



engineering center steyr

Exact Shape Models for Dip Painting Simulation and Isogeometric Analysis

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MAGNA's Global Product & Engineering Capabilities





5/27/2014

Dip Paint Simulation CAE- Process



Technique for Volumetric Consideration (VoF)



- Goal: Reduce Computation Time
- B-Reps (e.g. △ -mesh) → Volumina mesh by Reeb graph method
- e.g., entire car body ~8 000 elements
- tetrahedral mesh of entire car body 20 Million elements

Different Reeb graphs for a solid







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Application Fill & Drain Module



- Fill&Drain in time-domain
- Consideration of velocity trough narrow gaps (bottle necks)
- New distance field approach for detecting bottle necks



Starting from vertex Add neighbors to distance field Uistance to start vertex is below a demand Self-intersecting boundaries of distance fields = bottle neck



Application Fill & Drain Module



 Integration of the bottle neck into the Reeb graph by assigning the borders of patches







Dip Paint Simulation



Bernoulli's Principles by considering

- Pressure
- Velocity
- Time
- Gravity
- Density (constant for water and air)
- Incompressibility







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ECS

Automatic segmentation of B-Rep solids into hexahedral volumes



Automatic segmentation of B-Rep solids into hexahedral volumes





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Automatic segmentation of B-Rep solids into hexahedral volumes



- Cutting into base solids
- Predefined segmentation into hexes





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Automatic segmentation of B-Rep solids into hexahedral volumes



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Conclusion



Thank you for your attention!





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