

# **UQ for high dimensional problems**

with a view towards hyperbolic conservation laws

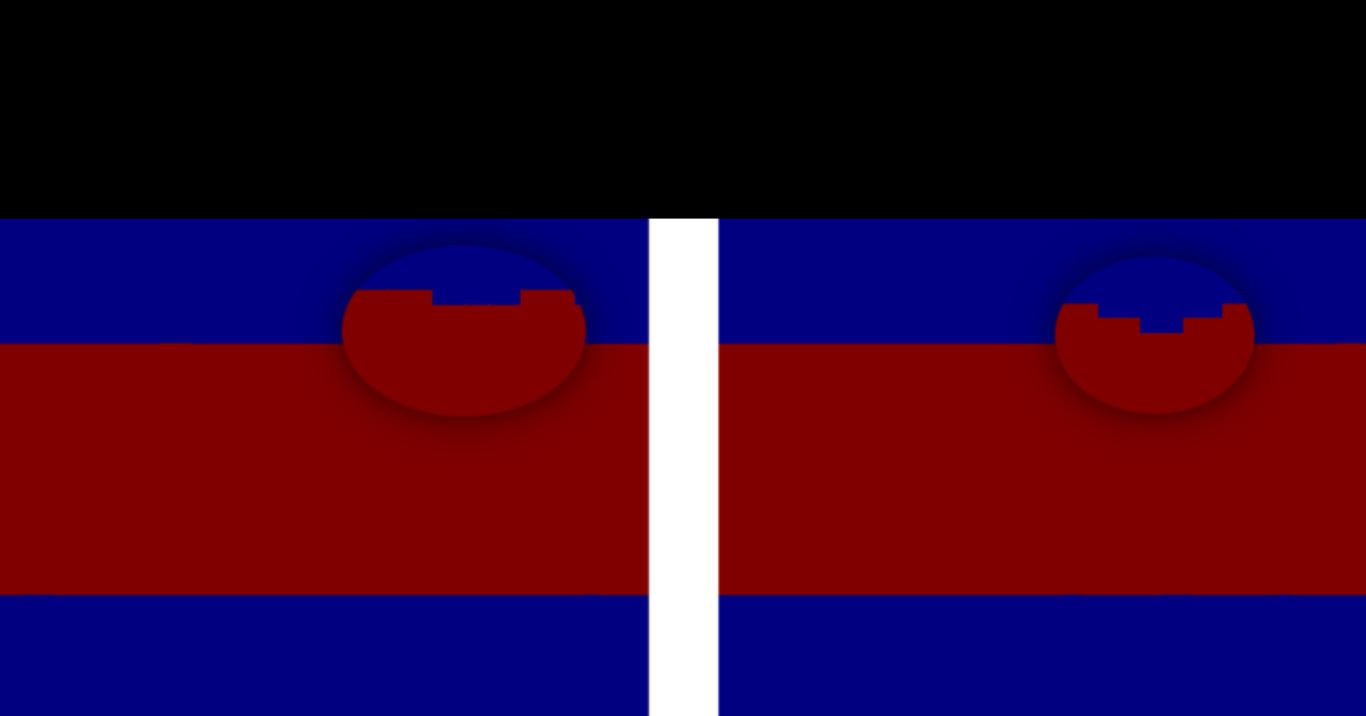
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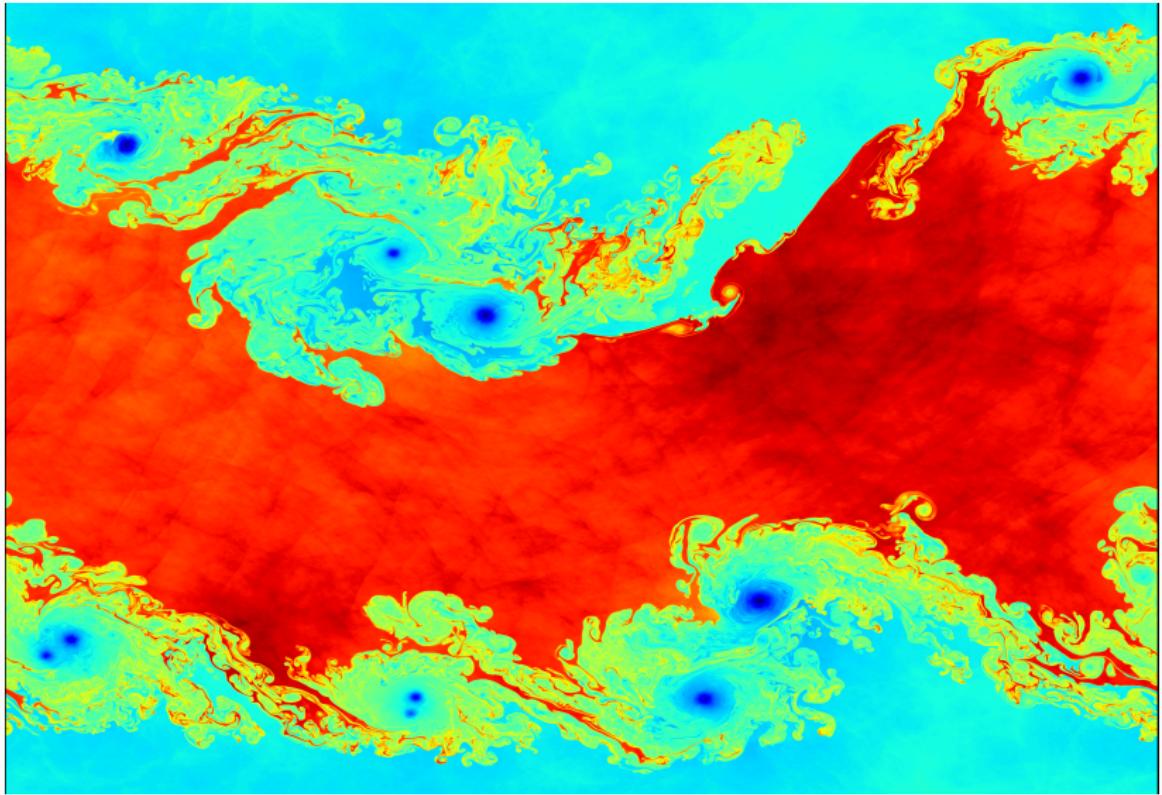
Kjetil Olsen Lye

