

What is Isogeometric Analysis?

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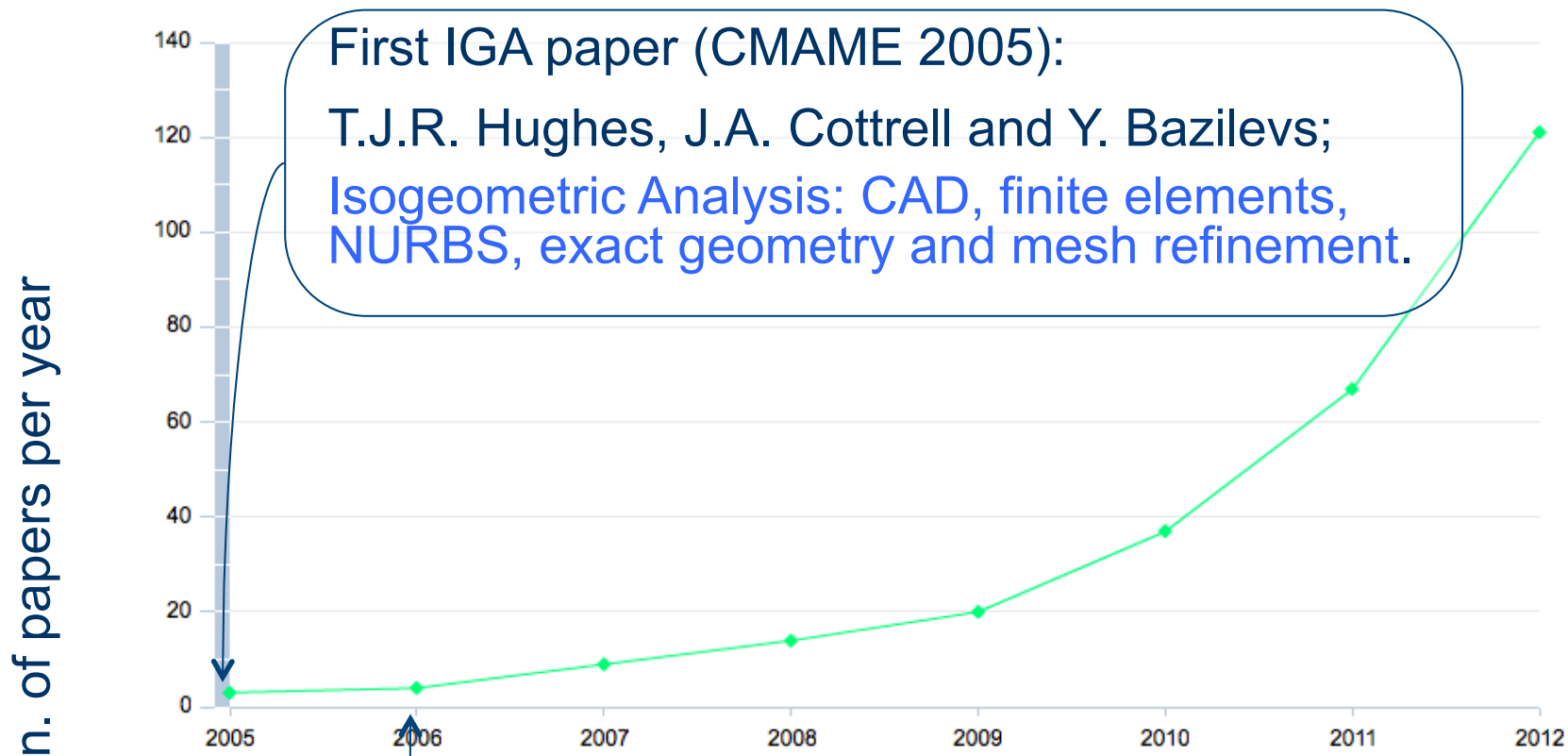
Milan, June 30, 2014

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European Community's Seventh Framework Programme
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Call FP7-2011-NMP-ICT-FoF

Isogeometric Analysis (IGA):

RECENT EMERGING technology for
Scientific Computing, stemming from
OLD ideas

IGA timeline and diffusion (from SCOPUS)



First IGA paper (CMAME 2005):

T.J.R. Hughes, J.A. Cottrell and Y. Bazilevs;
Isogeometric Analysis: CAD, finite elements,
NURBS, exact geometry and mesh refinement.

First “math” IGA paper (M3AS 2006):

Y. Bazilevs, L. Beirão Da Veiga, J.A. Cottrell, T.J.R. Hughes, G. Sangalli
Isogeometric analysis: Approximation, stability and error estimates for h-refined meshes.



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SEVENTH FRAMEWORK
PROGRAMME

Two fundamental steps in Virtual Manufacturing:

CAD (1970's - 1980's) – Engineering Design Process:

- ✓ engineering designs are encapsulated in CAD systems;
- ✓ CAD geometry is *exact*;
- ✓ hundreds of thousands analyses of CAD designs are performed in engineering offices throughout the world every day

FEM (1950's - 1960's) – Engineering Analysis Process:

- ✓ CAD geometry is replaced by FEM geometry (“mesh”);
- ✓ mesh generation accounts for more than 80% of overall analysis time and is the major *bottleneck*;
- ✓ mesh refinement requires interaction with CAD geometry;
- ✓ the mesh is an *approximate* geometry

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Critical issues

IDEA (Hughes et al., 2005): Isogeometric Analysis

In the *Analysis framework*, employ the same functions used to describe the geometry of the computational domain, i.e., typically, use **B-Splines and Non-Uniform B-Splines (NURBS)**.

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Alternative to standard FE analysis, *including isoparametric FEA as a special case*, but offering other features and possibilities:

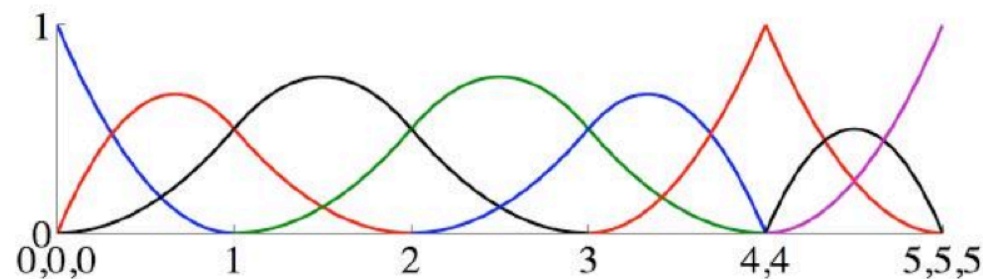
- ✓ **CAD geometry is exactly and efficiently represented**
- ✓ **simplified mesh refinement**
- ✓ *smooth* basis functions with *compact support*
- ✓ *superior* approximation properties
- ✓ *integration* of design and analysis

Starting point: Univariate B-Spline functions

Given a *non-uniform knot vector* $\mathcal{M} = \{\xi_1, \dots, \xi_{n+p+1}\}$, in the parametric domain, B-spline functions are iteratively defined as:

$$B_{i,0}(\xi) = \begin{cases} 1 & \text{if } \xi_i \leq \xi < \xi_{i+1} \\ 0 & \text{otherwise.} \end{cases}$$

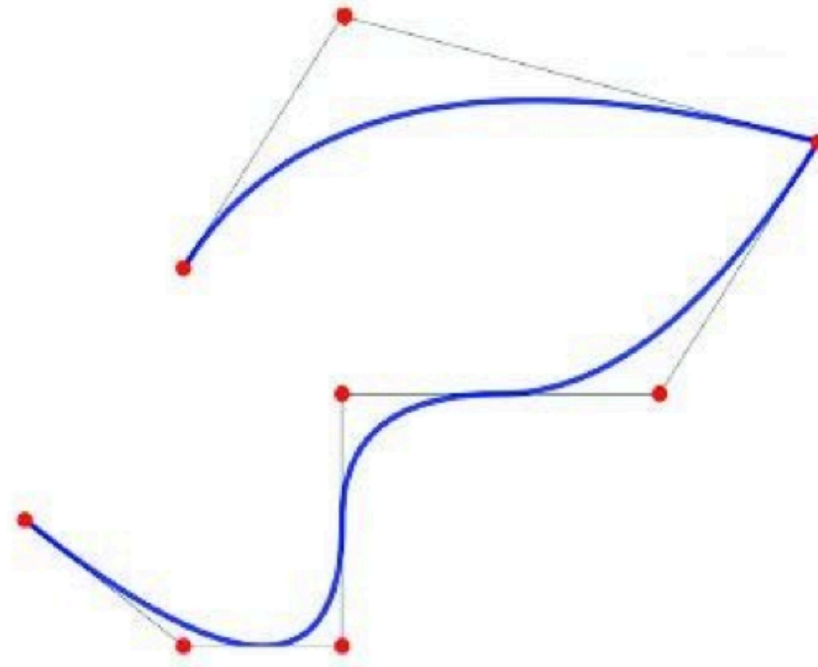
$$B_{i,p}(\xi) = \frac{\xi - \xi_i}{\xi_{i+p} - \xi_i} B_{i,p-1}(\xi) + \frac{\xi_{i+p+1} - \xi}{\xi_{i+p+1} - \xi_{i+1}} B_{i+1,p-1}(\xi).$$



The spline space is: $S_p(\mathcal{M}) = \text{span}\{B_{i,p}(\cdot)\}_{i=1,\dots,n}$

