

# Modelling of non-neutral wind profiles - current recommendations vs. coastal wind climate measurements

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## Introduction

- Wind velocity at the hub height is a parameter of paramount importance for wind engineering.
- Wind velocity is very often extrapolated from other heights (measured or modeled) - an „old” question: what is the vertical wind profile?
- Logarithmic and power laws are valid only in neutral conditions.
- For non-neutral conditions – Monin Obukhov similarity theory (MOST) is a recommended practice [1,2].

## Problem/Objective

- **How do MOST based vertical wind profile models perform?**
- **The test** – knowing the  $v_{z=10m}$ , humidity, pressure and temperature gradient extrapolate the velocity to  $v_{z=100m}$  and compare it with measured velocity.
- **The place** – mid-Norway coast, the Frøya island.

## Models tested

Stability corrected logarithmic model:

$$u(z) = \frac{u_*}{\kappa} \left( \ln \frac{z}{z_0} - \Psi(\zeta) \right) \quad \begin{matrix} z/L \geq 0 & \Psi(\zeta) = -4.8(z/L) \\ z/L < 0 & \left\{ \begin{array}{l} \Psi(\zeta) = 2 \ln(1+x) + \ln(1+x^2) - 2 \arctan(x) \\ x = [1 - 19.3(z/L)]^{0.25} \end{array} \right. \end{matrix}$$

Panofsky&Dutton model:

$$\alpha(\bar{z}/L) = \frac{\Phi(\bar{z}/L)}{\ln(\bar{z}/z_0) - \Psi(\bar{z}/L)} \quad \begin{matrix} \bar{z}/L \approx 0 & \Phi(\bar{z}/L) = 1; \Psi(\bar{z}/L) = 0 \\ \bar{z}/L > 0 & \Phi(\bar{z}/L) = 1 + 4.7(\bar{z}/L); \Psi(\bar{z}/L) = -4.7(\bar{z}/L) \\ \bar{z}/L < 0 & \left\{ \begin{array}{l} \Phi(\bar{z}/L) = [1 - 15(\bar{z}/L)]^{-0.25} \\ \Psi(\bar{z}/L) = -\ln \left[ \frac{(\bar{z}/L)^2 + (\bar{z}/L)^4}{(\bar{z}/L)^2 + (\bar{z}/L)^4} \right] - 2[\arctan(\zeta) - \arctan(\zeta_0)] \\ \zeta = [1 - 15(\bar{z}/L)]^{0.25}; \zeta_0 = [1 - 15(z_0/L)]^{0.25} \end{array} \right. \end{matrix}$$

Peña boundary layer height corrected model:

$$u(z) = \frac{u_*}{\kappa} \left[ \ln \left( \frac{z}{z_0} \right) - \Psi(\zeta) \left( 1 - \frac{z}{2z_{sl}} \right) \right] \quad z_{sl} = 0.1 \cdot 0.25 \frac{u_*}{f_c} \quad u_* = \sqrt{\left( \frac{\kappa^2}{\ln \frac{z}{z_0}} \right)^2 \cdot u_{z=10m}}$$

Smedman&Högström model:

$$\alpha = c_0 + c_1 \log(z_0) + c_2 [\log(z_0)]^2$$

Stability class	$c_0$	$c_1$	$c_2$
Very Unstable/Unstable	0.18	0.13	
Neutral	0.3	0.17	0.03
Weakly Stable	0.52	0.2	
Stable	0.8	0.25	
Very Stable	1.03	0.31	

## Site, equipment & data description

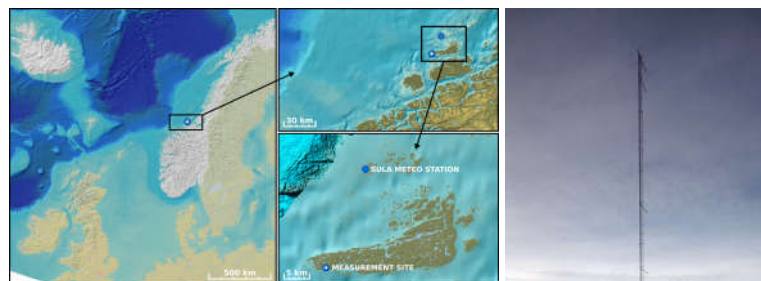


Fig. 1. Measurement station location

- 100 m high Met-mast.
- Velocity (Gill Wind Observer IID) & temperature measurements at: 10, 16, 25, 40, 70 and 100 m.
- Pressure & humidity from nearby Sula meteostation.
- Data acquisition time: Nov 2009- Dec 2012.
- Approx. 160000 of 10 min samples for each height.