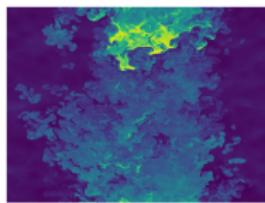
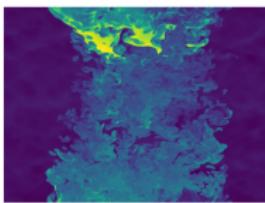
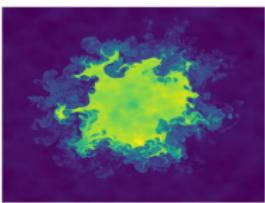
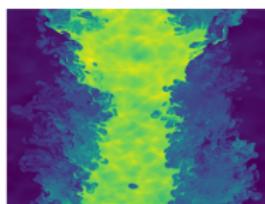
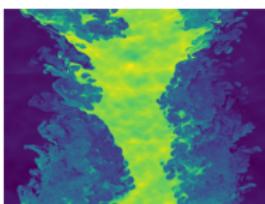
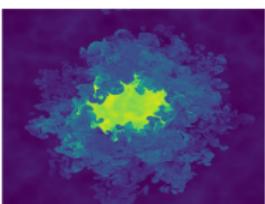
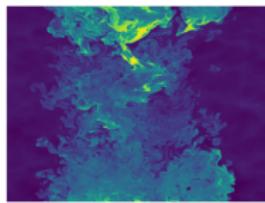
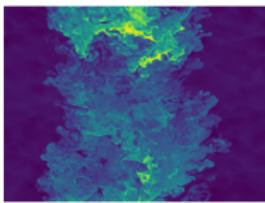
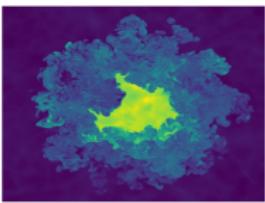
ETH Zurich

# About me

- PhD student at ETH Zürich
- Research interests:
  - Non-linear hyperbolic equations
  - Uncertainty quantifications
  - (Machine learning)

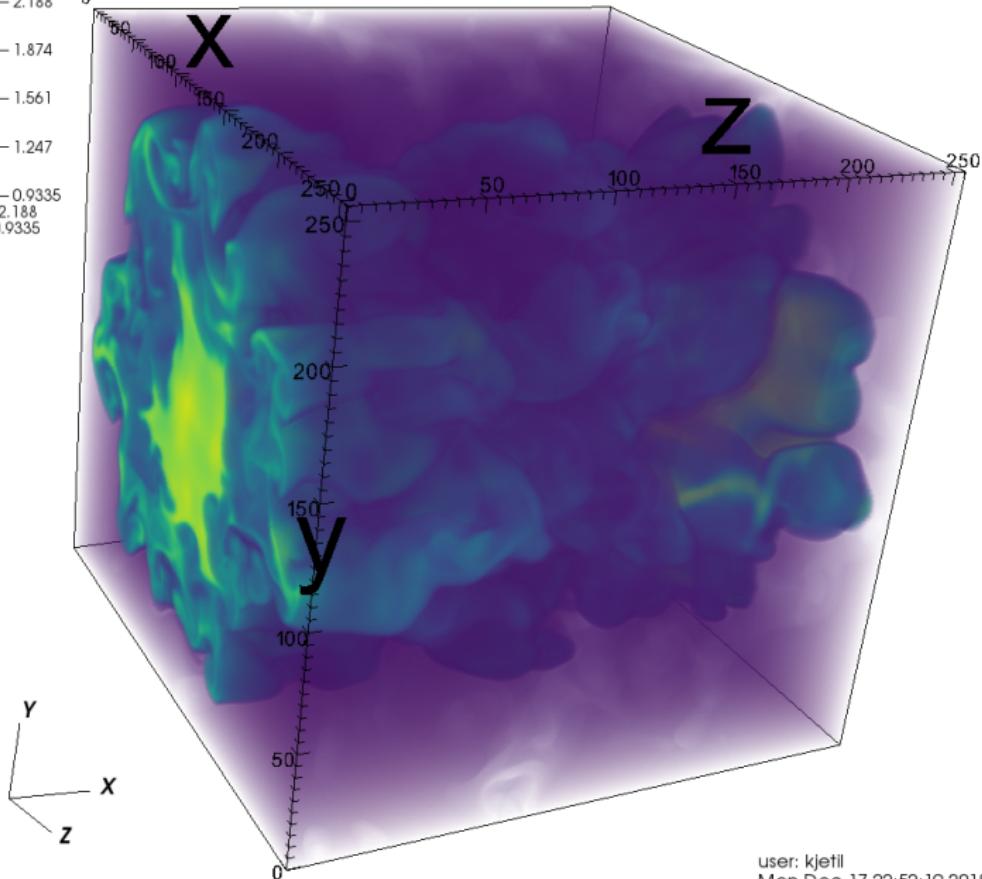
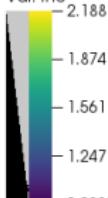






kh\_mean\_1.nc:Volume - rho

Var: rho  
Max: 2.188  
Min: 0.9335



user: kjetil  
Mon Dec 17 22:52:19 2018

# Introduction

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# Uncertainty quantifications

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- PDF, CDF, ...

# Focus of talk

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Compute

$$\int_{[0,1]^d} f(\mathbf{y}) \, d\mathbf{y}$$

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- $d$  is large
- $f$  could be ill-behaved (eg. discontinuous)

## Example



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$$p(h_0) = v_0 \cos(\alpha) \frac{v_0 \sin(\alpha) + \sqrt{(v_0 \sin(\alpha))^2 + 2gh_0}}{g} + x_0$$

