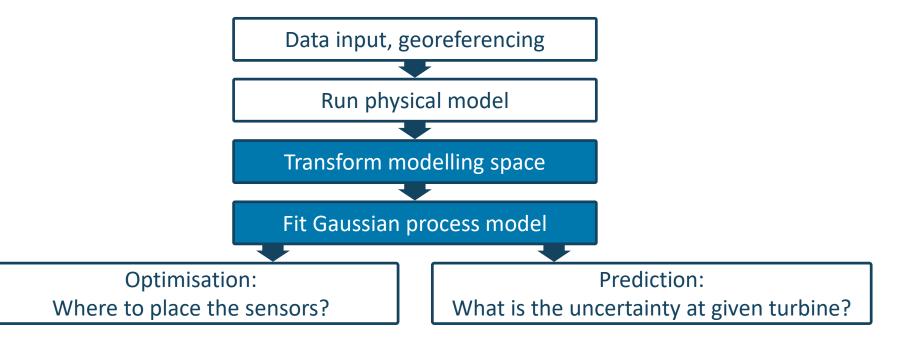




### **Proposed framework**

To include spatial uncertainty in decision-making





# Conclusions



- We propose a framework to maximise the decision value of Hs point measurements
- 3-5 point measurements seen as optimum
  - Bathymetry mainly determines placement
- Value of uncertainty quantification in O&M decisions:
  - <£1 M per year per site
- Ongoing work:
  - Trials at two UK sites
  - Transformations
  - Validation



# Thank you for your attention!

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