

DOCUMENTATION VERIFICATION AND VALIDATION OF REAL-TIME HYBRID MODEL TESTS WITH THE 10MW OO-STAR WIND FLOATER

Maxime Thys (SINTEF Ocean)
Lene Eliassen (SINTEF Ocean)
Petter A. Berthelsen (SINTEF Ocean)

Valentin Chabaud (SO/NTNU)
Thomas Sauder (SO/AMOS)

Layout

- Model testing: motivation and limitations
- Real-Time Hybrid Model testing
- OO-Star Wind Floater ReaTHM tests
- Verification
- Conclusion

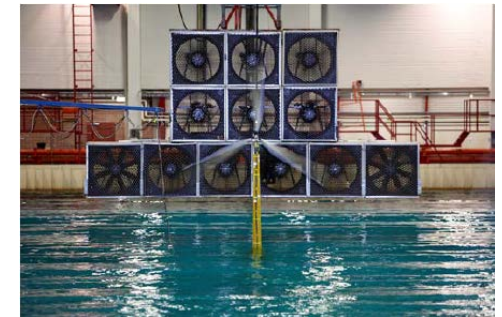
Motivation for model tests

- Common to all offshore structures
 - Significant investments should be de-risked and optimized
 - Some physical effects are not modelled correctly by engineering tools yet
 - Some physical effects are not known yet
 - Specific to FOWT
 - Complex coupling between wind and wave loads, structure and blade dynamics.
- Issue: the experiments must capture these couplings correctly

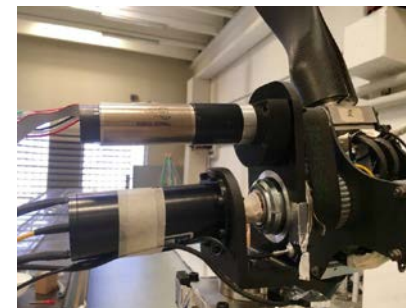


Limitations of classical approaches

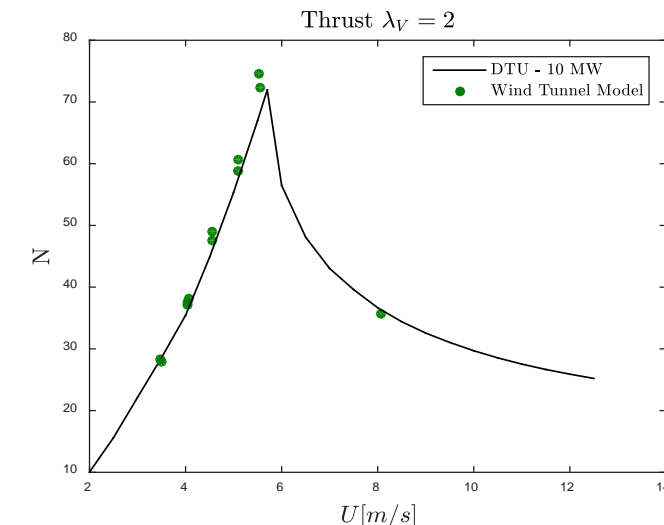
- Tests in wave tanks, using fans to generate the aerodynamic loading
 - *Challenge 1*: ensure a correct wind field above the wave field → accuracy, repeatability, traceability
 - *Challenge 2*: ensure a correct mass distribution of the RNA model
 - *Challenge 3*: Froude/Reynolds scaling conflict, and rotor re-design by "Performance scaling"