## Interesting quantities

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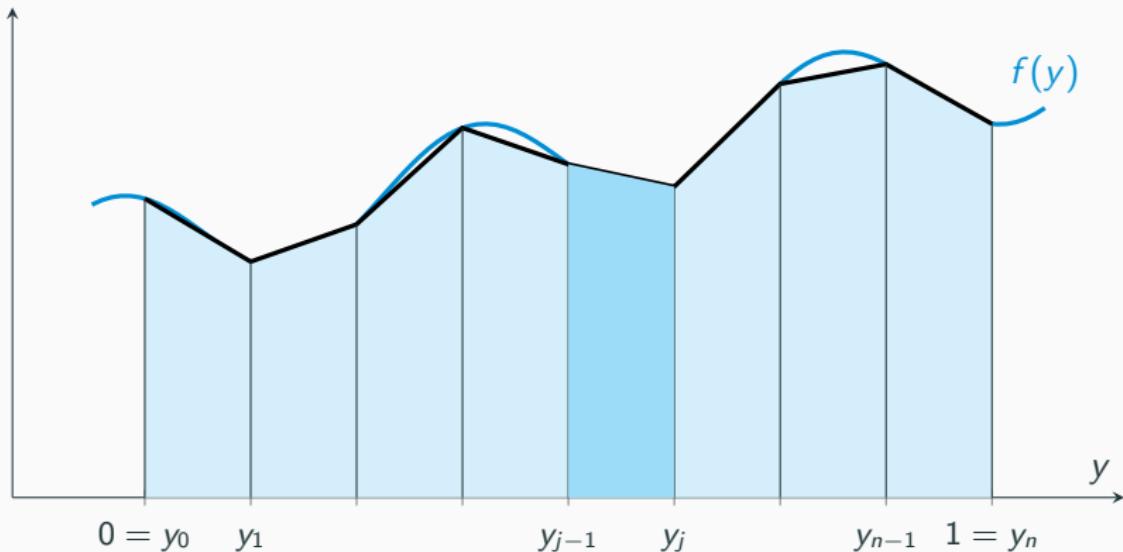
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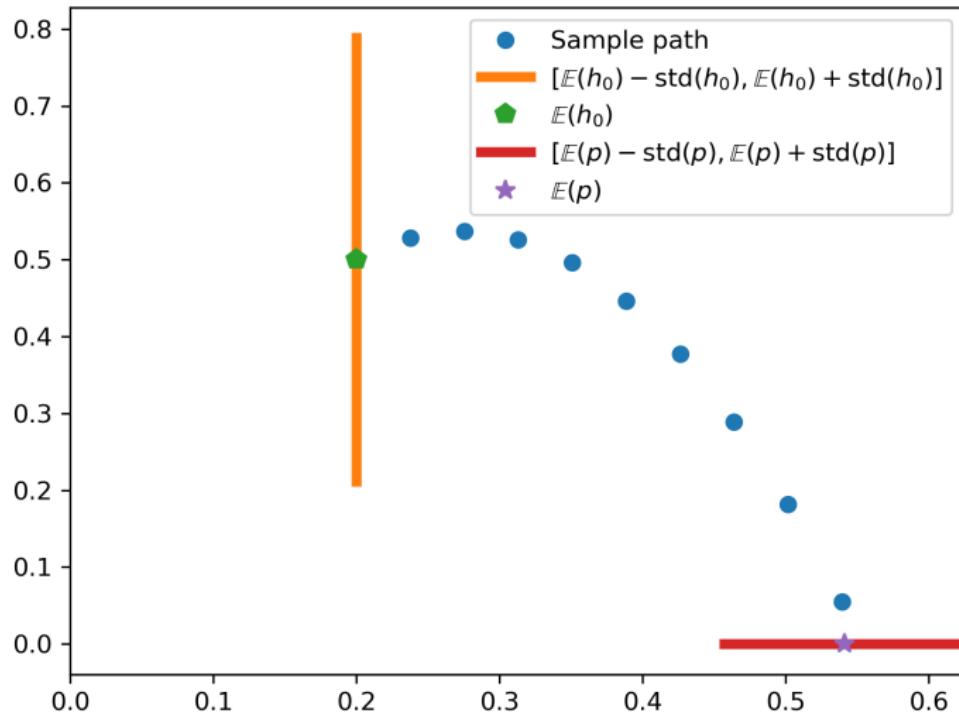
Both quantities involving the integral!

## Approximate by Trapezoidal rule

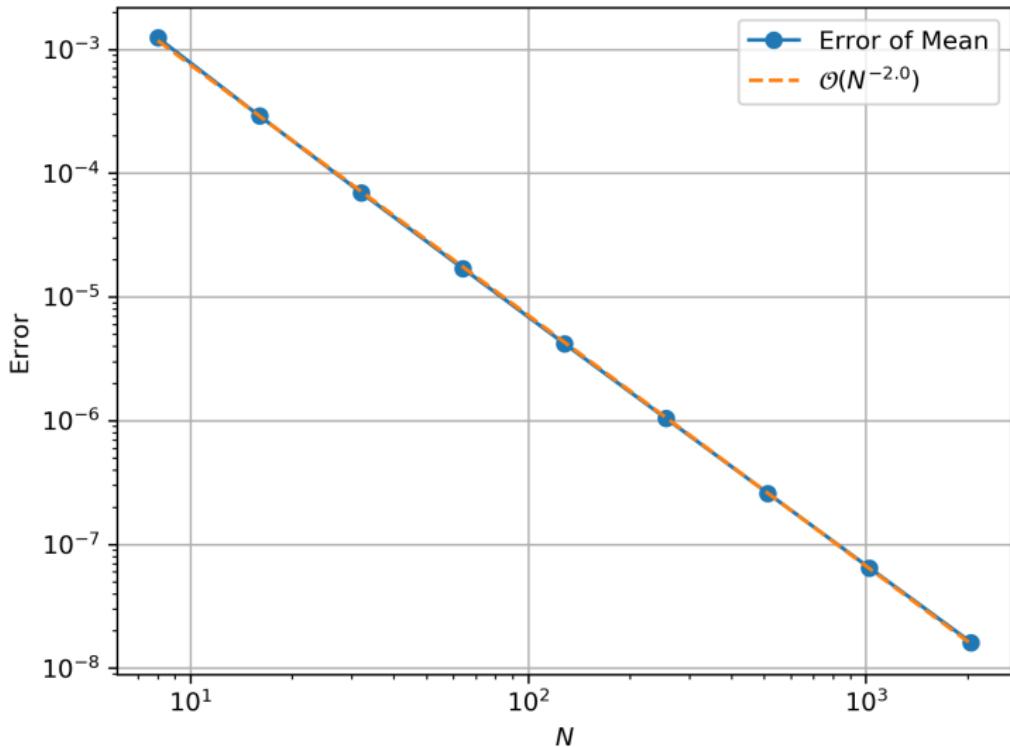
$$\int_0^1 f(y) dy \approx \frac{\Delta y}{2} \left( f(y_0) + 2 \sum_{i=1}^{N-1} f(y_{i-1}) + f(y_N) \right)$$



## Results varying initial height



## Error versus number of evaluations



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---

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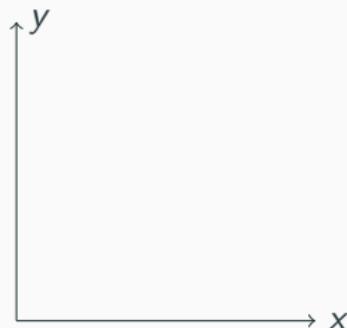
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- Integration in 2D?