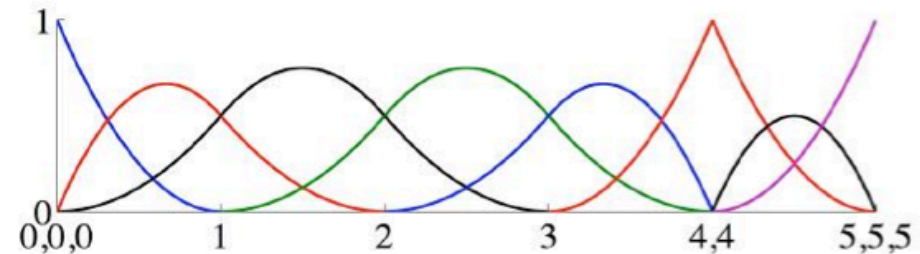
A spline curve

The image of $\mathbf{F}(\xi) = \sum_i \mathbf{C}_i B_i(\xi)$ is the B-spline curve:



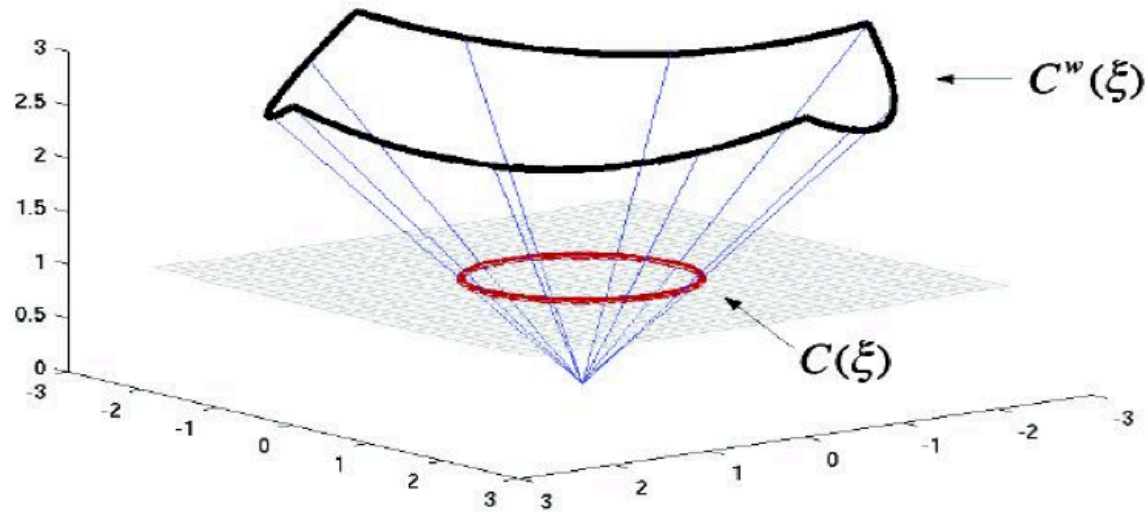
Control points

where $\mathbf{C}_i = \bullet$ and $B_i =$



A NURBS curve

A NURBS curve in \mathbb{R}^2 is the projection of a B-spline in \mathbb{R}^3



$$C(\xi) = \frac{[C_x^w(\xi), C_y^w(\xi)]}{C_z^w(\xi)} = \sum_{i=1}^n \mathbf{c}_i \frac{w_i B_{i,p}(\xi)}{\sum_{\hat{i}=1}^n w_{\hat{i}} B_{\hat{i},p}(\xi)} = \sum_{i=1}^n \mathbf{c}_i R_{i,p}(\xi).$$

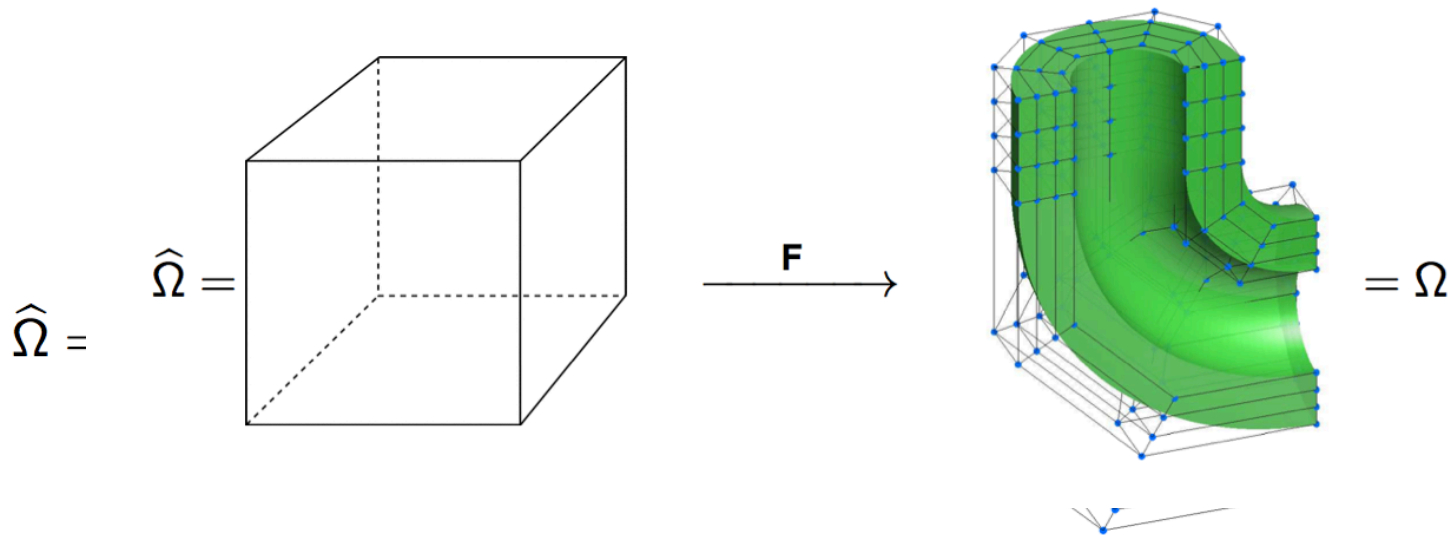
NURBS are able to exactly represent a vast set of geometrical objects, e.g. all the **conic sections**

Spline/NURBS volumes

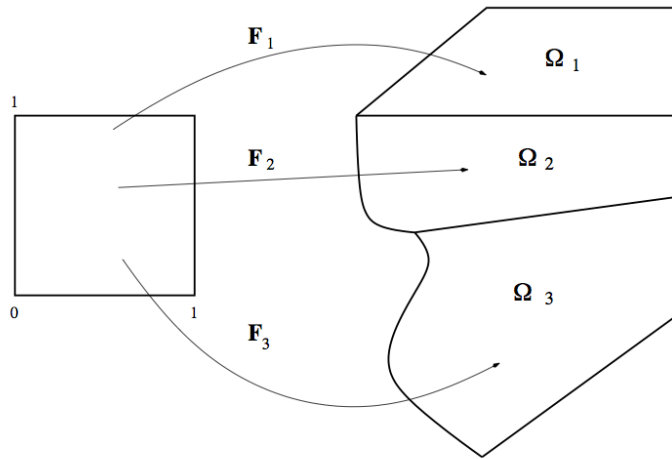
A spline space on a tensor product mesh $\mathcal{M} = \mathcal{M}_1 \otimes \mathcal{M}_2 \otimes \mathcal{M}_3$ is constructed by tensor product of univariate spaces:

$$S_{p_1, p_2, p_3}(\mathcal{M}) = S_{p_1}(\mathcal{M}_1) \otimes S_{p_2}(\mathcal{M}_2) \otimes S_{p_3}(\mathcal{M}_3)$$

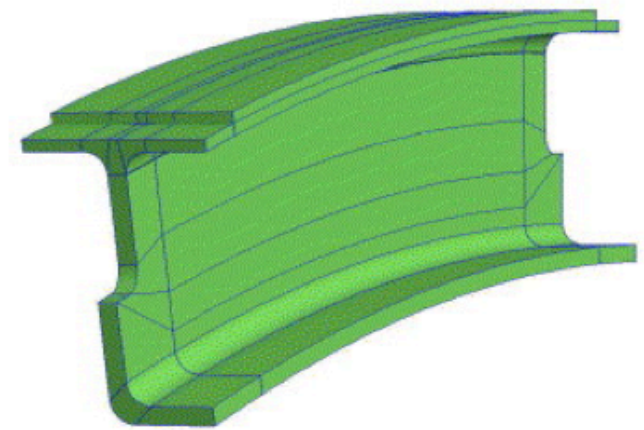
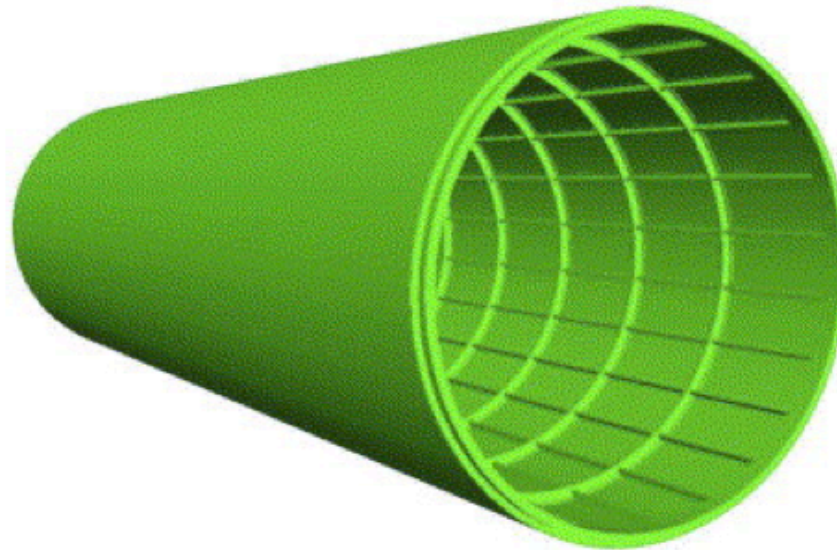
A *single-patch* spline geometry is parametrized by $\mathbf{F} \in (S_{p_1, p_2, p_3}(\mathcal{M}))^3$:



Spline/NURBS multi-patch volumes



Multi-patch geometries are typical in real-world applications

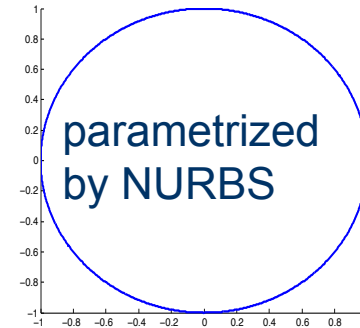


from T.J.R. Hughes group

FEM and IGA on a toy problem

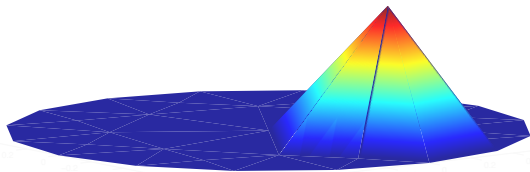
$$\begin{cases} -\Delta u = f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases}$$

CAD geometry

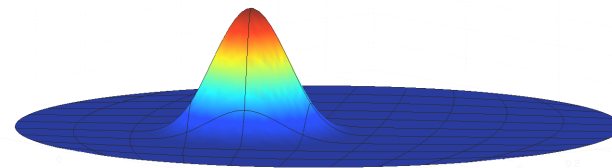


Find $u_h \in V_h$ such that $\int_{\Omega} \nabla u_h \cdot \nabla v_h = \int_{\Omega} f v_h, \forall v_h \in V_h.$

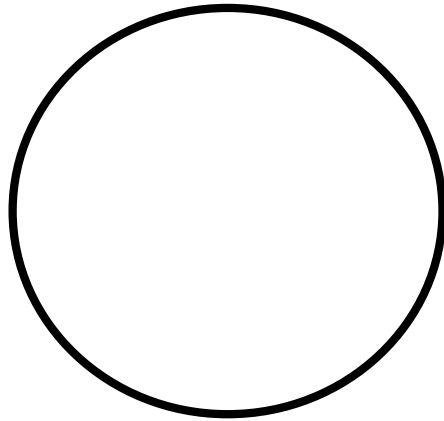
FEM



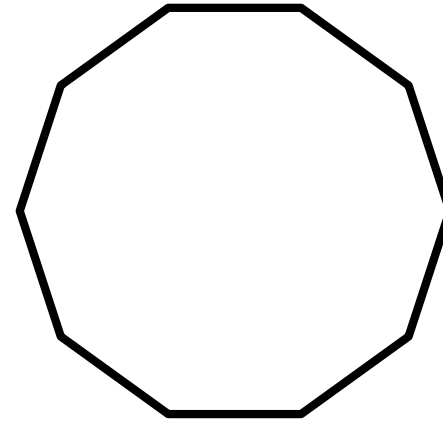
IGA



Exact geometry representation



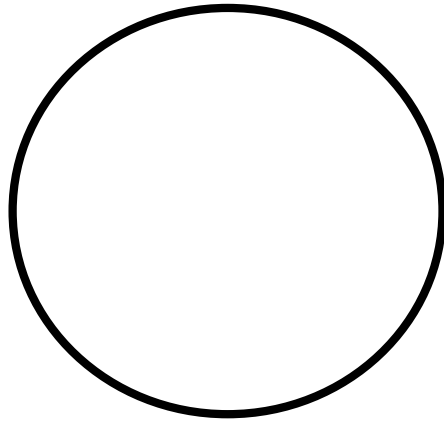
Exact



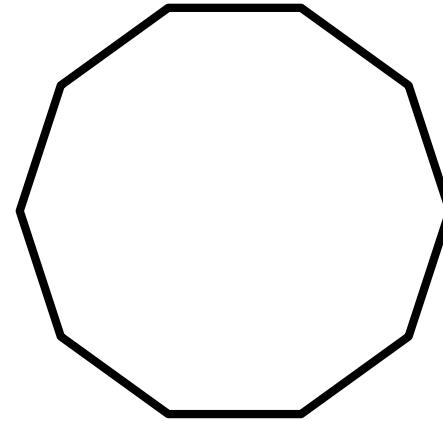
FEM domain

- ✓ Exact geometry provides **more accurate results** (computational domain is not altered)