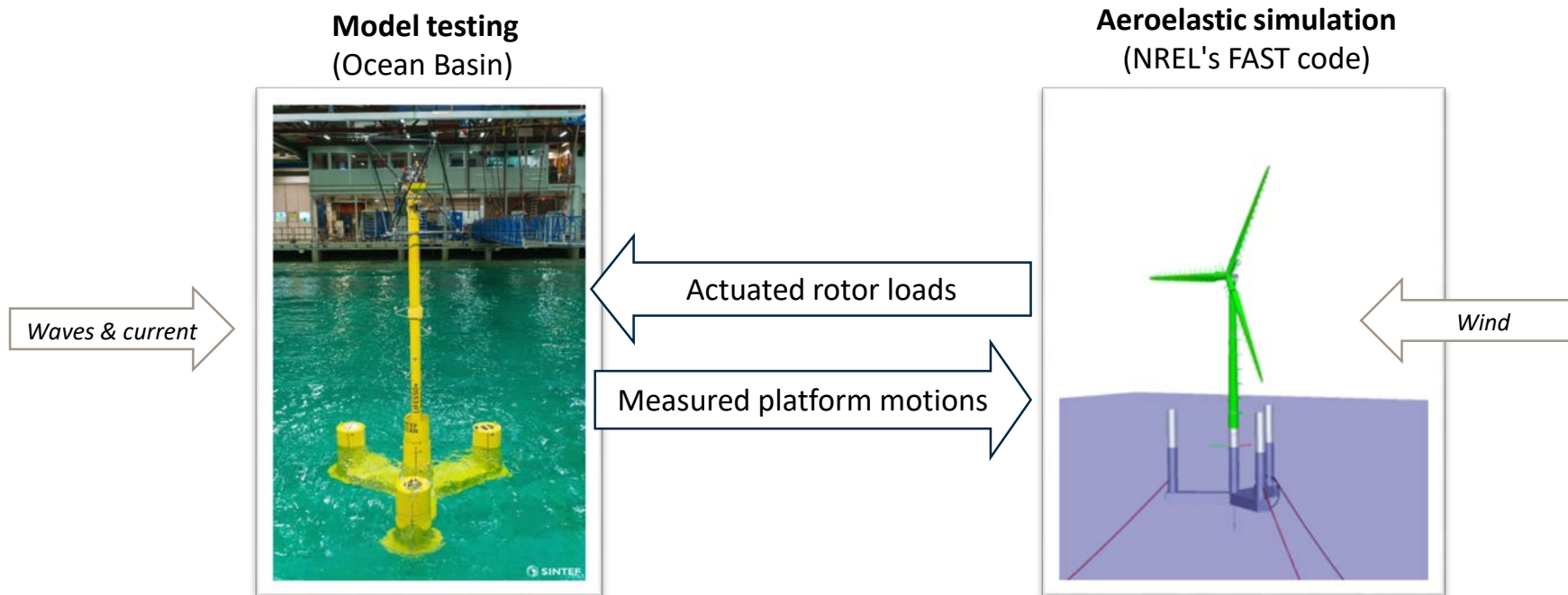
Hywind demo, 2005



Politecnico Milano / 2016



Real-Time Hybrid Model (ReaTHM[®]) testing



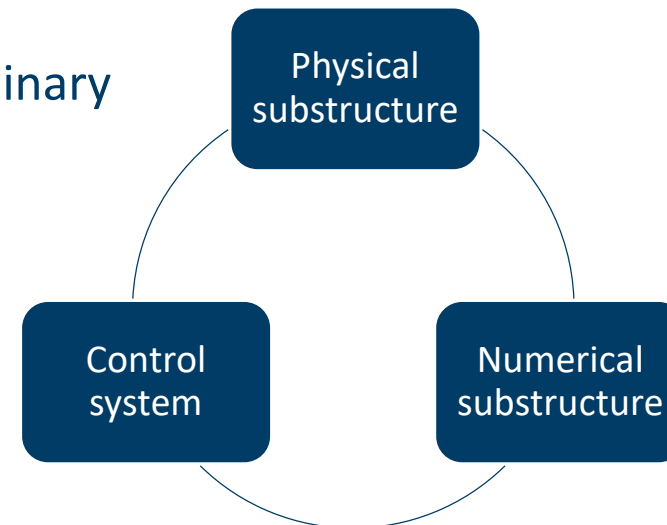
ReaTHM[®] testing

Strong points of ReaTHM[®] testing?

- Realistic and controlled rotor loads
- Possibility to test extreme conditions
- Cost-effective and flexible

Any challenges?

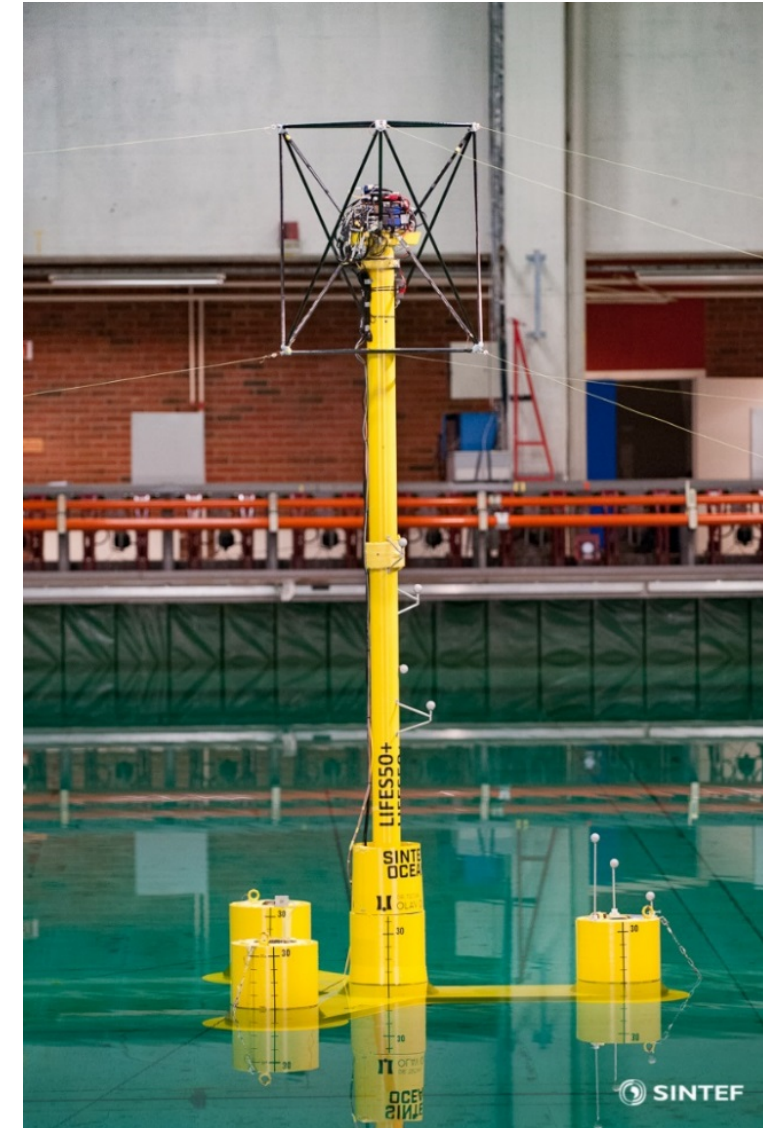
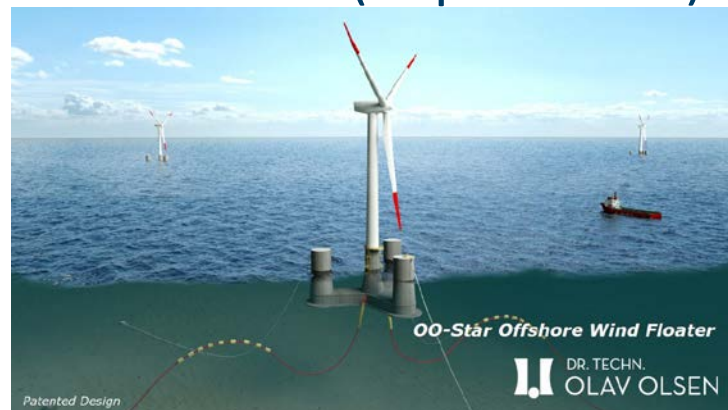
Multidisciplinary