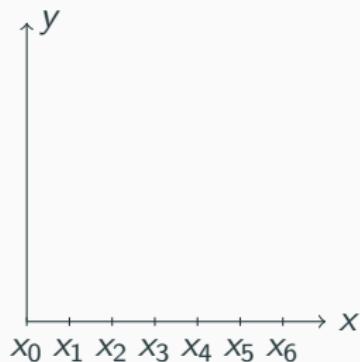
## Trapezoidal rule for two dimensions

$$\int_0^1 \int_0^1 f(x, y) \, dx \, dy$$



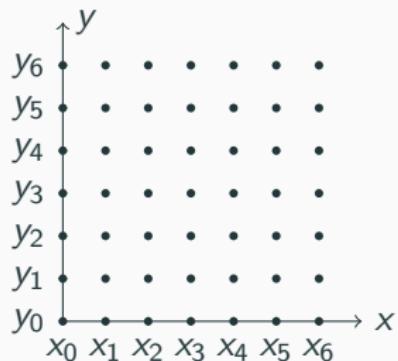
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$$\int_0^1 \int_0^1 f(x, y) dx dy \approx \int_0^1 \left( f(x_0, y) + 2 \sum_{i=1}^{N-1} f(x_i, y) + f(x_N, y) \right) \Delta x dy$$



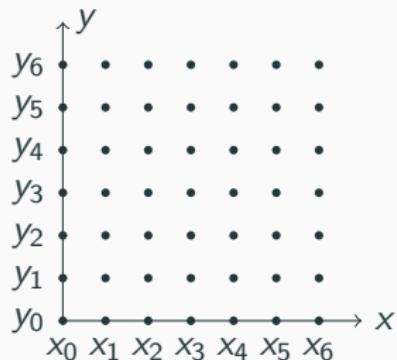
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$$\begin{aligned} \int_0^1 \int_0^1 f(x, y) dx dy &\approx \int_0^1 \left( f(x_0, y) + 2 \sum_{i=1}^{N-1} f(x_i, y) + f(x_N, y) \right) \Delta x dy \\ &\approx \left( f(0, 0) + f(1, 0) + f(0, 1) + f(1, 1) + 4 \sum_{i=1}^{N-1} \sum_{j=1}^{N-1} f(x_i, y_j) \right. \\ &\quad \left. + 2 \sum_{i=1}^{N-1} f(x_i, 0) + 2 \sum_{i=1}^{N-1} f(x_i, 1) + 2 \sum_{i=1}^{N-1} f(1, y_i) + 2 \sum_{i=1}^{N-1} f(0, y_i) \right) \end{aligned}$$

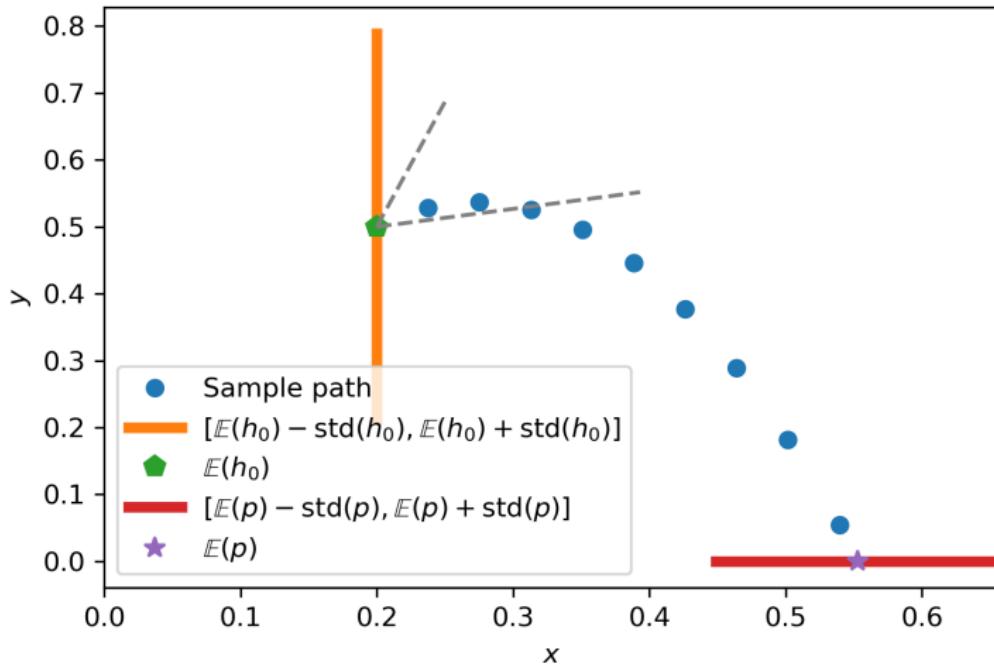


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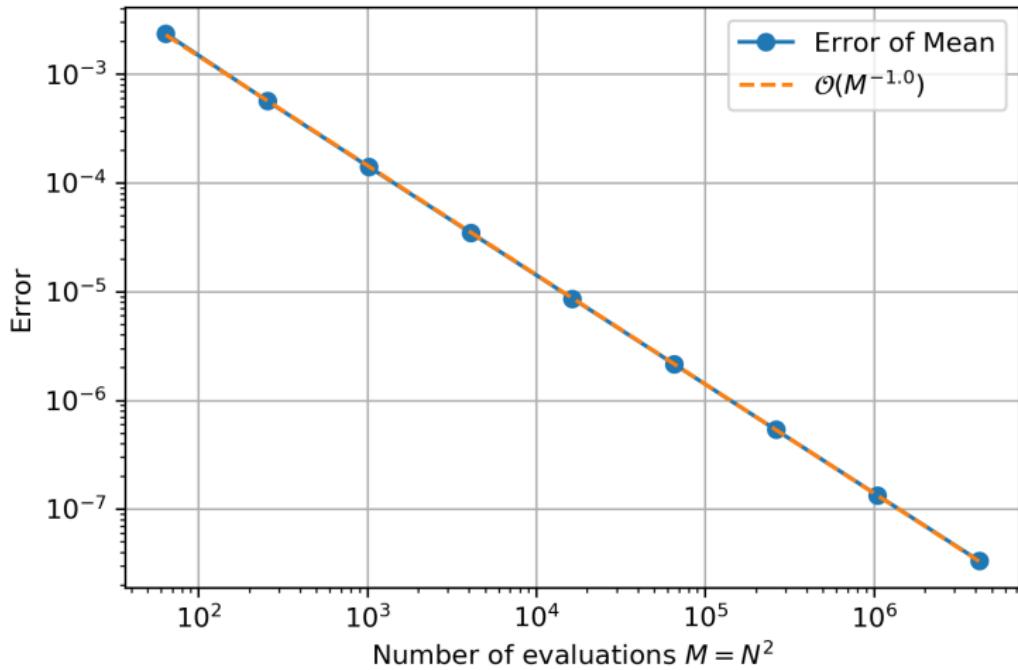
$$\int_0^1 \int_0^1 f(x, y) \, dx \, dy \approx \sum_{i=0}^N \sum_{j=0}^N w_{i,j} f(x_i, y_j)$$