Fig. 2. Met mast

## Atmospheric stability

For atmospheric stability calculations we used the bulk Richardson number as a basis for Obukhov length calculation:

$$Ri = \frac{g}{\theta_v} \frac{\Delta \bar{\theta}_v z_m}{(\Delta u)^2} \ln \left( \frac{z_1}{z_2} \right) \quad L = \begin{cases} \frac{z_m}{Ri}, & Ri < 0 \\ \frac{z_m}{Ri} (1 - 5Ri), & 0 \leq Ri \leq 0 \end{cases}$$

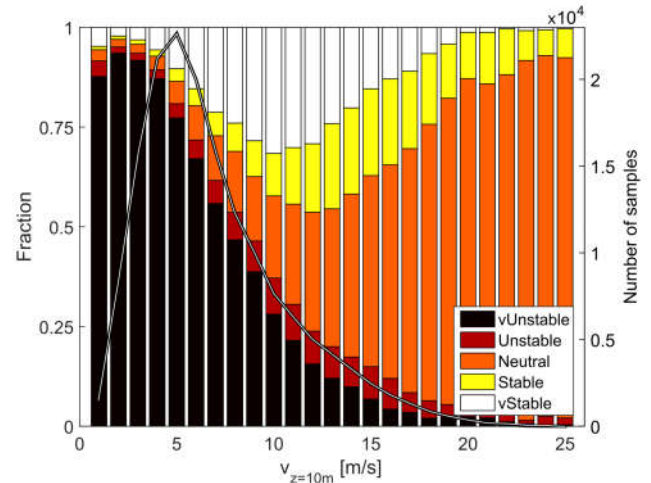


Fig. 3. Atmospheric stability distribution.

## Results

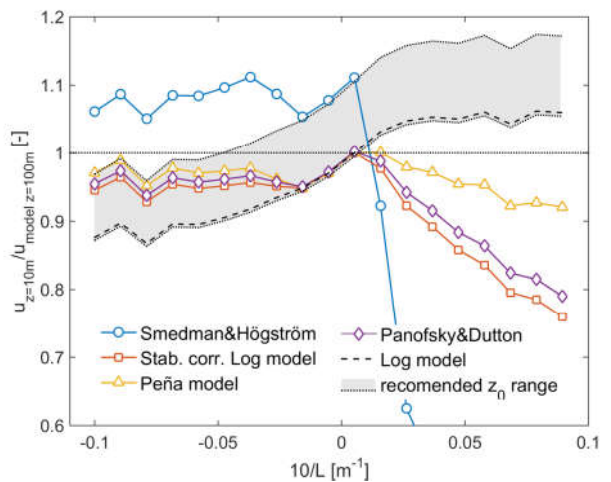


Fig. 4. Wind speed ratio between the measured and predicted wind velocity at  $z_2=100m$  against atmospheric stability.

## Conclusions

- 5 % underestimation of predicted wind velocity is observed during unstable conditions.
- The deviation grows dramatically up to 20 % (!) in stable atmosphere.
- Given the frequency/number of non-neutral observations that can result in serious error in wind prediction and finally in wind resources estimation.
- Although the problem of is not new, a lot of space for improvement is visible and desired.

## References

- [1] DNV, G. (2014). DNV-RP-C205: Environmental conditions and environmental loads. DNV GL, Oslo, Norway.
- [2] Fisher, et al., (1998). COST-710-final report: harmonisation of the pre-processing of meteorological data for atmospheric dispersion models.