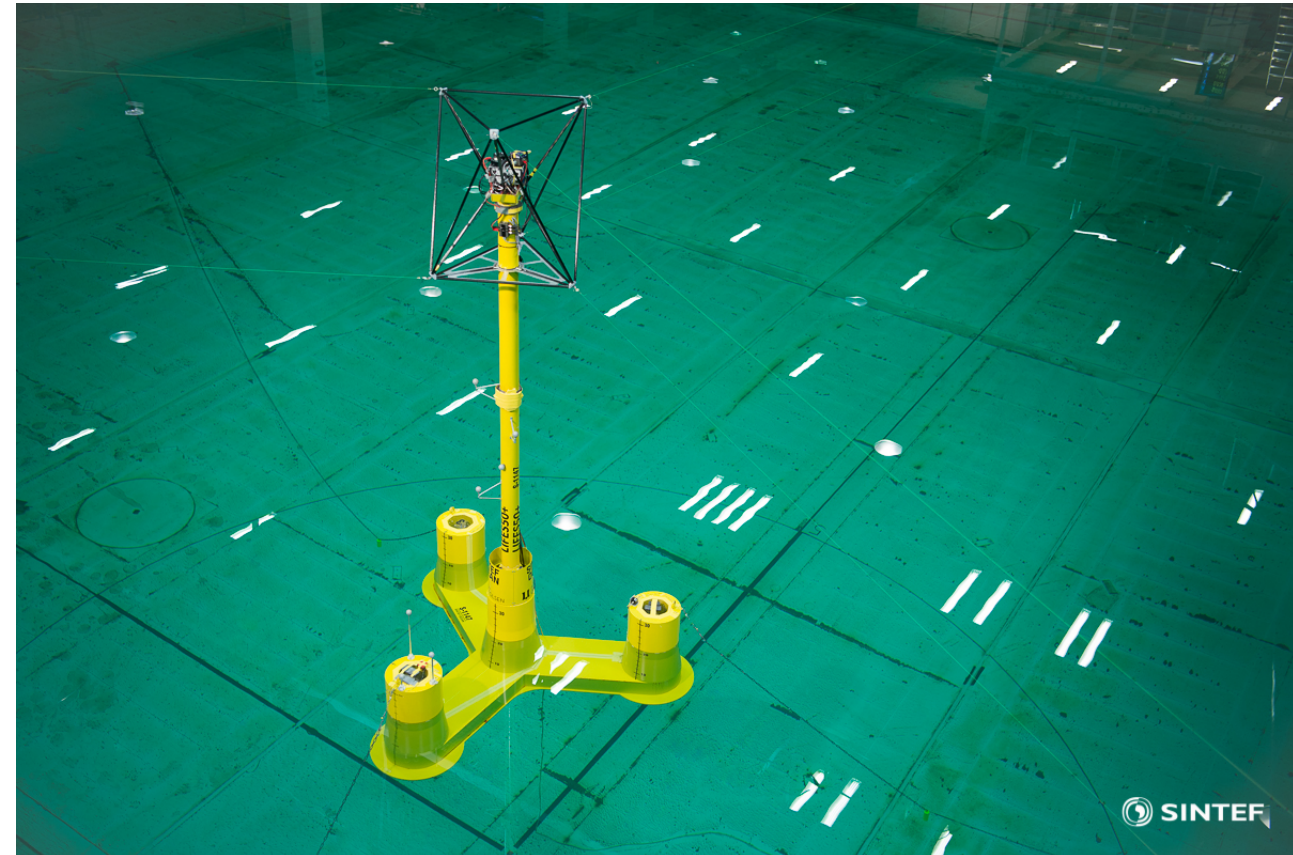
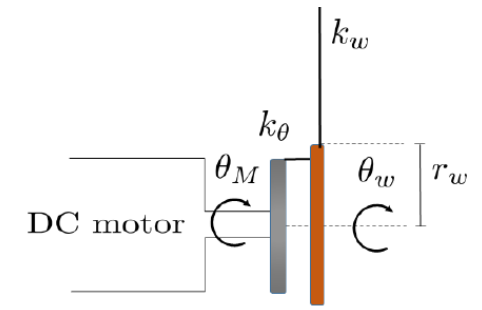
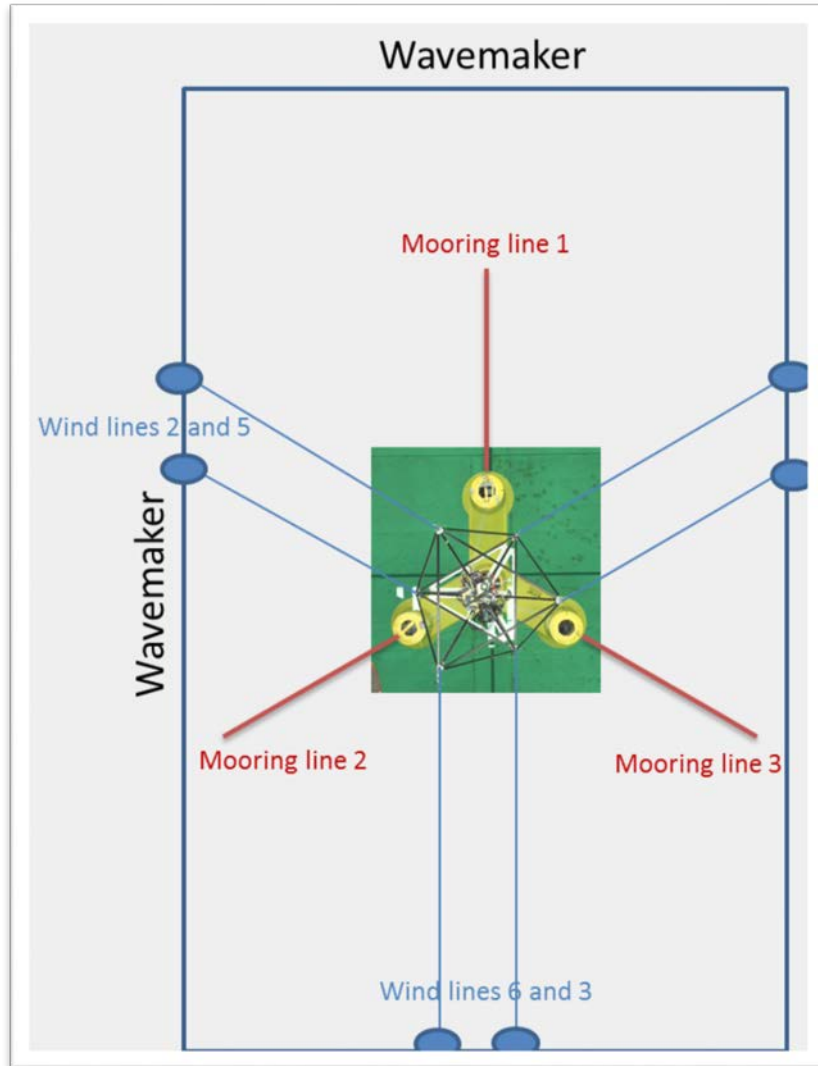
How to ensure high quality testing?