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- **Seven parameters**

## Landing position depends on 7 parameters

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$$p(h_0, \alpha, v_0, C_D, r, \rho, m) \frac{dm dr dC_D dv_0 d\alpha dh_0}{20 \cdot 5\pi/12 \cdot 0.2 \cdot 0.015 \cdot 0.3 \cdot 0.07}$$

## How many evaluations of $p$ do we need?

- We have 7 parameters ( $d = 7$ )
- Trapezoidal rule error

$$\text{Error} \leq C h^2$$

Require Error  $< 1/25 \approx 4\%$

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- $\Rightarrow N^d = N^7 = 5^7 = 78125$  evaluations

## Finding $p$

---

Governing ODE

$$\begin{cases} \frac{d^2}{dt^2}\mathbf{x}(t) = -\mathbf{F}_D(C_D, r, \rho, \frac{d}{dt}\mathbf{x}(t))/m - g\mathbf{e}_2 \\ \mathbf{x}(0) = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} \\ \mathbf{x}'(0) = \begin{pmatrix} v_0 \cos(\alpha) \\ v_0 \sin(\alpha) \end{pmatrix} \end{cases}$$

## Finding $p$

$\mathbf{x}(t)$  depends on the parameters

$$\begin{cases} \frac{d^2}{dt^2} \mathbf{x}(\textcolor{brown}{h}_0, \alpha, v_0, C_D, r, \rho, m; t) = -\mathbf{F}_D(\textcolor{brown}{C}_D, r, \rho, \frac{d}{dt} \mathbf{x}(\dots; t))/m - g \mathbf{e}_2 \\ \mathbf{x}(\textcolor{brown}{h}_0, \alpha, v_0, C_D, r, \rho, m; 0) = \begin{pmatrix} 0 \\ y_0 \end{pmatrix} \\ \frac{d}{dt} \mathbf{x}(\textcolor{brown}{h}_0, \alpha, v_0, C_D, r, \rho, m; 0) = \begin{pmatrix} v_0 \cos(\alpha) \\ v_0 \sin(\alpha) \end{pmatrix} \end{cases}$$

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Assuming underlying probability space  $\Omega$

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for  $\omega \in \Omega$ .

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for  $\omega \in \Omega$ . Solve using eg. Forward-Euler:

$$\mathbf{x}^{n,\Delta t}(\omega) = \mathbf{x}^{n-1,\Delta t}(\omega) + \Delta t \mathbf{v}^{n-1,\Delta t}(\omega)$$

$$\mathbf{v}^{n,\Delta t}(\omega) = \mathbf{v}^{n-1,\Delta t}(\omega) + \Delta t (-\mathbf{F}_D(C_D(\omega), r(\omega), \rho(\omega), \mathbf{v}^{n-1,\Delta t})/m(\omega) - g\mathbf{e}_2)$$

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**Set**  $p^{\Delta t}(\omega) = y^{N,\Delta t}(\omega)$ .

## Algorithm: Compute expected position using Trapezoidal rule

Input:  $\Delta t, \Delta h_0, \Delta \alpha, \Delta v_0 \dots$

1. Initialize mean  $E = 0$
2. For each integration point  $h_0^i, \alpha^j, v_0^k, \dots$ :

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Then

$$E \approx \mathbb{E}(p)$$

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Runtime to obtain an error  $\epsilon$ :

- Forward Euler:  $\mathcal{O}(\epsilon^{-1})$
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- Total cost:

$$\overbrace{\mathcal{O}(\epsilon^{-1})}^{\text{Forward Euler}} \cdot \underbrace{\mathcal{O}(\epsilon^{-7/2})}_{\text{Trapezoidal}} = \mathcal{O}(\epsilon^{-4.5}).$$

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- $N = \mathcal{O}(\epsilon^{-1/k}) \Rightarrow M = \mathcal{O}(\epsilon^{-1})$

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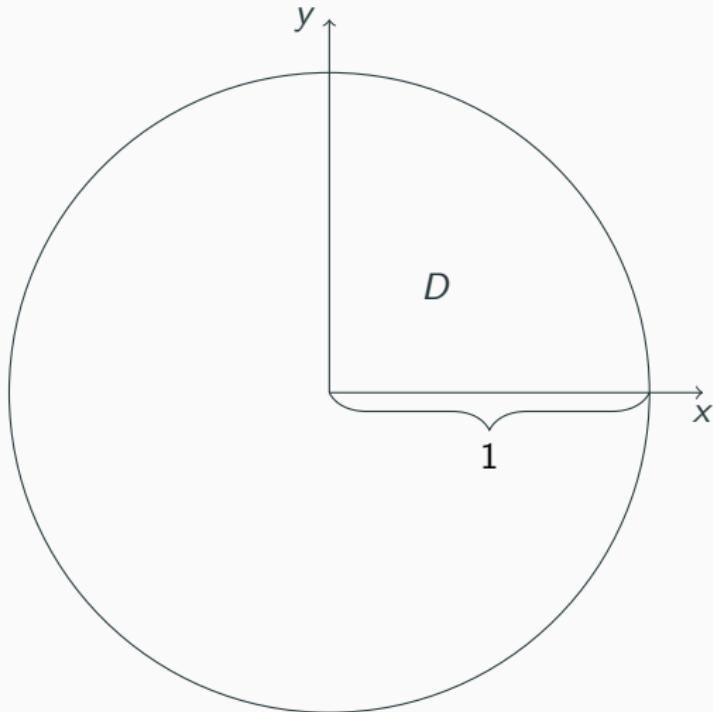
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## Monte Carlo methods