Exact geometry representation



Exact

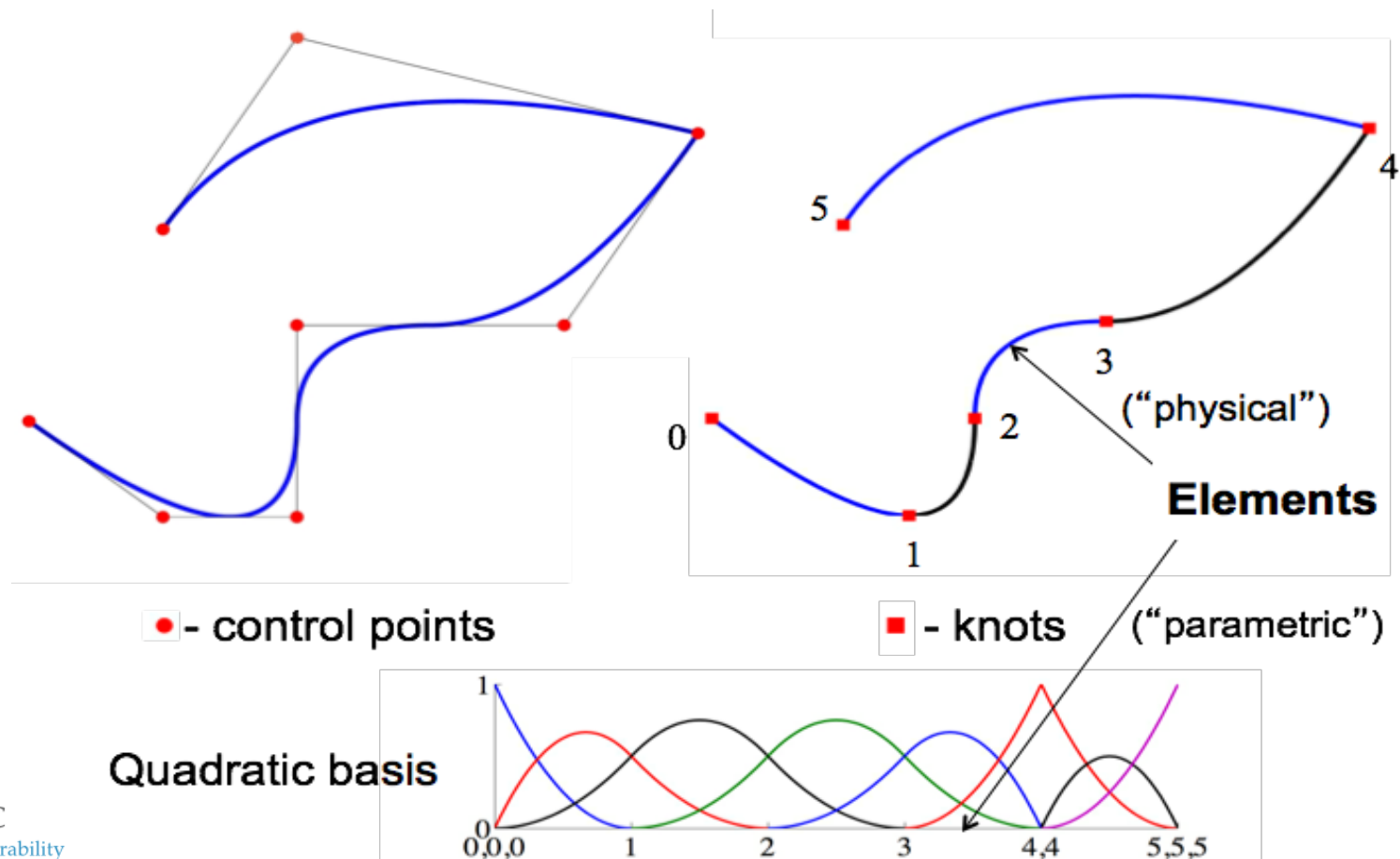


FEM domain

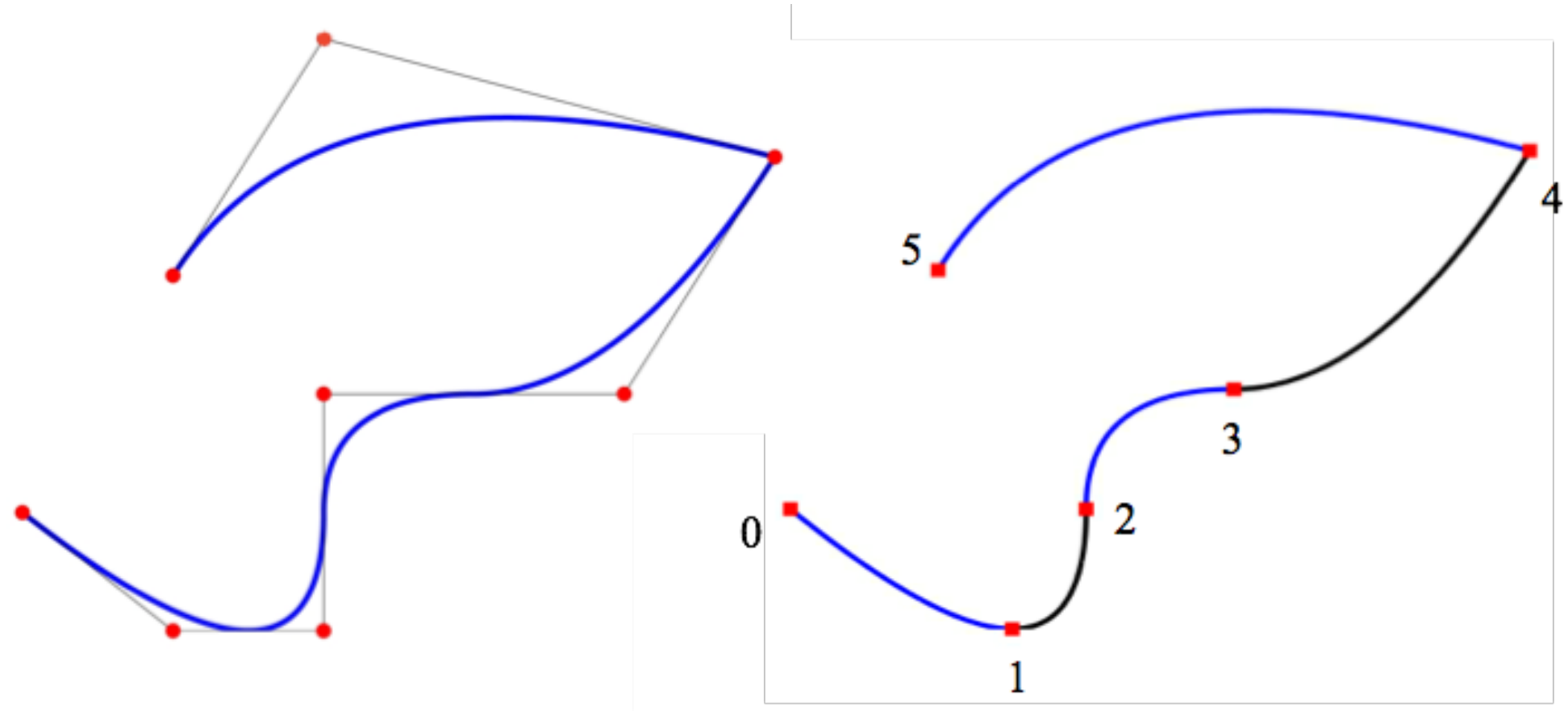
- ✓ Exact geometry provides **more accurate results** (computational domain is not altered)
- ✓ Sometimes the **perturbed geometry** causes **wrong** models (Babuska-Pitkaranta paradox 1990)

Refinement strategies (1D case): strategies to improve accuracy, acting on the mesh and/or on the approximation space.

The *parametric space* is mapped into the *physical space*, constructed as the linear combination of the basis functions and the control points: the analogues of the *elements* are the *images of the knot sequence* and *3 refinement strategies* can be adopted: *h-p-k refinements*.



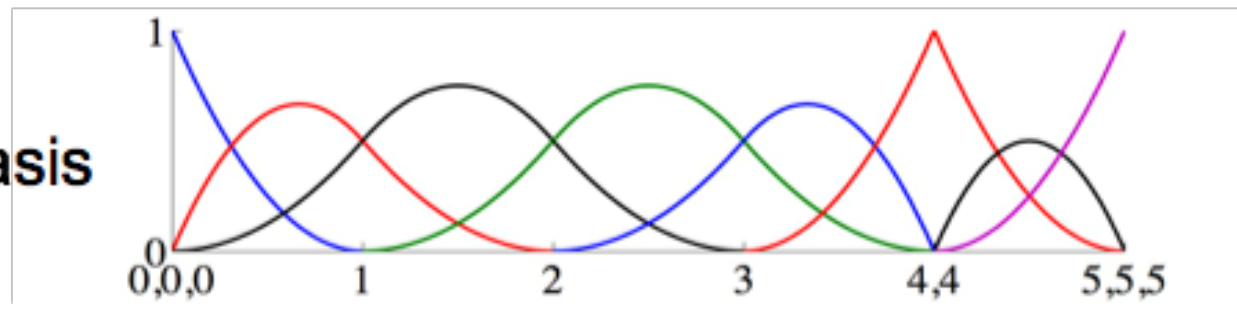
Example of h -refinement: mesh refinement



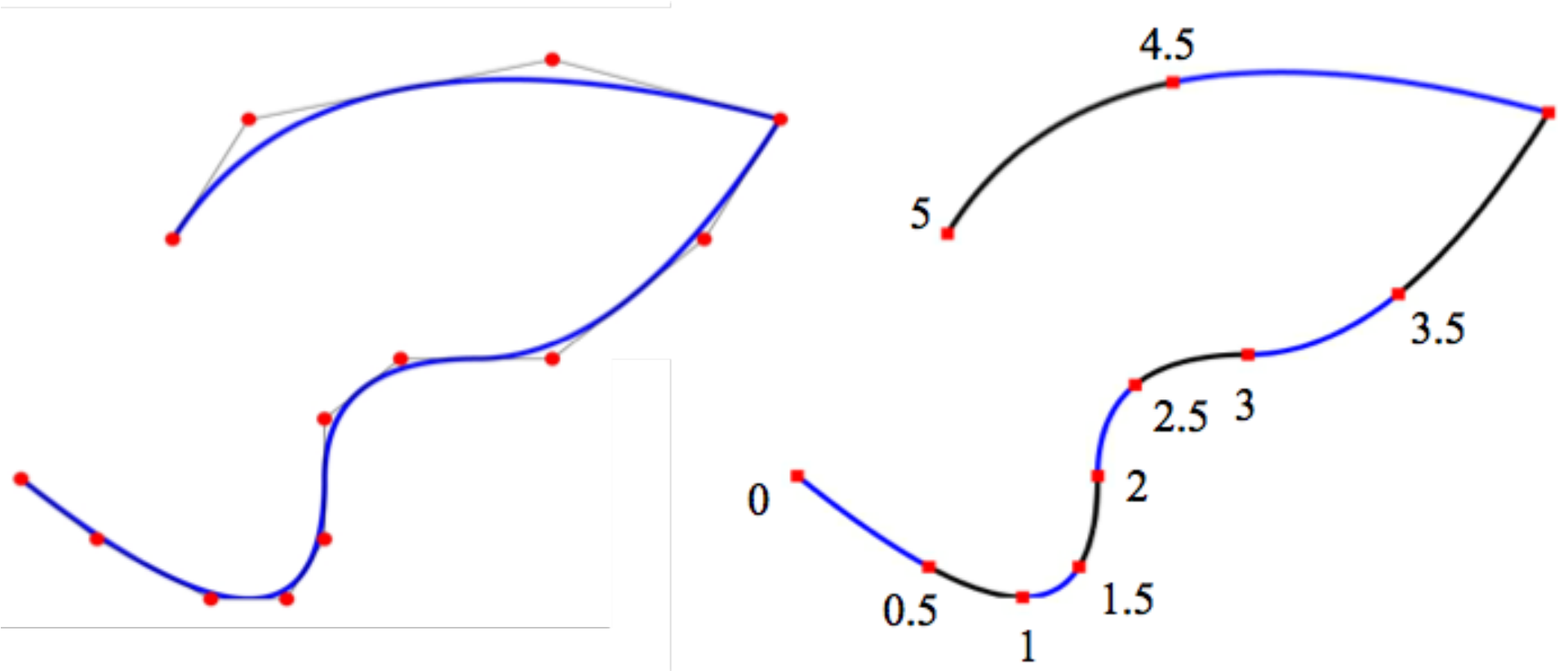
● - control points

■ - knots

Quadratic basis



Example of h -refinement: mesh refinement



● - control points

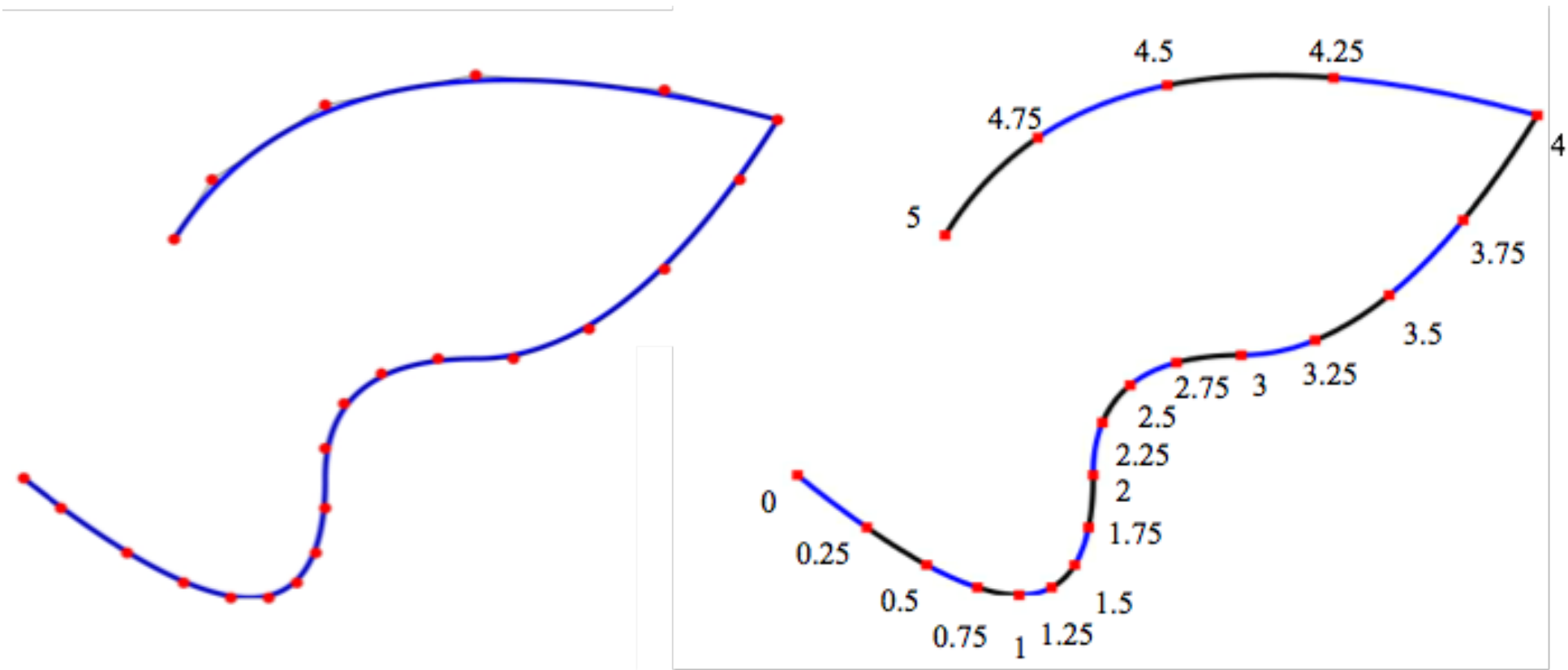
■ - knots

Quadratic basis

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Example of h -refinement: mesh refinement