OO-Star Wind Floater model tests

- Lifes50+ H2020 project (<http://lifes50plus.eu/>)
- OO-Star Wind Floater with DTU 10MW turbine
- Tested in Nov 2017 in the Ocean Basin at SINTEF Ocean
- Scale 1/36
- Environmental conditions of Gulf of Main (depth 130m)
- Objectives:
 - Concept performance verification
 - Data for num. calibration
 - Develop hybrid methods

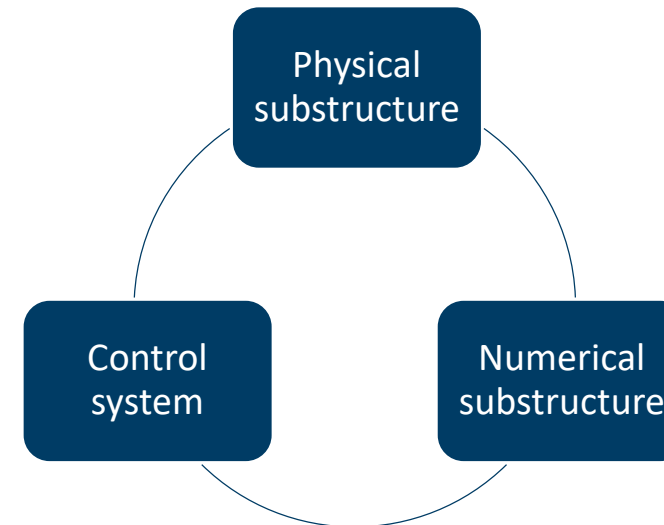


OO-Star Wind Floater model tests



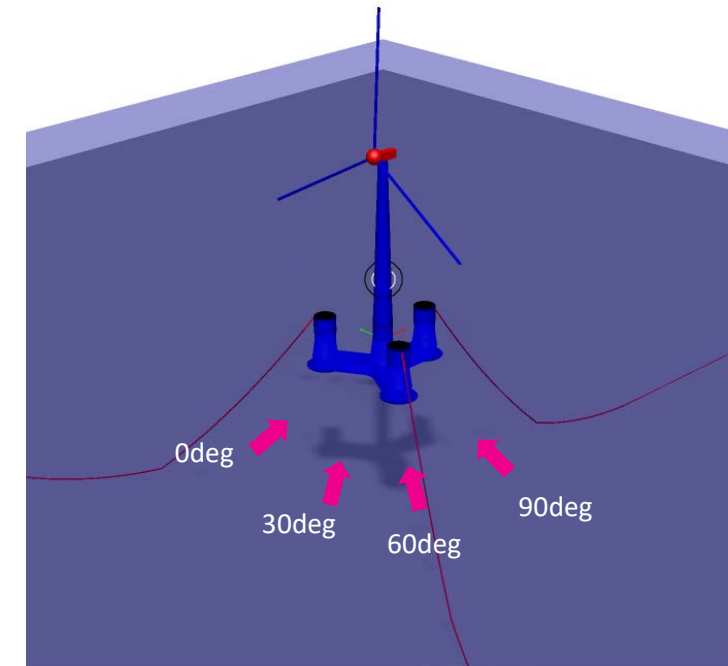
Verification: Stepwise approach

- General: Sensitivity study
- Substructure Verification
- Verification of complete system



Verification: Sensitivity study

- How important are each of the turbine load components for operational and parked conditions?
- Realized by use of Riflex-SIMO-Aerodyn, where rotor loads are modified one by one.
- Sensitivity to
 - aerodynamic sway, heave, pitch, and yaw
 - Gyro moments/centrifugal forces
 - Vertical and horizontal directionality
- 16 loading conditions



Description	Unit	EC1	EC2	EC3	EC4
Wind	m/s	8.0	11.4	20.0	44.0
TI	%	12.7	12.4	9.5	11.0
Wind model	-	NTM	NTM	NTM	NTM (EWM)
Power law coeff.	-	0.14	0.14	0.14	0.11
H_s	m	2.3	2.5	3.6	10.9
T_p	s	9.7	9.8	9.9	16.0
Wave spectrum	-	PM	PM	PM	PM

Verification: Sensitivity study

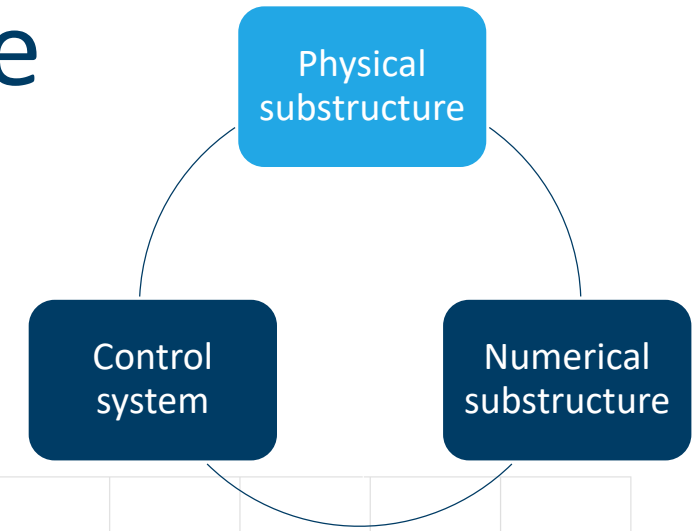
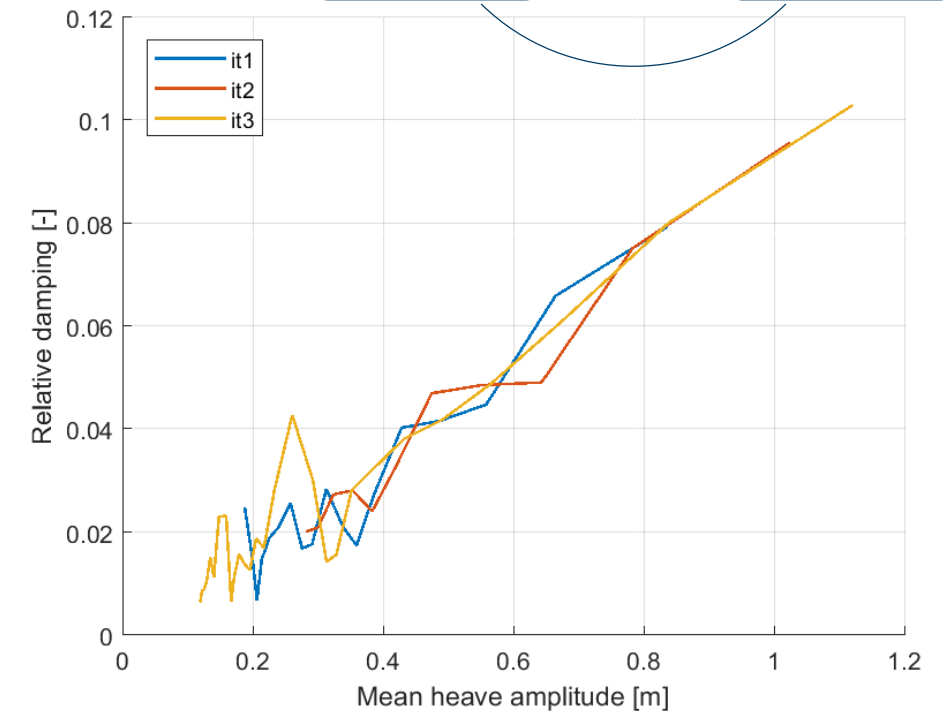
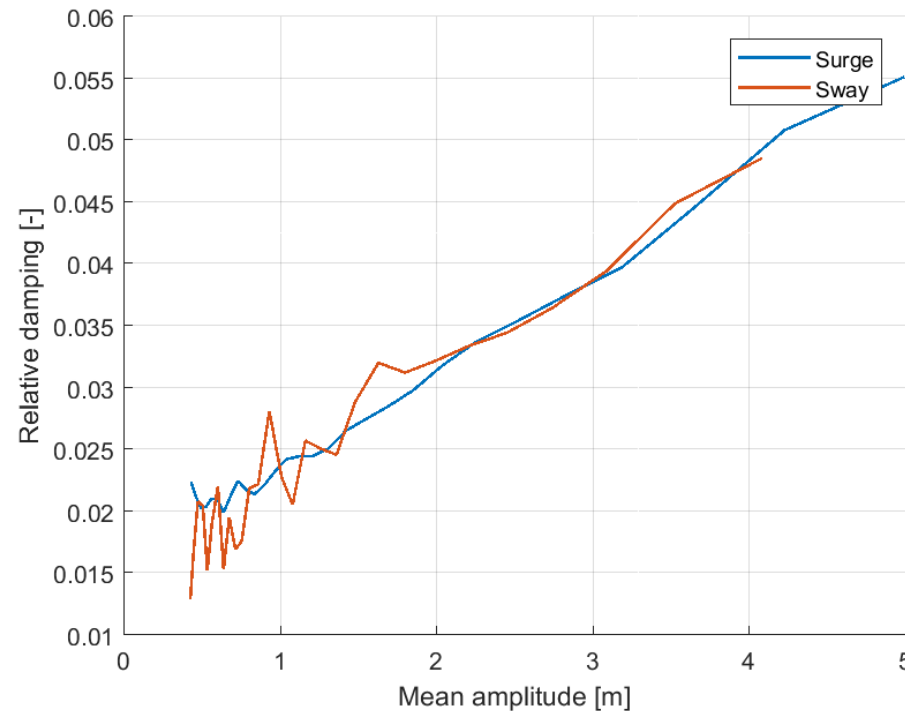
- Influence on standard deviation for quantities of interest (DOF1-6, mooring line tensions, BM and SF)