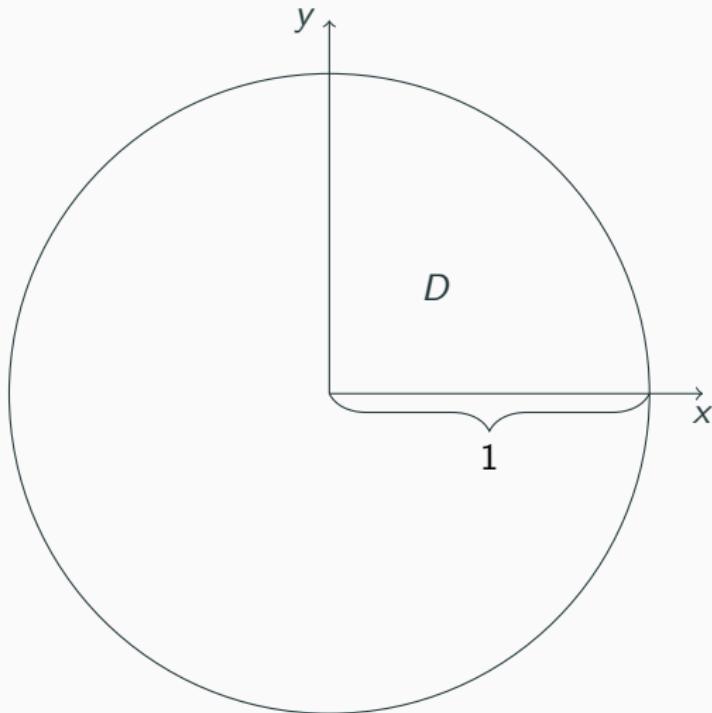
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## Obligatory example: Computing $\pi$



$$|D| = \frac{\pi}{4}$$

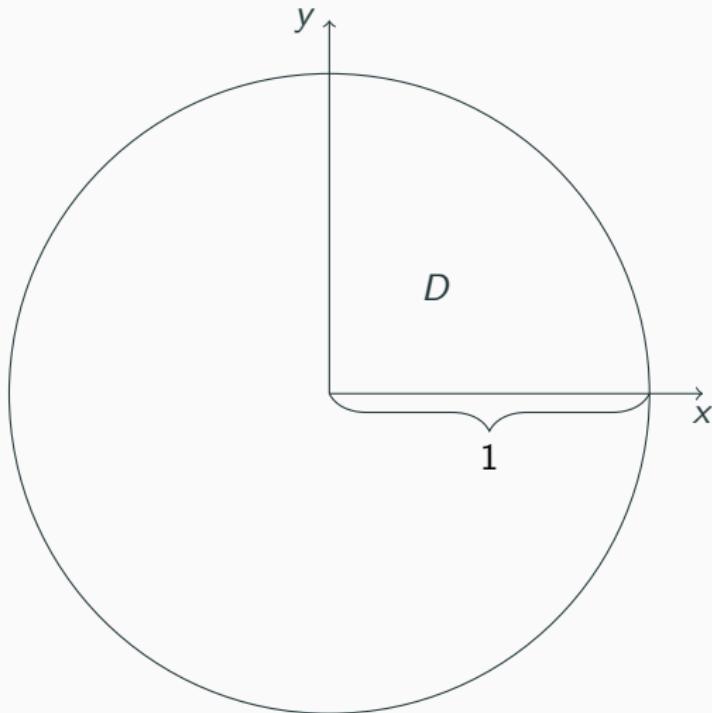
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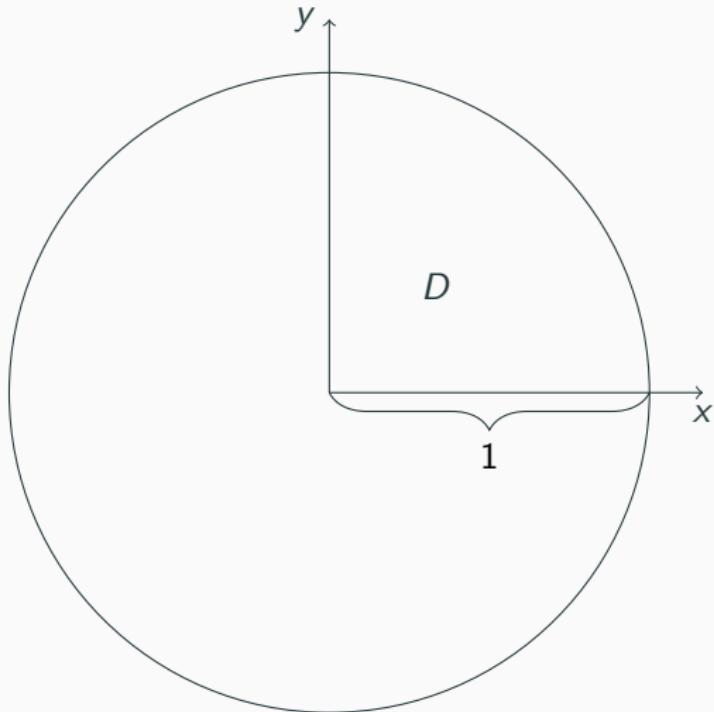


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$$\Rightarrow \pi = 4 \int_0^1 \int_0^1 \mathbf{1}_{B(0,1)}(x, y) \, dx \, dy$$

## Obligatory example: Computing $\pi$



$$|D| = \frac{\pi}{4}$$

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$$\begin{aligned}\Rightarrow \pi &= 4 \int_0^1 \int_0^1 \mathbf{1}_{B(0,1)}(x, y) dx dy \\ &\approx 4 \frac{1}{M} \sum_{k=1}^M \mathbf{1}_{B(0,1)}(X_k, Y_k)\end{aligned}$$

$X_k \sim \mathcal{U}[0, 1]$ ,  $Y_k \sim \mathcal{U}[0, 1]$   
independent random  
variables

# Convergence of Monte Carlo

---

$$\left( \frac{1}{M} \sum_{k=1}^M X_k - \mathbb{E}(X) \right)^2$$

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---

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## Monte Carlo error

---

In expectation we converge

$$\mathbb{E} \left( \left( \frac{1}{M} \sum_{k=1}^M X_k - \mathbb{E}(X) \right)^2 \right)^{1/2} = \frac{\text{Var}(X)^{1/2}}{M^{1/2}}$$

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---

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Then

$$E \approx \mathbb{E}(u(\cdot, T))$$

# Example

---

See notebook

# Conclusion

---

- Monte Carlo

$$\int_{\Omega} f(X(\omega)) \, d\mathbb{P}(\omega) \approx \frac{1}{M} \sum_{k=1}^M f(X_k(\omega))$$

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- ... but sometimes the best we have

## Multilevel Monte Carlo

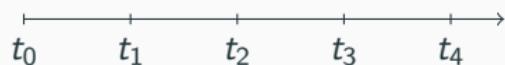
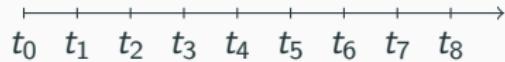
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## Multilevel telescoping sum

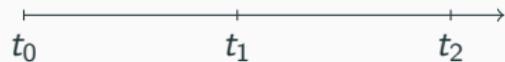
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Numerical approximation  $u^\Delta$