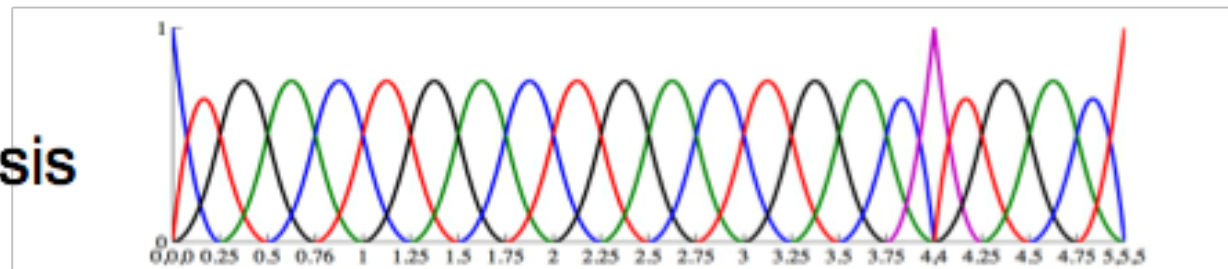


● - control points

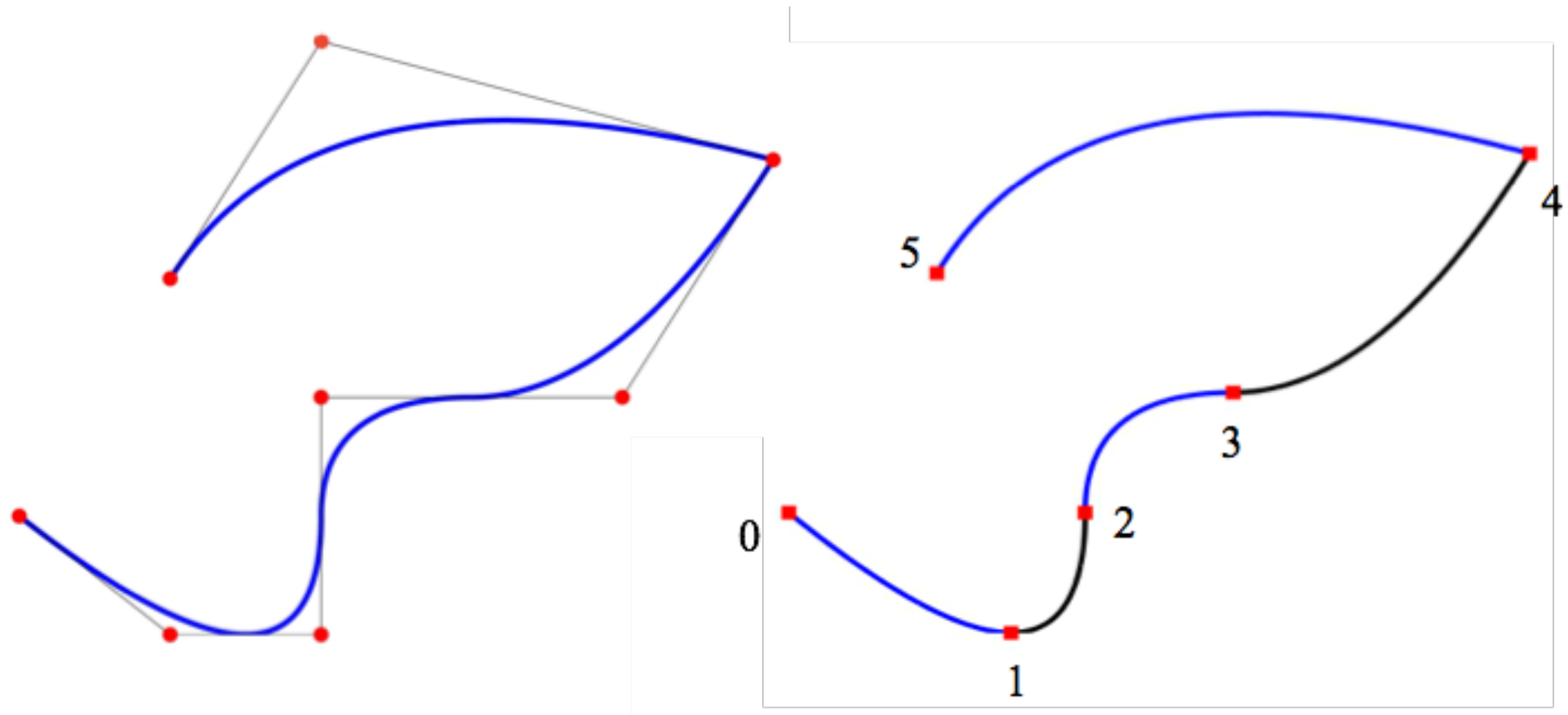
■ - knots

Quadratic basis

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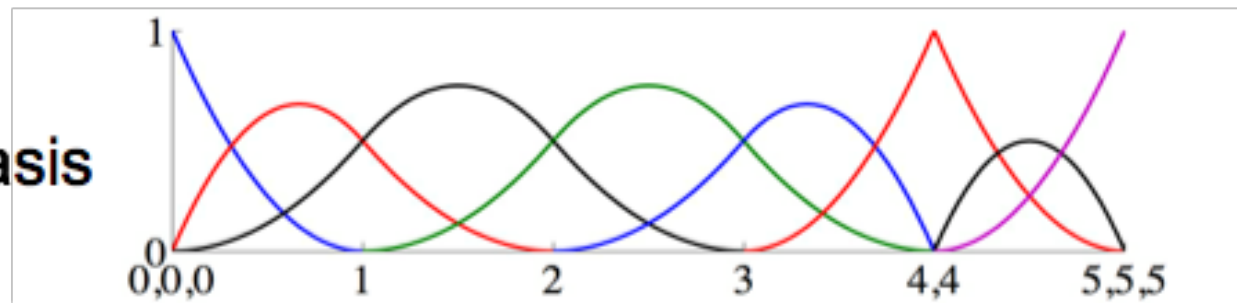
Example of p -refinement: enlarge approximation space, same mesh



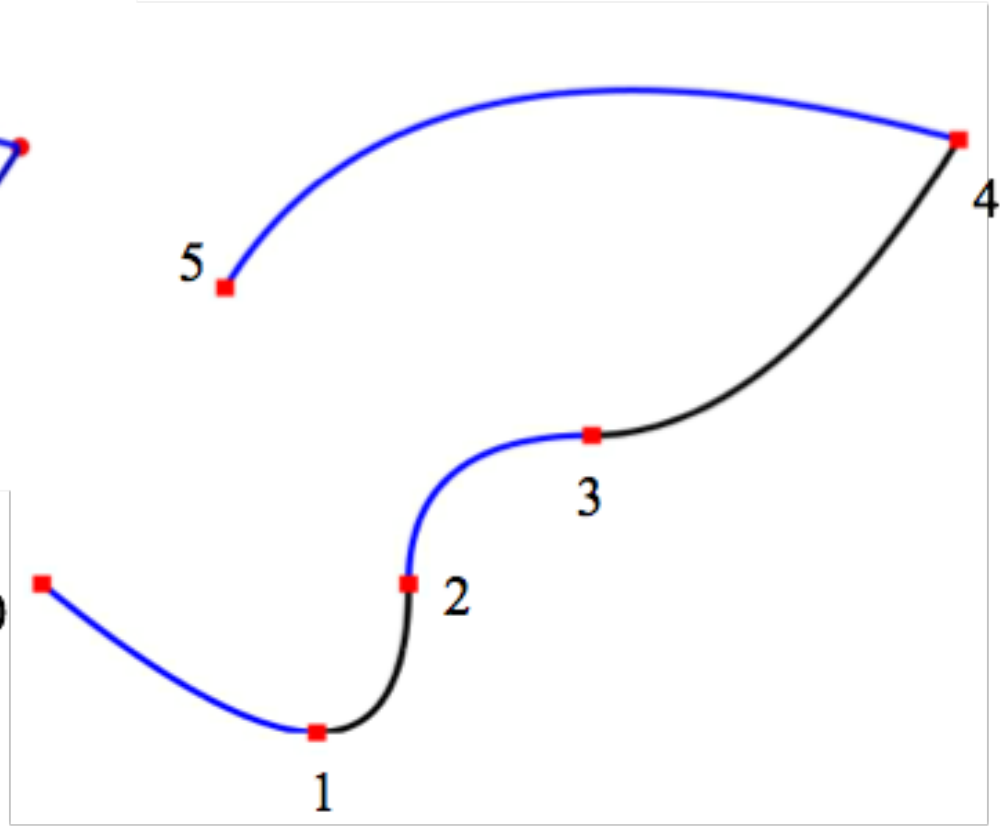
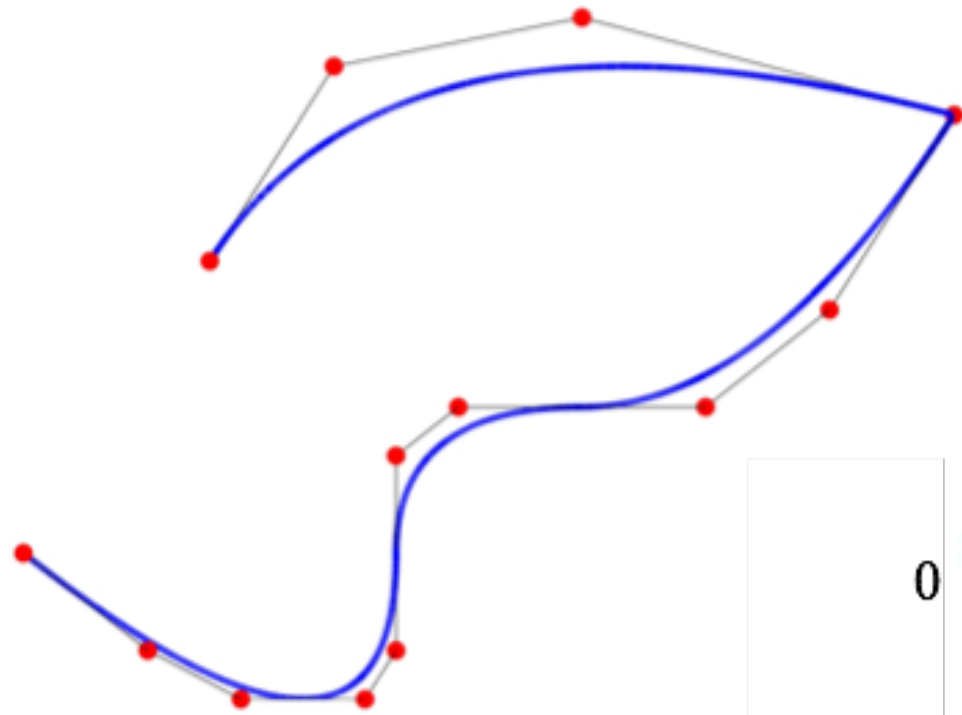
● - control points