Removed	Operating (EC1-3)	Parked (EC4)
Aerodynamic sway	small	15% tension and 8% yaw and pitch
Aerodynamic heave	small	12% tension
Aerodynamic pitch	+18% pitch and +10% SF	+22% pitch and +22% BM
Aerodynamic yaw	-85% on yaw (small)	small
Vertical directionality	small	7% pitch and 15% tension

11 => 6 actuators in two parallel horizontal planes to apply all loads except heave

Verification of Physical Substructure

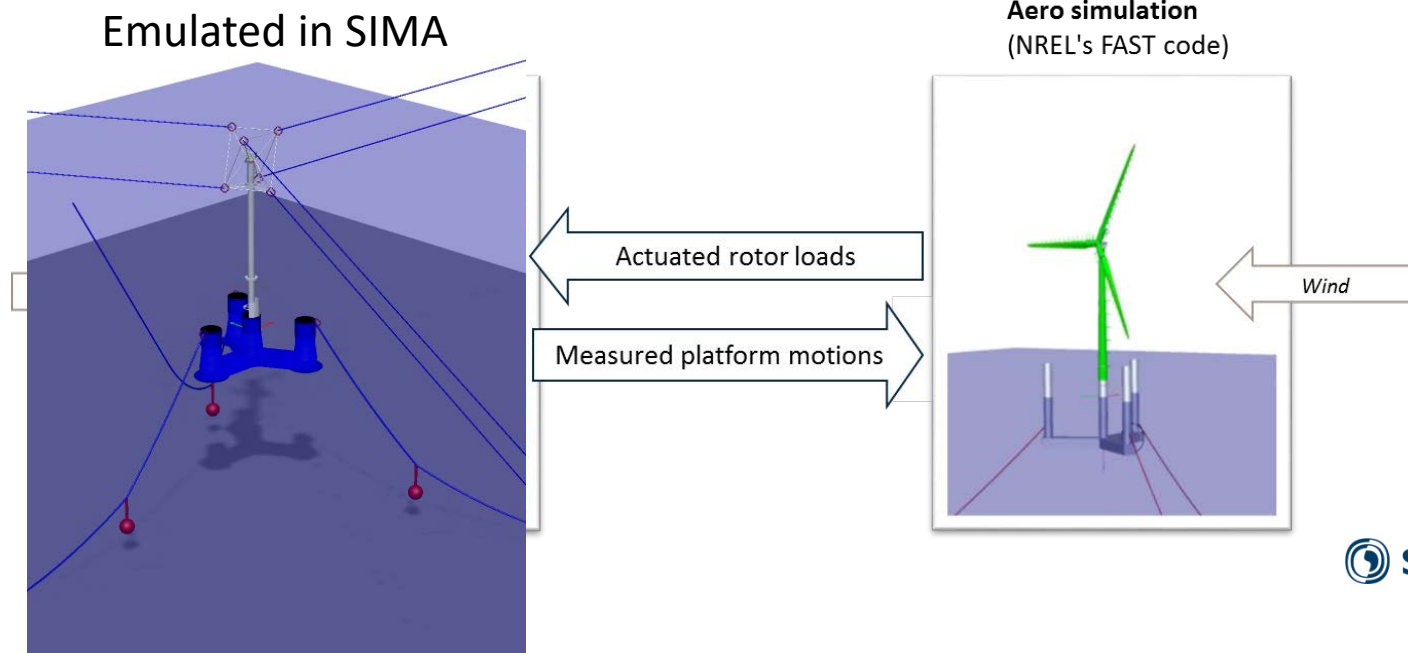
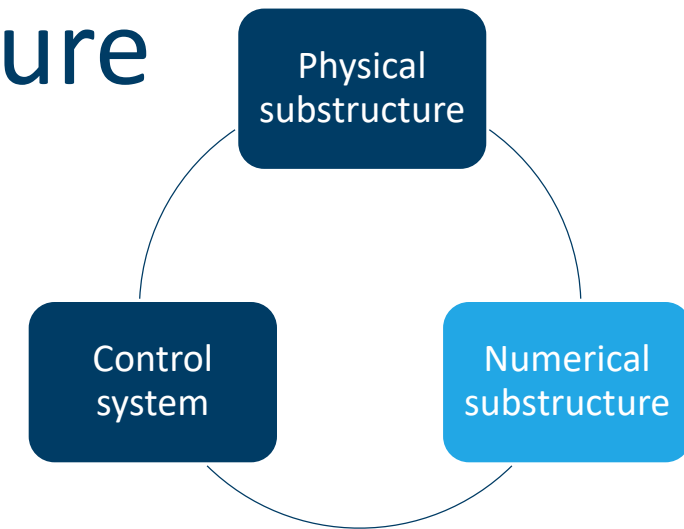
- Pullout
- Decay
- Repetitions