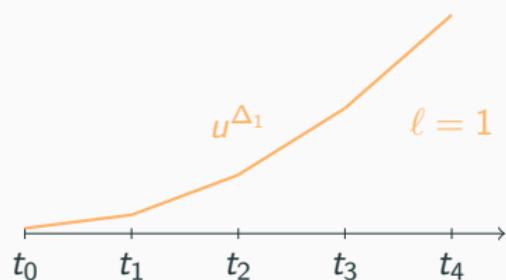
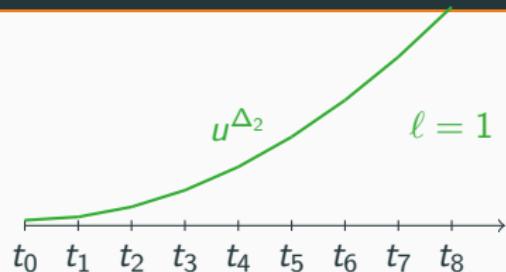
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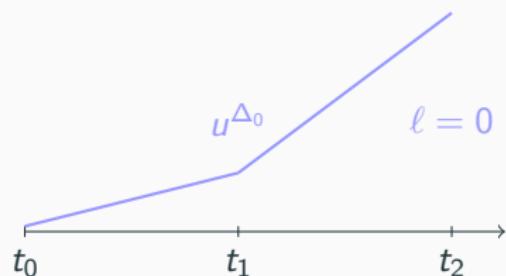
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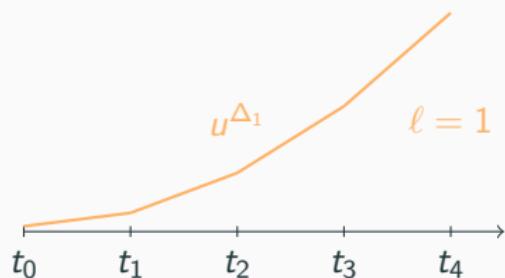
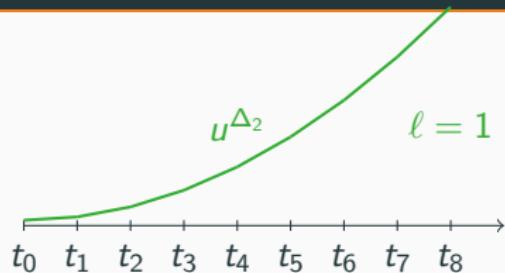
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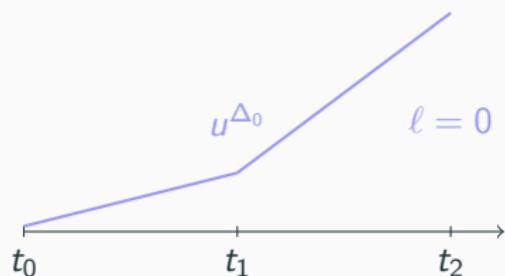


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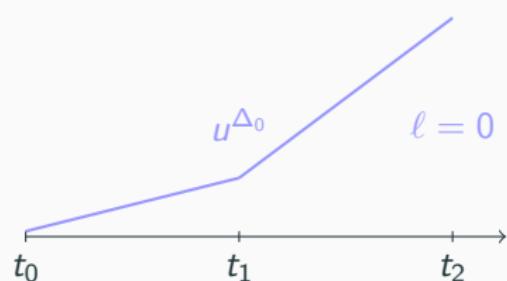
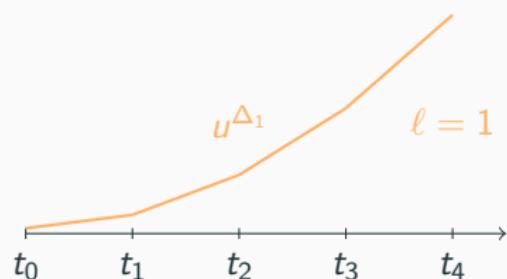
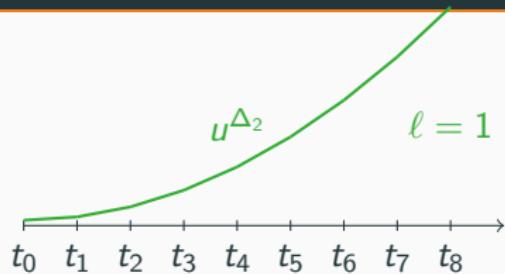


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## Multilevel telescoping sum



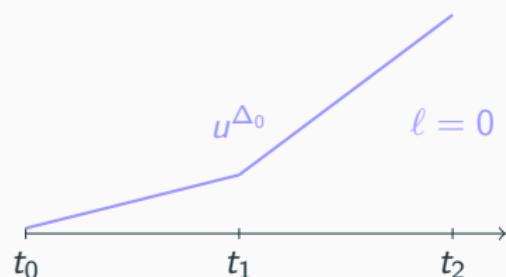
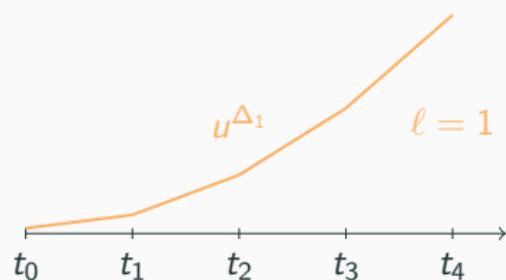
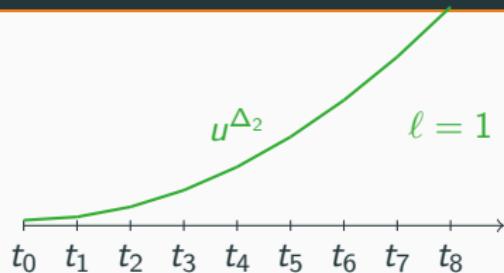
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Similarly,

$$\begin{aligned} u^{\Delta_2} &= (u^{\Delta_2} - u^{\Delta_1}) \\ &\quad + (u^{\Delta_1} - u^{\Delta_0}) + u^{\Delta_0} \end{aligned}$$

## Multilevel telescoping sum



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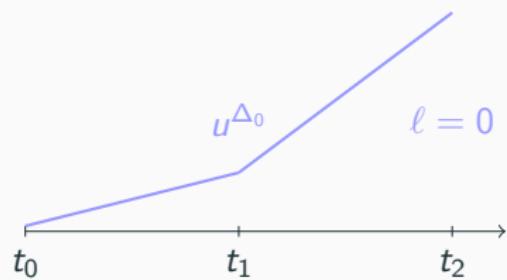
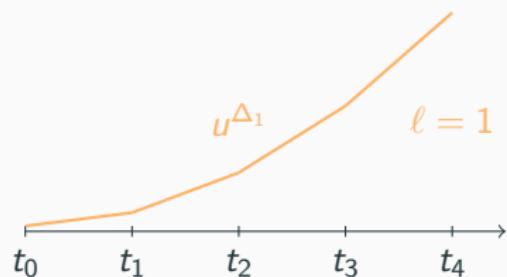
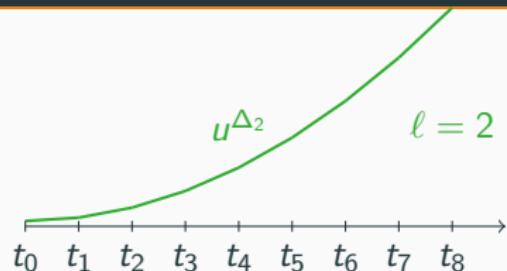
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In general,

