

# Deltares

## A comparison of methods for the nonlinear optimization problem of hydropower generation in a reservoir cascade

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## Reservoir cascade

- Three reservoirs, Inspired by the Grand River system (USA)
- Question: When to release how much?
  - o Reservoir inflow
  - o Load balance
  - o Flood control
  - o Generator limit
  - o Dam safety
  - o ...

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### Equations

- Reservoir equation (linear)
- Turbine flow (power generation) and spill flow (no power generation) (linear)
- Relation between water level and volume (nonlinear)
- Power generation (nonlinear)
- Head difference (nonlinear)
- Tailwater level (linear)

$$\frac{\partial V}{\partial t} = Q_{\rm in} - Q_{\rm out}$$

$$Q_{\text{out}} = Q_{\text{turbine}} + Q_{\text{spill}}$$

$$h = f(V)$$
$$P = \Delta h \cdot Q_{\text{turbine}} \cdot \eta \cdot \rho \cdot g$$

$$\Delta h = h - h_{
m tailwater}$$

$$h_{\text{tailwater}} = \gamma(Q_{\text{out}})$$

# **Optimization problem**

- Equality constraints:
  - o physical equations (previous slide)
- Bounds: physical limits:
  - o Minimum and maximum volume / pool elevation
  - o Maximum turbine admission
  - o Generator limits
  - o Spillway capacity
- Operational goals
  - o Generation targets (load)
  - o Operational range for water levels
  - Priorities (goal programming) and weights (Pareto optimization)
  - o Discharge targets

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# (Nonlinear) reservoir optimization - linearization

- 1. Volumes and flows only
  - Very fast
  - Limited in equations to volumes and flows:
  - no hydropower, no water level
  - Compute hydropower in post-processing:
  - no optimization to maximize hydropower
  - no incentive to keep the water level high
- 2. Linear approximation
  - Compute linear although not linear
- 3. Piecewise-linear
  - Split nonlinear function into linear pieces
  - Linear behavior for sections limits inaccuracy
  - Quite fast

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• Adds Boolean logic to the optimization





## Nonlinear reservoir optimization

- 4. Homotopy
  - Novel approach (Deltares, software: RTC-Tools)
  - Functional principle: "bend" the equations from linear towards nonlinear equations with the help of a  $\theta$  between 0 and 1 during the optimization (iteration steps)
  - Path-stable solution, connected to a global optimum of the linear part of the problem

$$\begin{split} P_{\rm h} &= (1 - \theta) \cdot {\rm g} \cdot \rho \cdot \eta \cdot Q_{\rm turbine} \cdot \Delta \widetilde{H} & \text{linear part, } \Delta {\rm H} \text{ is constant} \\ &+ \theta \cdot ({\rm g} \cdot \rho \cdot \eta \cdot Q_{\rm turbine} \cdot \Delta {\rm H}) & \text{nonlinear part, } \Delta {\rm H} \text{ is variable} \end{split}$$

 $\Delta \widetilde{H} = \text{const}$ 

- 5. Heuristic approaches
  - Functional principle:
  - e.g. genetic algorithm inspired by natural selection
  - Can optimize anything
  - No guarantee for a global optimum
  - Result can depend on seeding
  - a little change in inflow can lead to a completely different result  $\rightarrow$  not suitable for operational use
  - Comparatively slow

## The RTC-Tools model for the Grand River cascade



# **Operational goals**

Variable	Goal		Priority	Weight
Н	Drawdown forebay < 0.0625 m/h	$\rightarrow$ Bank stability	1	1.0
Qout	Qout,GL < 1 000 m <sup>3</sup> /s Qout,LH < 1 000 m <sup>3</sup> /s Qout,FG < 1 500 m <sup>3</sup> /s	→ Flood protection goal	2	1.0
V	$\begin{array}{l} 515\ 801\ 371\ m^3 < V_{GL} > 2\ 447\ 982\ 614\ m^3 \\ 250\ 765\ 250\ m^3 < V_{LH} < 548\ 049\ 719\ m^3 \\ 458\ 160\ 288\ m^3 < V_{FG} < 1\ 604\ 750\ 133\ m^3 \end{array}$	$\rightarrow$ Water level range goals	3	1.0
V	1 639 356 717 m <sup>3</sup> < VGL< 1 949 341 935 m <sup>3</sup>	$\rightarrow$ Inner H goal for GL	4	1.0
Р	P = power request timeseries	→ Load request goal	5	1.0
Qspill	Minimize Qspill	ightarrow all water through the turbines	6	100.0
Qturb	Minimize change in Qturb	$\rightarrow$ Smooth flow through turbines	6	1.0
Qspill	Minimize change in Qspill	$\rightarrow$ Smooth flow through spillway	6	1.0