Verification of Numerical Substructure

Physical part of the experiments emulated in SIMA for verification of

- Allocation (rotor loads->forces on actuators 1-6)
- Scaling
- Applied actuators forces



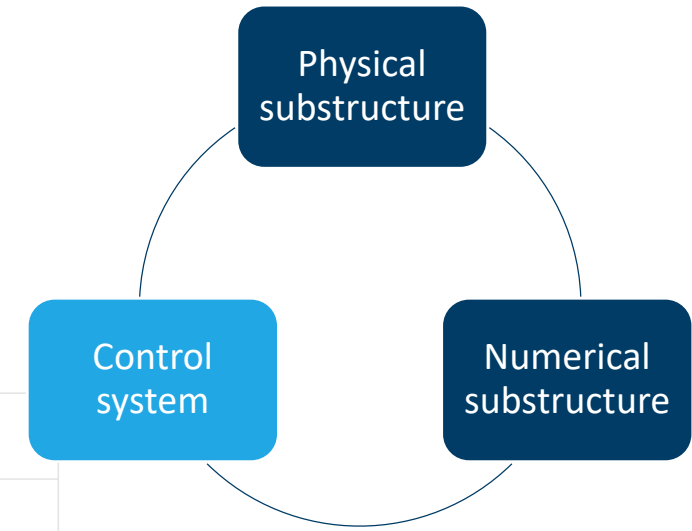
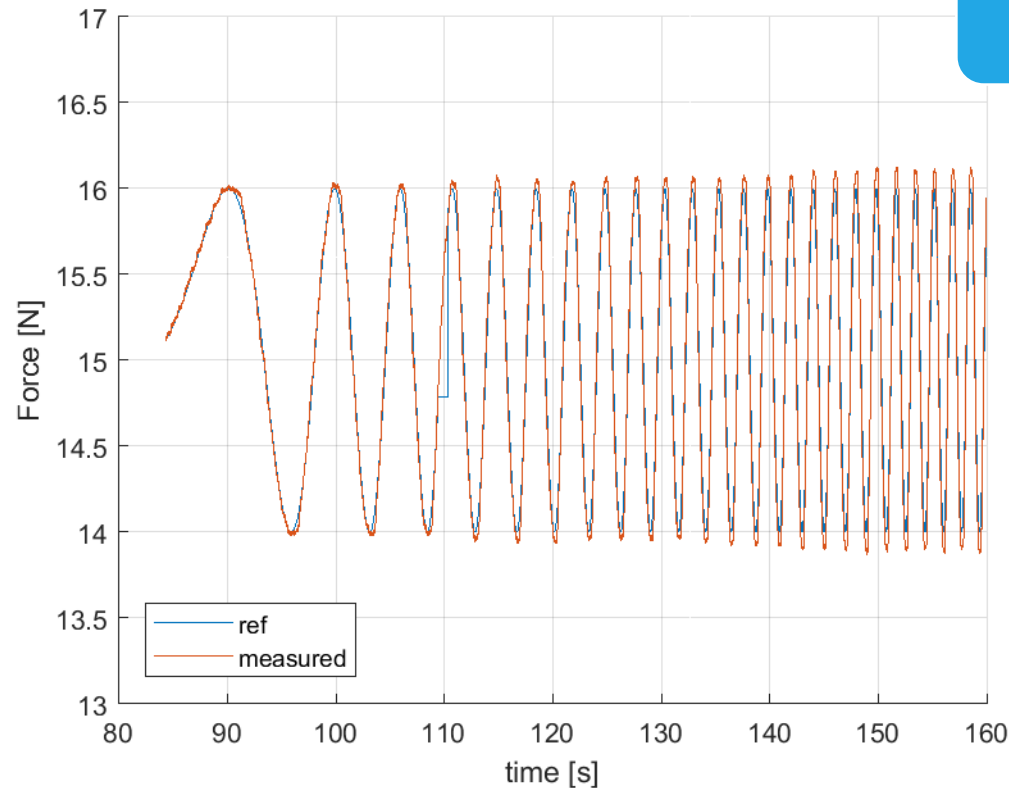
Verification of Control System

Main objectives:

- Reference tracking
- Disturbance rejection

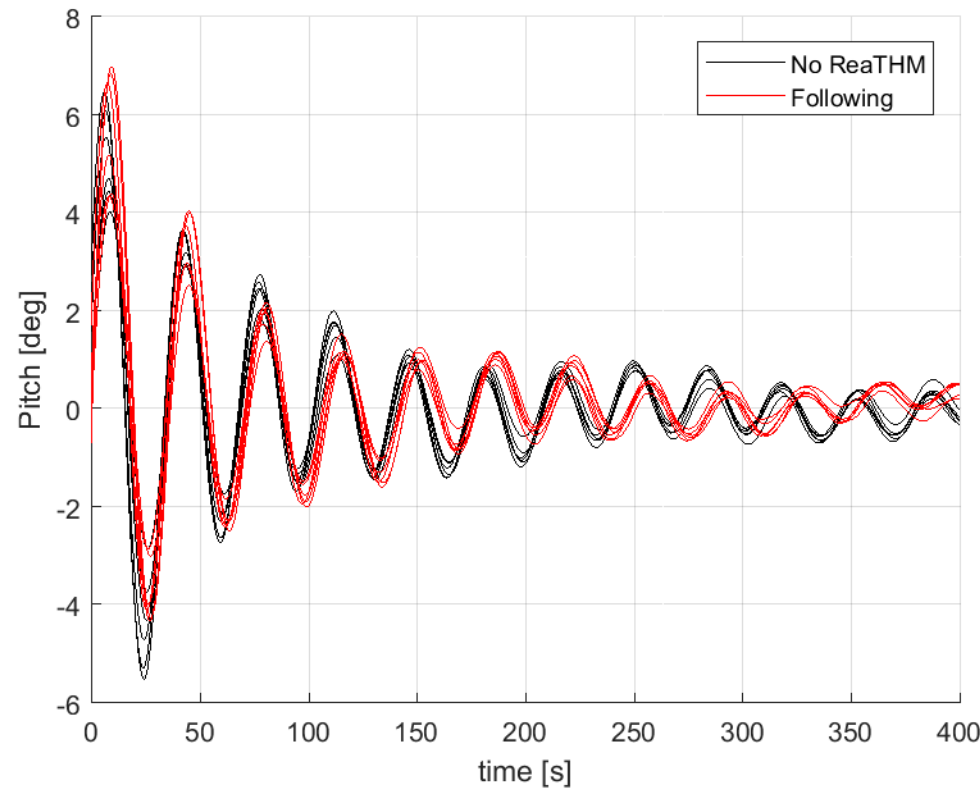
Through:

- Chirp tests
- Following tests



Verification of Complete System: Decay

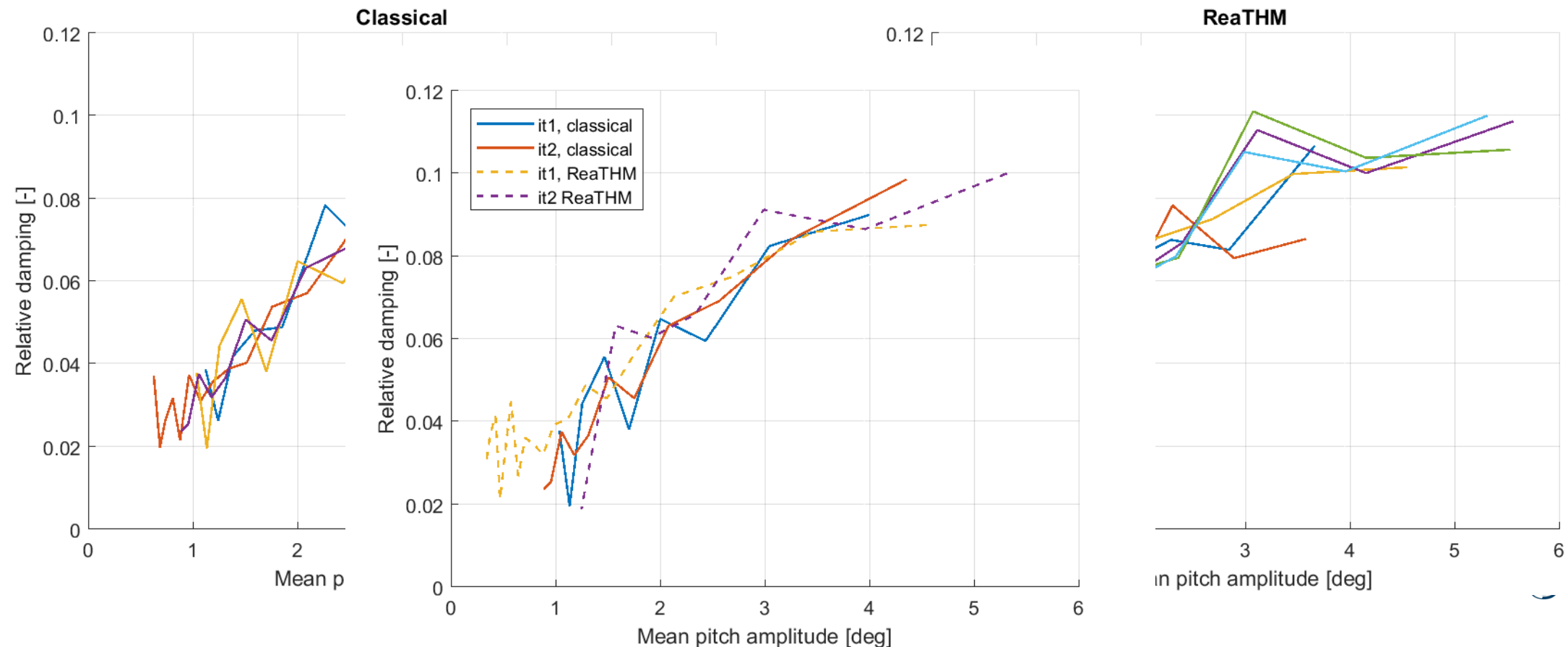
Pitch decay test without ReaTHM system and with the system in following mode