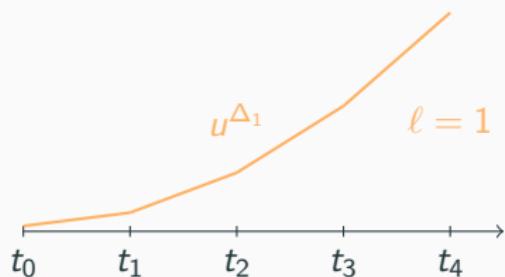
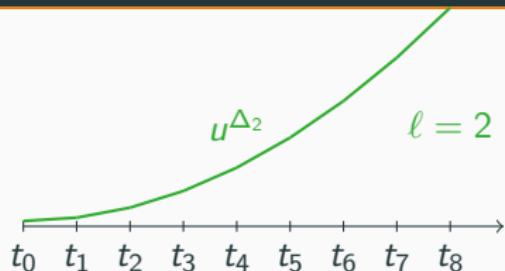
$$u^{\Delta_L} = \sum_{l=1}^L (u^{\Delta_\ell} - u^{\Delta_{\ell-1}}) + u^{\Delta_0}$$

## Multilevel Monte Carlo [Giles, 2008; Heinrich 2001]



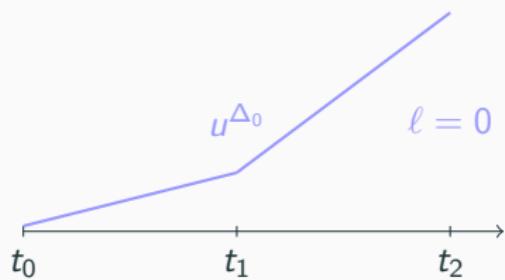
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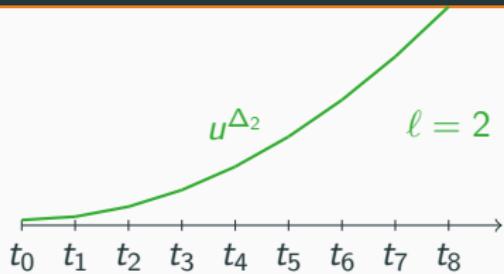


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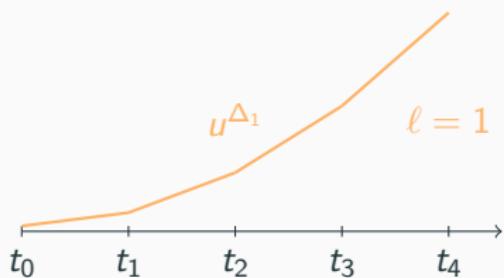
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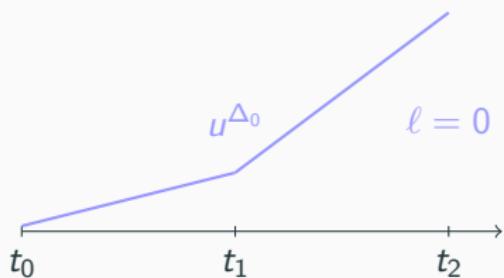


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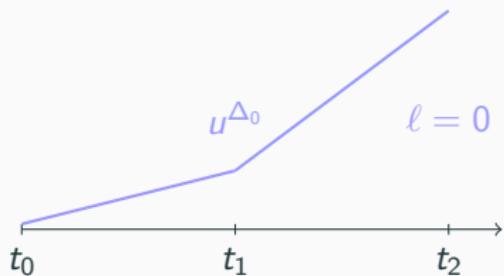
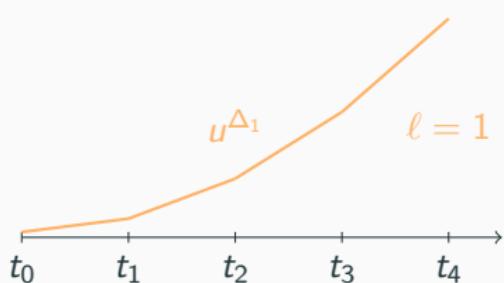
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In general,

$$\mathbb{E}(u^{\Delta_L}) = \sum_{l=1}^L \mathbb{E}(u^{\Delta_l} - u^{\Delta_{l-1}}) + \mathbb{E}(u^{\Delta_0})$$

## Variance reduction

---

$$\mathbb{E}(u^{\Delta_1}) = \mathbb{E}(u^{\Delta_1} - u^{\Delta_0}) + \mathbb{E}(u^{\Delta_0})$$

# Variance reduction

---

$$\begin{aligned}\mathbb{E}(u^{\Delta_1}) &= \mathbb{E}(u^{\Delta_1} - u_k^{\Delta_0}) + \mathbb{E}(u_k^{\Delta_0}) \\ &\approx \underbrace{\frac{1}{M_1} \sum_{k=1}^{M_1} (u_k^{\Delta_1} - u_k^{\Delta_0})}_{\approx \mathbb{E}(u^{\Delta_1} - u^{\Delta_0})} + \underbrace{\frac{1}{M_0} \sum_{k=1}^{M_0} u_k^{\Delta_0}}_{\approx \mathbb{E}(u^{\Delta_0})}\end{aligned}$$

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Error

$$\begin{aligned}\mathbb{E} \left( (E_{M_0, M_1}(u) - \mathbb{E}(u^{\Delta_1}))^2 \right)^{1/2} &= \mathbb{E} \left( (E_{M_0, M_1}(u) - (\mathbb{E}(u^{\Delta_1} - u^{\Delta_0}) + \mathbb{E}(u^{\Delta_0})))^2 \right)^{1/2} \\ &\quad + \mathbb{E} \left( (E_{M_0, M_1}(u^{\Delta_0}, u^{\Delta_1}) - \mathbb{E}(u^{\Delta_1}))^2 \right)^{1/2} \\ &\frac{\text{Var}(X)^{1/2}}{M^{1/2}}\end{aligned}$$