■ - knots

Quadratic basis



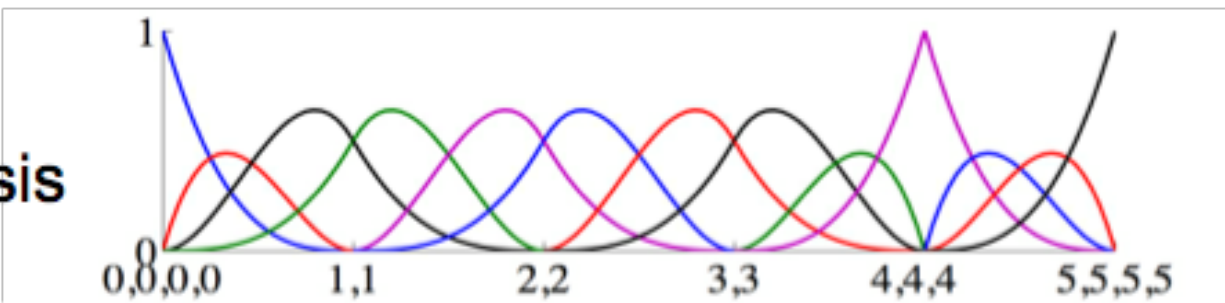
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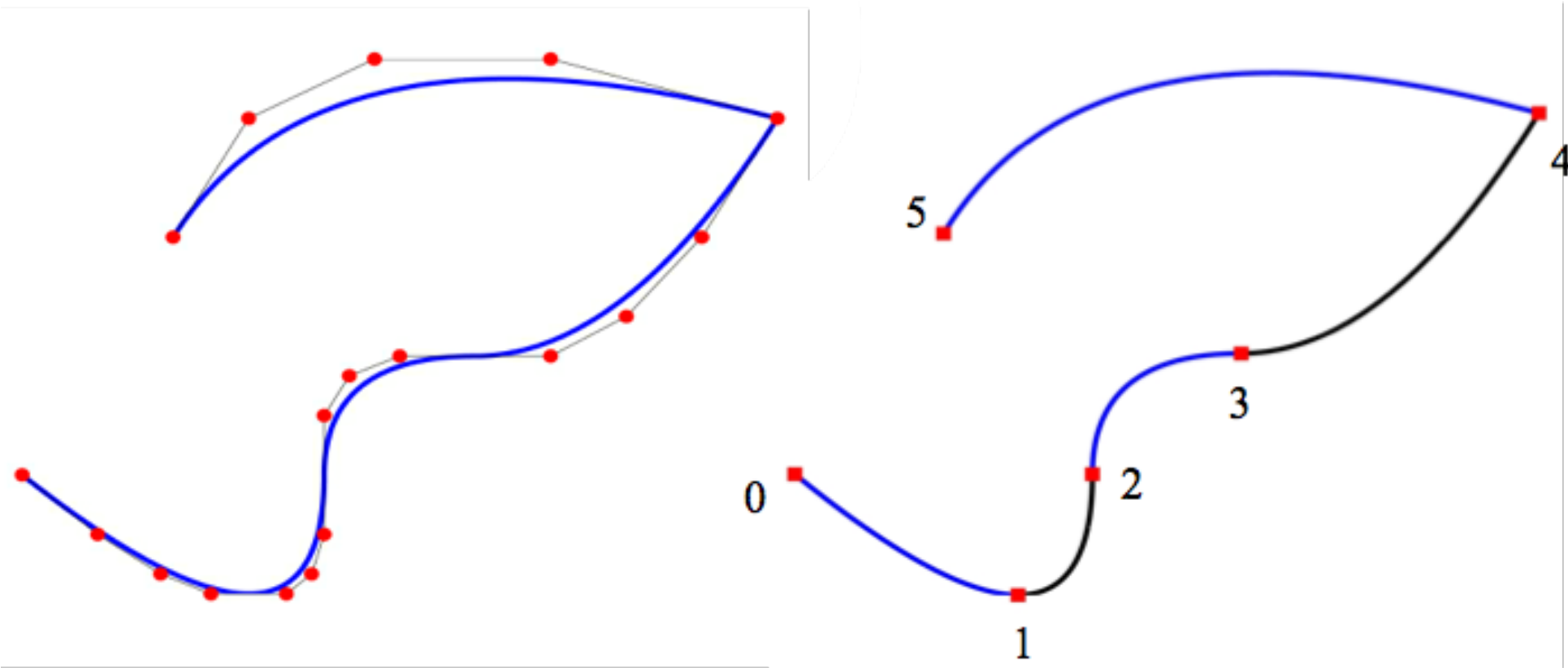
● - control points

■ - knots

Cubic basis



Example of p -refinement: enlarge approximation space, same mesh

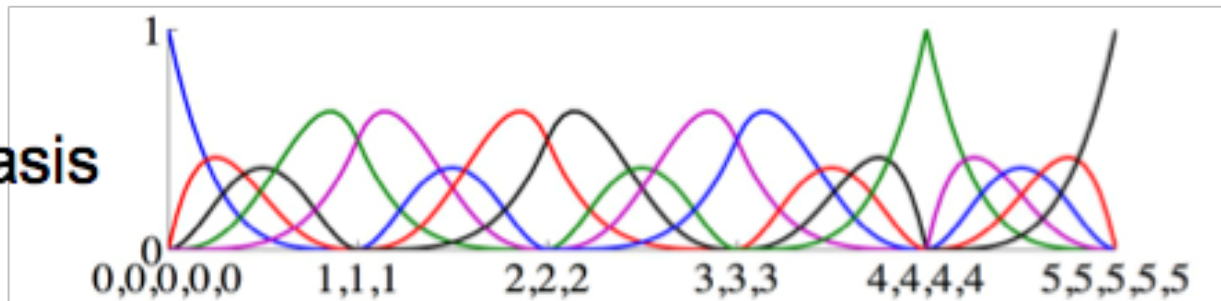


● - control points

■ - knots

Quartic basis

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**A third refinement strategy:
k-refinement [no analogue in FEM]**

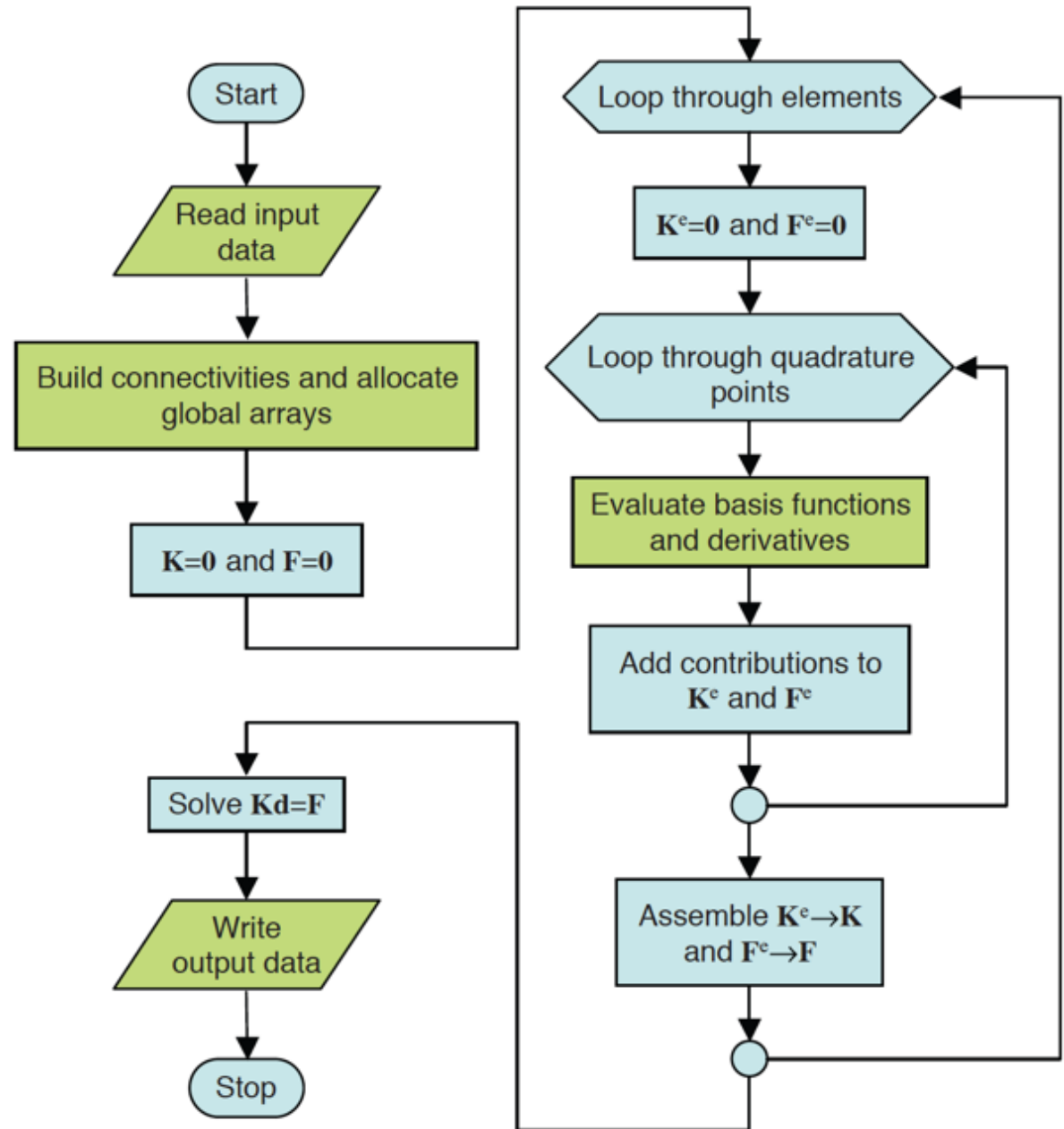
- Procedure in which the polynomial order and smoothness (differentiability) of the B-Spline basis functions are simultaneously increased
- No analogues in FEM
- Leads to possibilities previously unavailable in FEM:
 - Discretization of higher-order PDEs
 - Continuous stresses
 - Collocation methods
- Gives a sequence of “non-nested” spaces...