	Tn Pitch [s]
No ReaTHM	34.9
Following	35.8
Rel. Diff [%]	2.5

Verification of Complete System: Decay

Pitch decay test without ReaTHM system and with the system in following mode

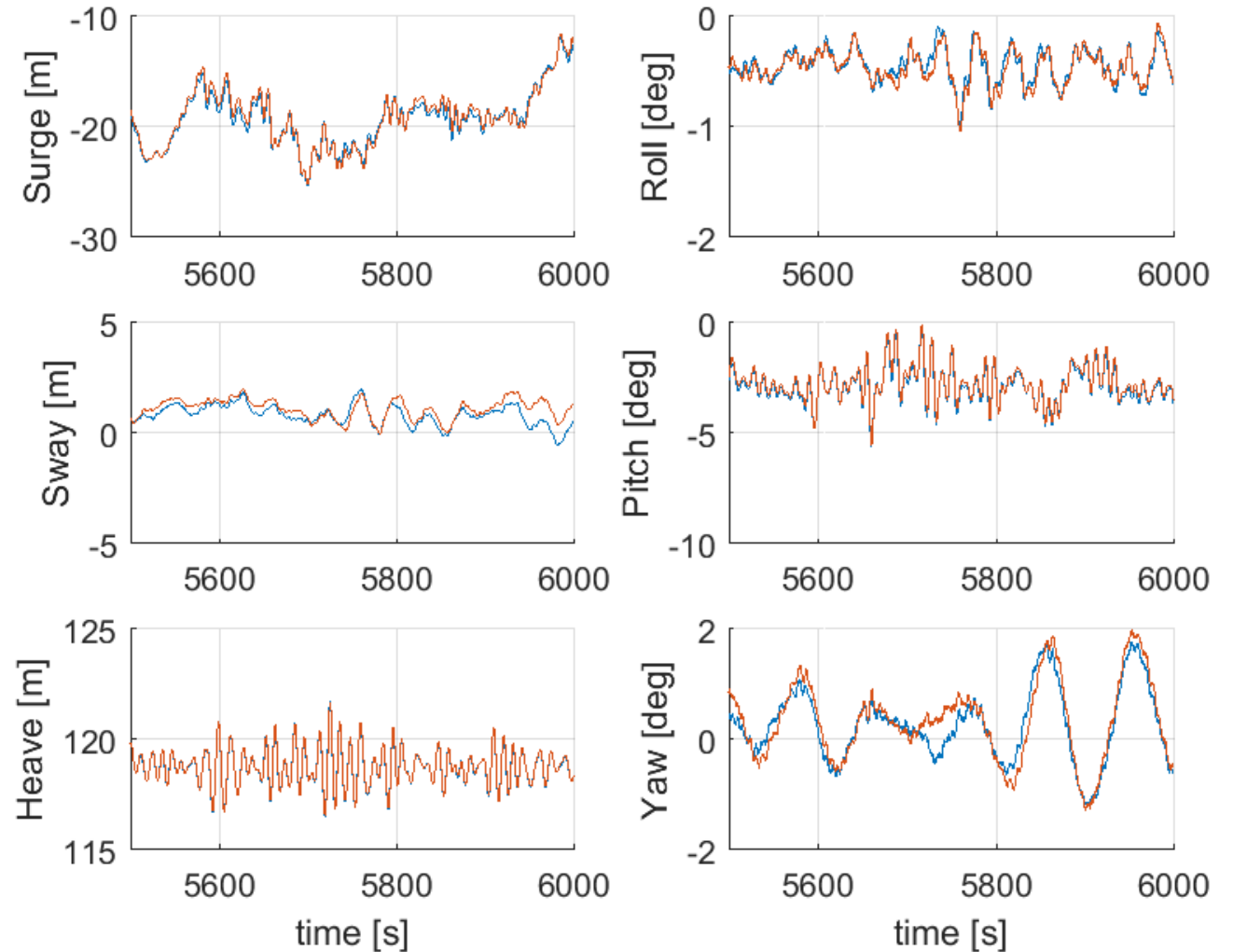
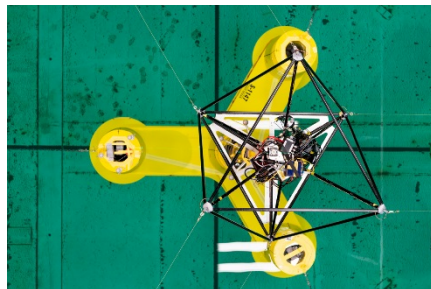


Verification of Complete System: Repetition

Test repetition:

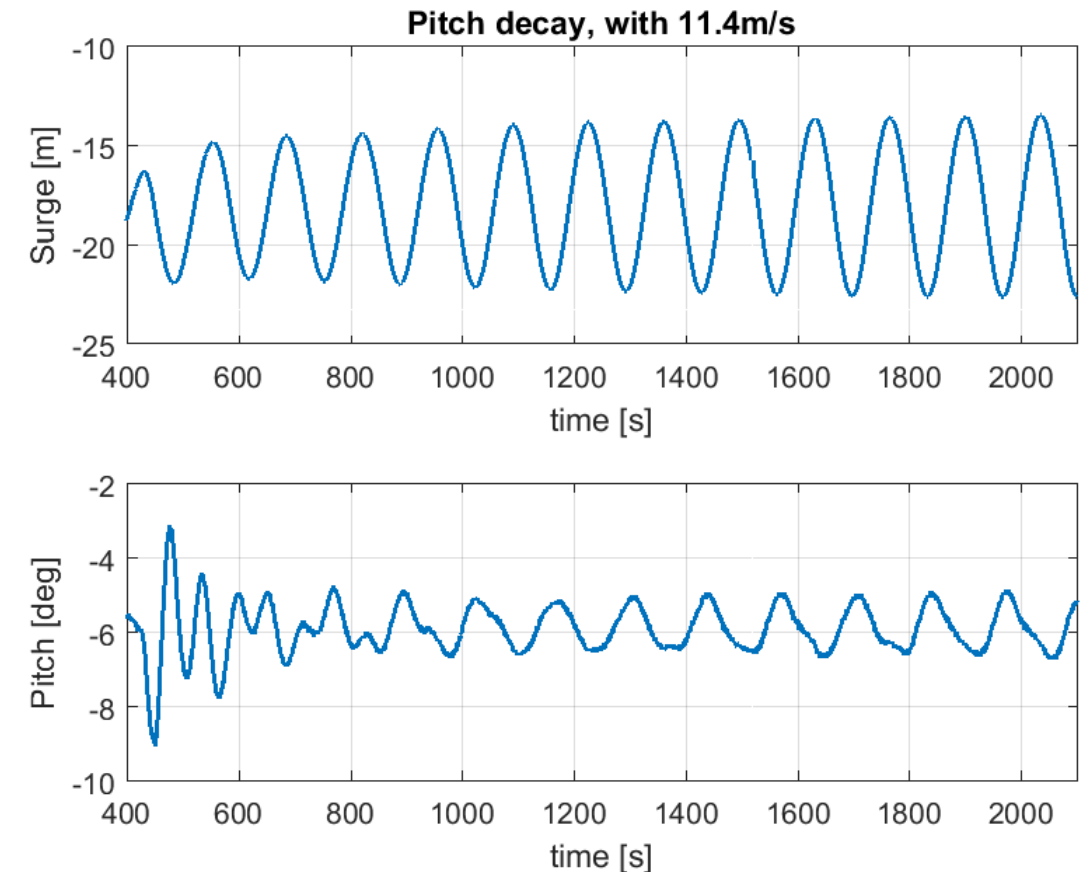
- DLC 1.6
- Waves: Pierson-Moskowitz
Hs=7.7m and Tp=12.4s
- Wind: NTM 8m/s

Collinear wind
and waves



Conclusions

- ReaTHM® testing is a multidisciplinary method
- Sensitivity analysis is key in the design process
- New verification and documentation methods developed for substructures and complete system
- Examples shown from Lifes50+ with OO-Star Wind Floater
- More work needed to address experimental uncertainty of hybrid tests -> Phase 2 of Lifes50+ in March 2018
(*Nautilus-DTU10*)



Acknowledgments



The research leading to these results has received funding from the European Union Horizon2020 programme under the agreement H2020-LCE-2014-1-640741



"The present work was part of the "HYBRID KPN" project supported by the Maritime Activities and Offshore Operations Program" (MAROFF) of the Research Council of Norway (grant No. 254845/O80).



Also, we are grateful to Dr. techn. Olav Olsen AS for the permission and contribution to set up the public 10MW semi-submersible design based on their concept of the OO-Star Wind Floater (www.olavolsen.no).



Teknologi for et bedre samfunn