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Reservoir outflow

## Flood scenario: Lake Hudson



#### Load balance scenario: system-wide generation



obtained with different methods

23  $\Delta^{I}h_{piecewise linear}$ 22  $\Delta h_{homotopy}$ Δ H [m AoD] 21  $\Delta h_{\text{linear}}$ 20 Domain border  $\Delta h$  (piecewise-linear) 19 18 17 16 15 Aug-08 Aug-10 Aug-06 Aug-07 Aug-09 Aug-11 Aug-12 Aug-13 Time 1200 Discharge [m<sup>3</sup>/s] Q<sub>turbine</sub>, piecewise-linear Q<sub>turbine</sub>, linear Q<sub>turbine, homotopy</sub> 1000 800 600 400 200 0 Aug-09 Aug-08 Aug-06 Aug-07 Aug-10 Aug-11 Aug-12 Aug-13 Time 1.5×10° ∑ 10<sup>8</sup> Jaw 5×10<sup>7</sup> Power generation, re-calculated  $\mathsf{P}_{\mathsf{linear}}$ homoton piecewise linea n Aug-08 Aug-10 Aug-06 Aug-07 Aug-09 Aug-11 Aug-12 Aug-13 Time

Optimization result for Lake Hudson

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#### Load balance scenario: release and volume (GL)



## Technical remarks and conclusions

- Result quality
  - All three methods produce good results
  - Different accuracy for the physics:
    - Homotopy
      - shows most accurate results for Q ∆h in generation
    - Piecewise-linear
      - Represents interplay Q  $\Delta h$  to some extent
    - Tends to not leave  $\Delta h$  domains
    - Linear
      - No incentive to keep water level high, only Q determines the generation



- Usability, performance and math
  - o Linear
    - Fast
    - Proven technology, straight-forward
    - Easy to understand
    - Global optimum for a simplified problem
  - o Piecewise-linear
    - Adds mixed integer logic
    - comes with user choices and tuning:
      - domain borders
      - scaling of the optimization problem
    - More domains (more accuracy) means exponentially more computing time (not shown here, see Haf 2019 for more details)
    - Global optimum for a simplified problem
  - o Homotopy
    - Easy to apply from a modeler's perspective
    - Must be supported by the software (here: RTC-Tools)
    - Novel method, not generally tested for other equations
    - Path-stable only
    - Not (yet) compatible with mixed integer logic
    - Not (yet) compatible with ensemble optimization

# **RTC-Tools**



- A toolbox for (real-time) control and optimization of water systems
- Websites
  - o https://www.deltares.nl/en/software/rtc-tools/
  - o https://oss.deltares.nl/web/rtc-tools



- Open source
- Modelica-library with various flow equations
- Comes as Python package
- Conflict resolution with goal programming and weighting factors
- Ensemble optimization
- Integrates in Delft-FEWS for operational use





RTC-Tools optimization results in Delft-FEWS TransAlta (van Loenen & Fru, CEATI conference 2021)

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## Nonlinearity #1: Storage geometry

$$\frac{\partial V}{\partial t} = Q_{\rm in} - Q_{\rm out}$$

- The reservoir equation is linear
- The water volume in a reservoir is an <u>increasing</u>, but generally <u>nonlinear</u> function of water level.
- **Solution**: preprocess water level goals to volume goals





# Nonlinearity #2: Hydropower generation

• Instantaneous power from a hydroelectric turbine:

 $P = \eta \cdot \rho \cdot \mathbf{g} \cdot Q \cdot \Delta H.$ 

- Q and  $\Delta H$  are optimization variables.
- *P* is a nonlinear, even <u>nonconvex</u>, function of *Q* and  $\Delta H$ .
- Solution: Choose of optimization variables and goals such that the problem is <u>nonlinear</u> but <u>convex</u> formulations
  - Assume  $\Delta h = \text{const}$  (no incentive to keep the water level high)
  - Maximize power as optimization goal



Hydropower production depends on  $Q \bullet \Delta h$  (maximize is ok, but not load balance)

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