2D and 3D versions of h-p-k refinement procedures are available.

Implementation

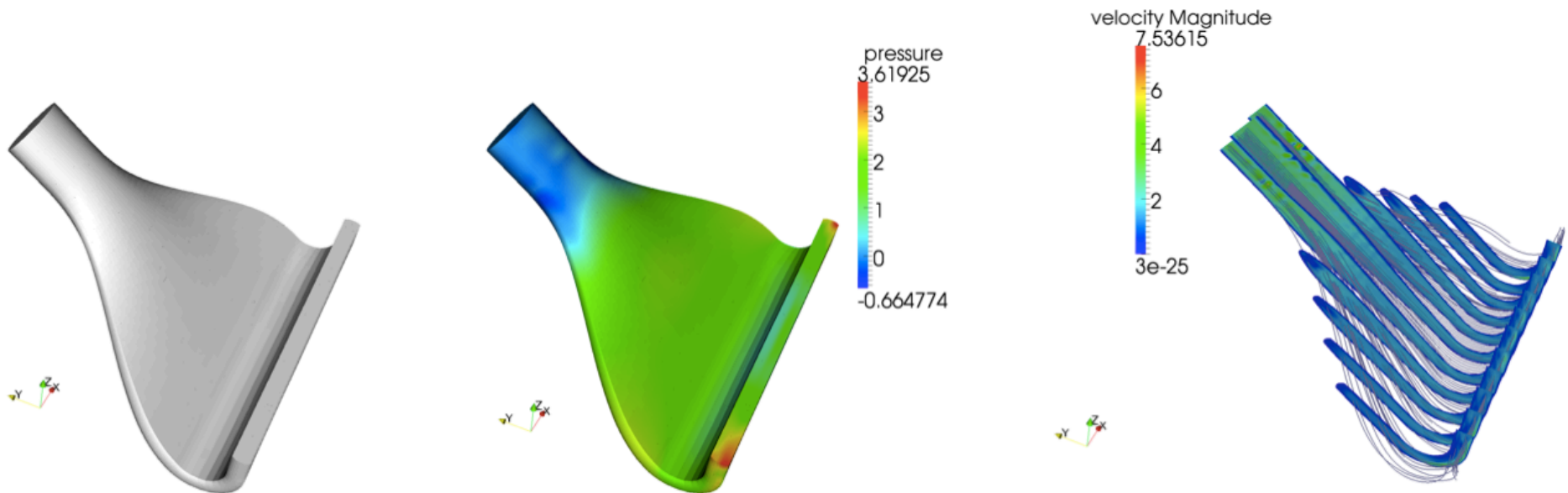
Flowchart of a classical finite element code. Such a code can be converted to a single-patch isogeometric analysis code by replacing the routines shown in green.

[Cottrell et al., 2009]

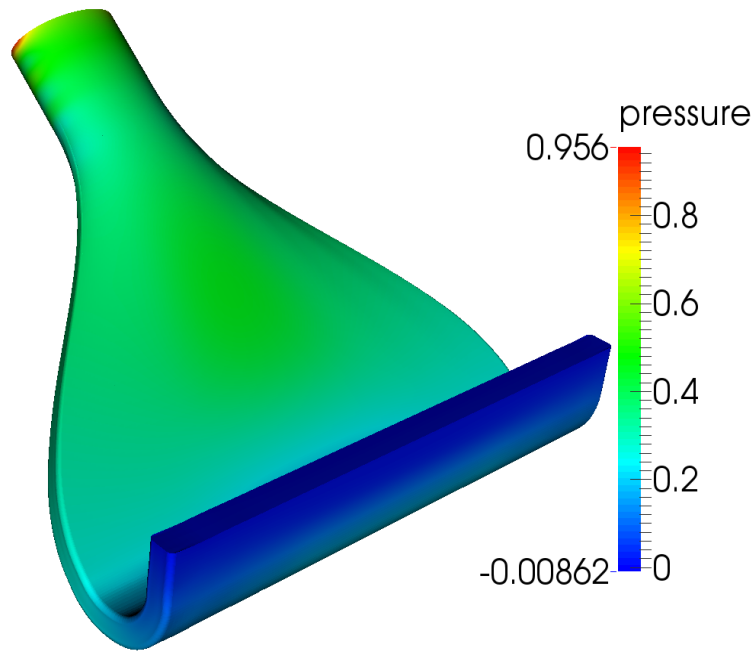


IGA for Navier-Stokes

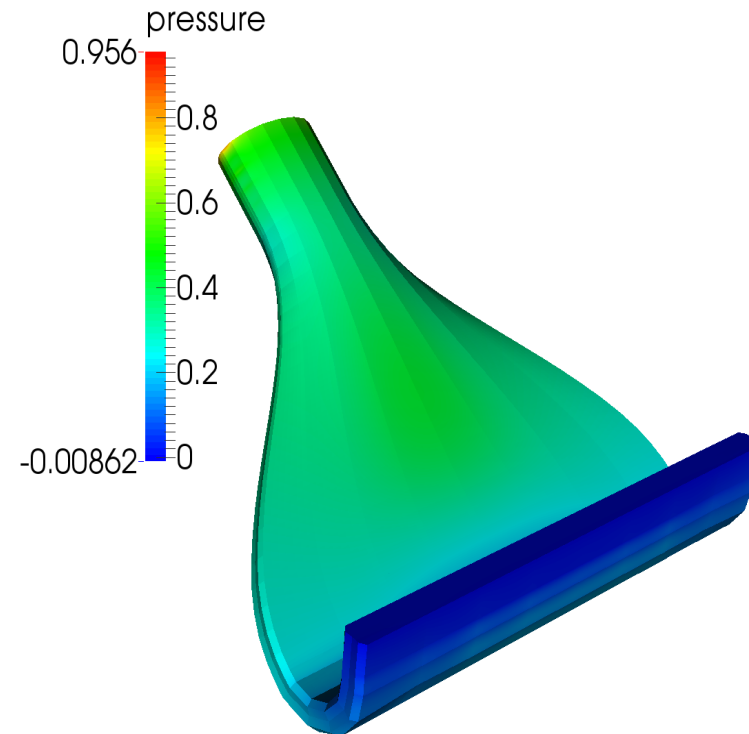
$$\begin{cases} \rho (\partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u}) - \mu \Delta \mathbf{u} + \nabla p = \mathbf{f} & \text{on } \Omega \times (0, T) \\ \nabla \cdot \mathbf{u} = 0 & \text{on } \Omega \times (0, T), \end{cases}$$



