

# 3D Beam element for FSI-simulation of flow around turbine blades

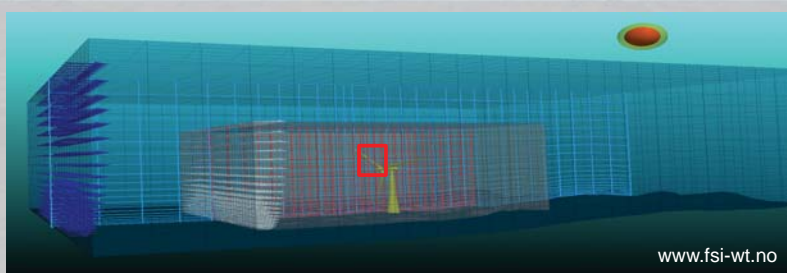
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## INTRODUCTION

We present here a nonlinear 3D beam formulation applicable for fluid-structure interaction (FSI) of wind turbine blades. The nonlinear 3D beam formulation is derived from a 3D continuum, where large-deformation kinematics and the St. Venant-Kirchhoff constitutive law are assumed. The initial configuration may be curved and twisted. The beam is intended for two different FSI-approaches:

- Semi 3D:** The strip theory approach using 2D CFD
- Full 3D:** Here the fluid flow is computed using 3D CFD



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## 3D BEAM GEOMETRY

The NREL 5MW blade is defined as a series of cross-section airfoils at various points along the blade axis. Corresponding cross-sectional beam stiffness data are given and can be used directly. Alternatively we may make a full 3D model of the blade and compute the cross sectional stiffness data by integration. The nonlinear 3D beam handles non-symmetric cross-sections – which is common for turbine blades.



Figure 1: 3D turbine blade geometry may be generated by lofting the given cross-sections

## HILBER-HUGHES-TAYLOR $\alpha$ -METHOD

Numerical damping is crucial to avoid unphysical oscillations in computed results. The Hilber-Hughes-Taylor (HHT)  $\alpha$ -Method is the most popular time integration scheme for nonlinear beams, where the numerical damping is controlled by the value of  $\alpha$ .

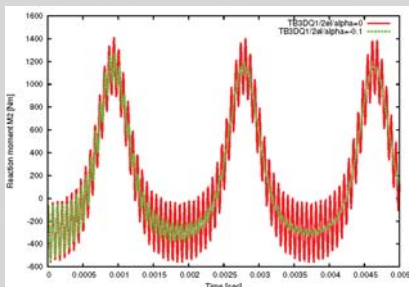


Figure 1: The computed reaction moment with and without numerical damping.

## CONCLUSION

**IFEM Beam** is a versatile nonlinear 3D beam element applicable for FSI-simulations of offshore wind turbines.

## NONLINEAR 3D BEAM FORMULATION

The nonlinear 3D beam formulation is derived from a 3D continuum, where large-deformation kinematics (Green-Lagrange strain tensor and second Piola-Kirchhoff stress tensor) and the St. Venant-Kirchhoff constitutive law are assumed.

- We may use Lagrange polynomials or Splines.
- The local element kinematics are based on both Timoshenko and Bernoulli assumptions, considering both low-order and higher-order terms in second-order approximations of the Green-Lagrange strains.
- Account for membrane, bending, transverse shear and torsional effects.
- Linearly varying cross section along the beam axis that may be non-symmetric.
- Consistent inertia and dynamic tangent stiffness are derived that allows for arbitrarily large motions and achieve second order convergence in the Newton iterations.

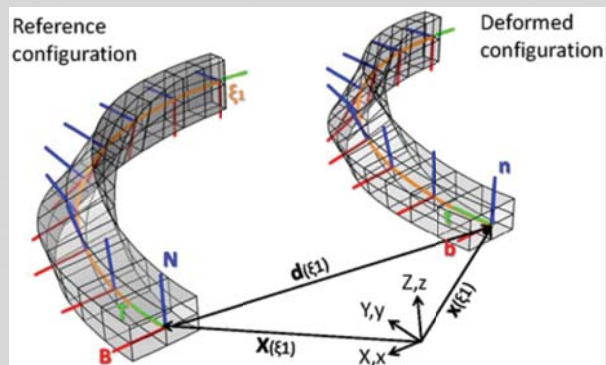


Figure 2: The beam element in the reference (left) and deformed (right) configuration, showing the local coordinate system. Six DOFs per node.

## VERIFICATION EXAMPLE

To verify the implemented nonlinear 3D beam formulation in IFEM we solved a double cantilever beam problem (point load at midpoint) and compared the computed displacement, velocity and acceleration with ABAQUS.

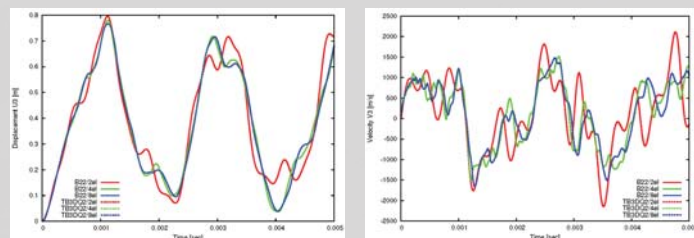


Figure 3: The tip displacement (left) and velocity (right) for  $p=2$ . The results from IFEM and ABAQUS coincides very well!

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