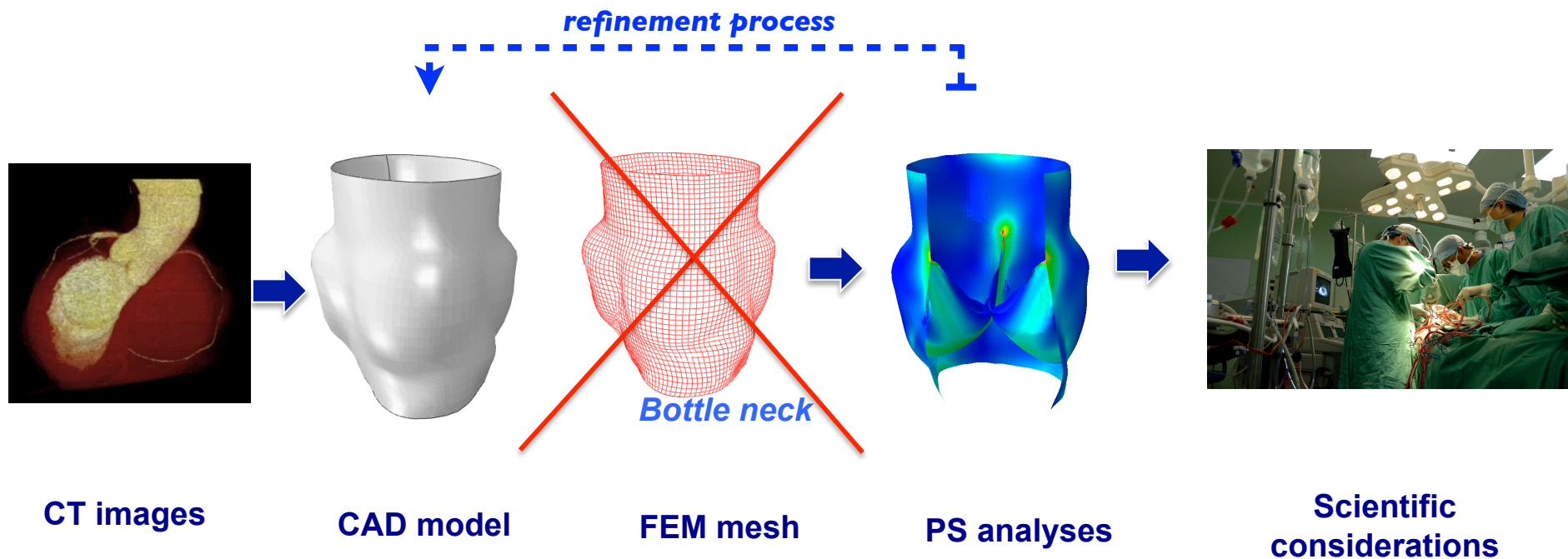
Pressure profile: IGA



Pressure profile: FEM

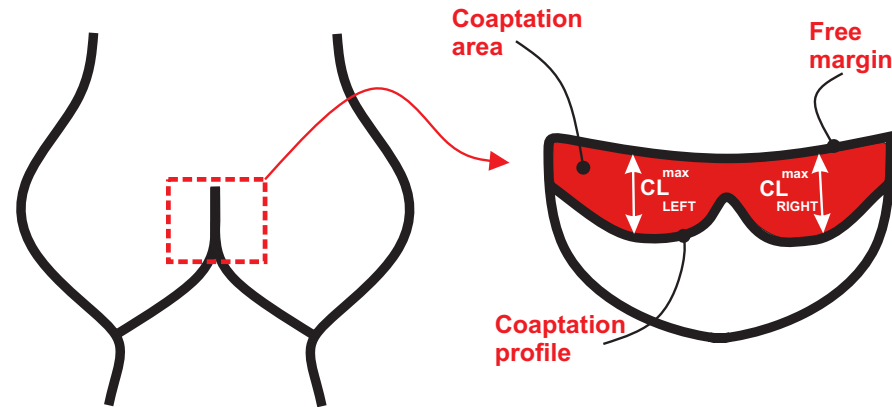


IGA for patient-specific structural analysis of aortic valve closure



IGA: R-M quadratic C1 shell for root and K-L quadratic shell for leaflets

FEA: Belytschko-Tsay 4-node R-M shell for root and leaflets

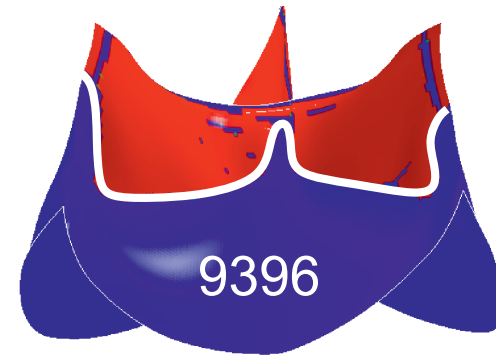
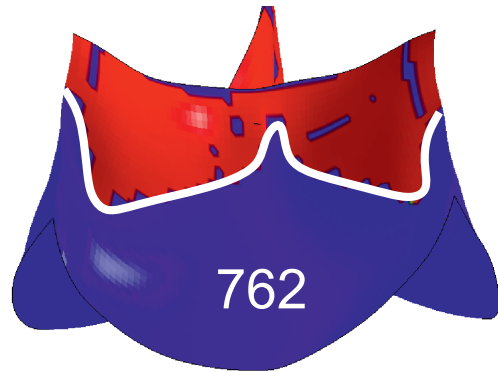


Simulation of valve closure: comparison with finite elements

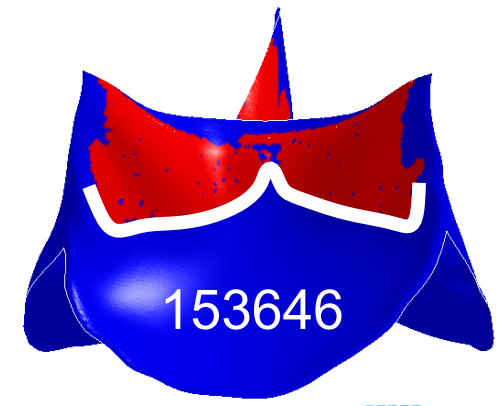
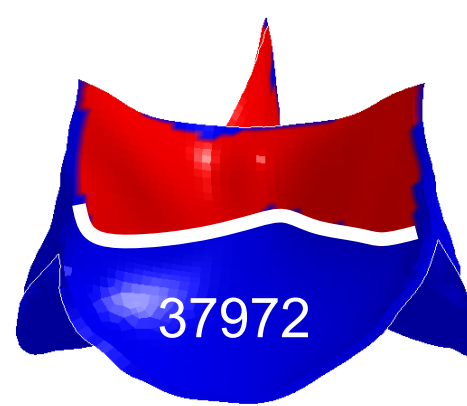
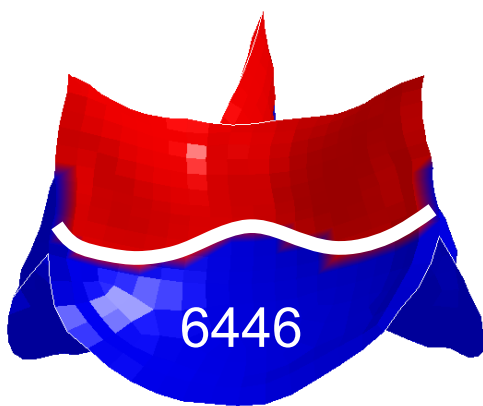
Analysis	# nodes	# DOF	Coaptation length	
			CL_{left}^{max} [mm]	CL_{right}^{max} [mm]
IGA	762	3708	9.30	9.40
	2890	19476	9.25	9.40
	9396	50496	9.30	9.35
FEA	1112	6672	11.1	12.8
	3117	18702	10.8	10.2
	6446	38676	10.4	9.80
	14329	85974	9.70	9.70
	37972	227832	9.45	9.50
converged	153646	921876	9.30	9.35

Coaptation profiles for different meshes (IGA and FEA)

IGA:



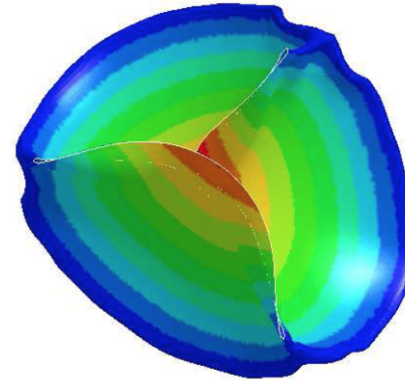
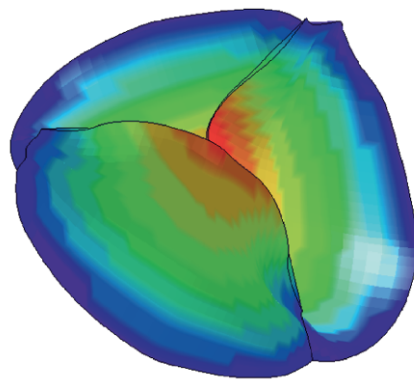
FEA:



a) IGA (762 nodes)

b) FEA (153646 nodes)

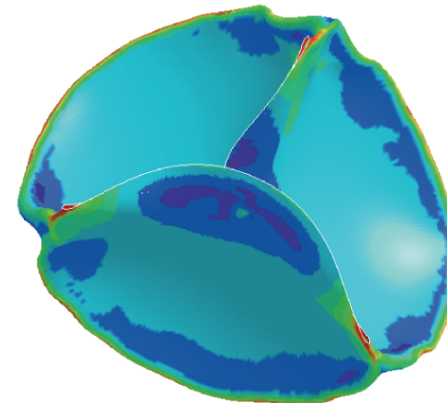
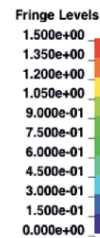
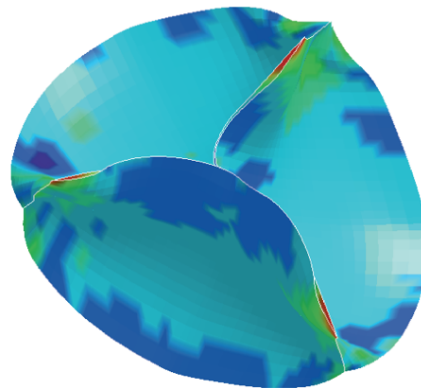
z-displacement contour map [mm]:



(a)

(b)

von Mises stress contour map [MPa]:



(a)

(b)

Comparison of computational time (IGA vs FEA)

Analysis	# nodes	# cpus	time step	# increments	total analysis time
IgA	762	12	2.30e-07	4347490	1h 15m
FEA	153646	12	2.65e-08	37787314	550h 23m

23 full days (24 hours)

Morganti S. et al., ICES Report 14-10,
and submitted to “*Computer Methods in Applied Mechanics and Engineering*”

CONCLUSIONS

Isogeometric Analysis is an emerging technology capable of:

- Directly **interacting** with the CAD systems
- Greatly **simplifying** the refinement processes
- **Improving** the solution accuracy
- **Reducing** the computational costs

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If your applications demand high level quality...

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TRY IT !!!