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Regione Lombardia - POLIMI

FIRB 2008

FUTURO
IN RICERCA



SNAPLE



 POLITECNICO DI MILANO

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14th Winter School in eScience SINTEF

Big Data Challenges to
Modern Statistics



Statistical and Numerical techniques for Spatial Functional Data Analysis

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MODELLISTICA E CALCOLO SCIENTIFICO



MODELING AND SCIENTIFIC COMPUTING



Starting grant project SNAPLE, research team



Starting grant of Ministero dell'Istruzione dell'Università e della Ricerca

“Advanced statistical and numerical methods for the analysis of high dimensional functional data in life sciences and engineering”

SNAPLE Statistical and Numerical methods for the Analysis of Problems in Life sciences and Engineering



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PI
Statistics



PostDoc

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Numerical Analysis



PostDoc

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John A. D. Aston

Statistics





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“Advanced statistical and numerical methods for the analysis of high dimensional functional data in life sciences and engineering”



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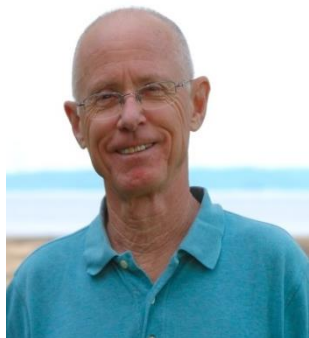
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Fabio Nobile

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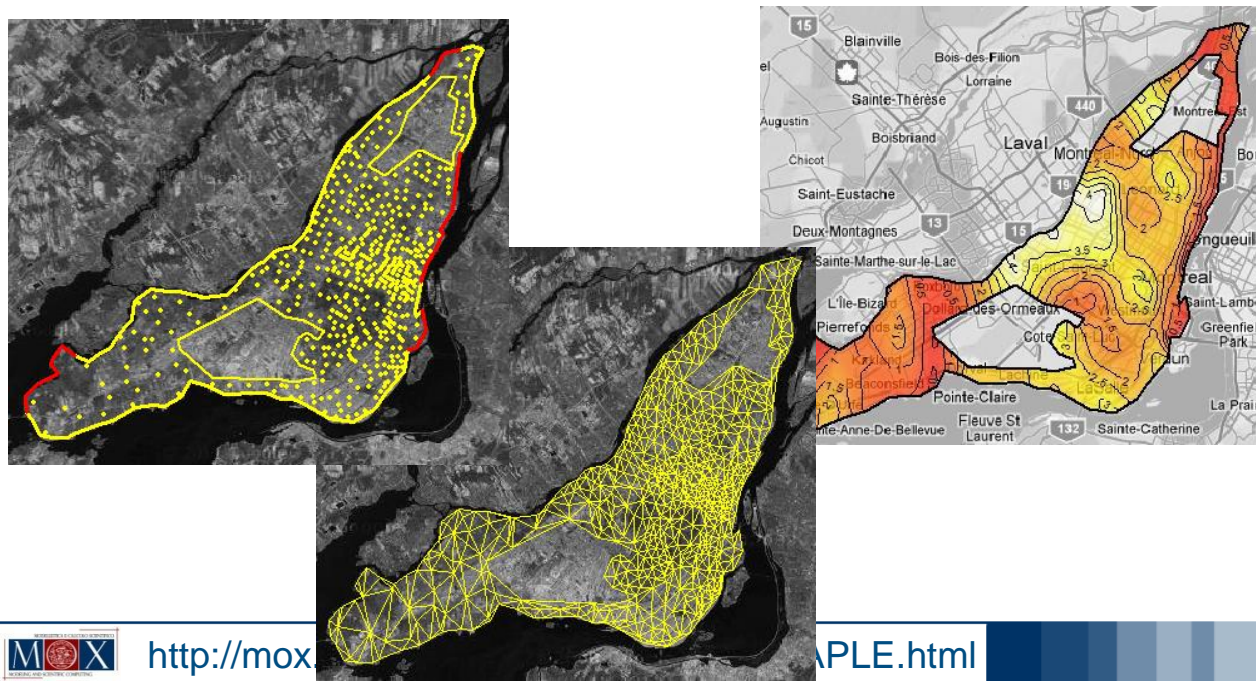


► Problem: *surface estimation* and *spatial field estimation* (spatial regression)

► We interface *statistical* methodology and *numerical analysis* techniques and propose

spatial regression models with *partial differential regularization*

→ estimation problem solved via *Finite Elements*



► Can handle data distributed over *irregular domains*

► Can comply with general conditions at domain boundaries

→ Sangalli, Ramsay, Ramsay, 2013, JRSSB



- ▶ Can incorporate **prior knowledge** about phenomenon under study allowing for very flexible modelling of space variation (**anisotropy and non-stationarity**)

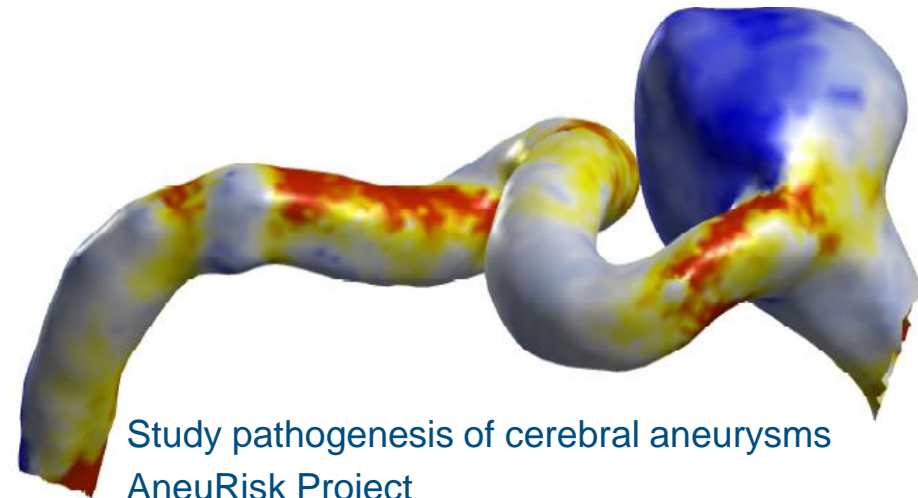
→ Azzimonti, Sangalli, Secchi, Nobile, Domanin, 2013, TechRep
 → Azzimonti, Nobile, Sangalli, Secchi, 2013, TechRep



Study pathogenesis of atherosclerotic plaques
 MMathematics for CARotid ENdarterectomy @ MOX

- ▶ Can deal with data over bi-dimensional Riemannian **manifolds**

→ Ettinger, Perotto, Sangalli, 2012, TechRep
 → Dassi, Ettinger, Perotto, Sangalli, 2013, TechRep



Study pathogenesis of cerebral aneurysms
 AneuRisk Project



► Data:

$\Omega \subset \mathbb{R}^2$: a region of interest, bounded, with $\partial\Omega \in \mathcal{C}^2$

for $i = 1, \dots, n$

▷ $\mathbf{p}_i = (x_i, y_i) \in \Omega$

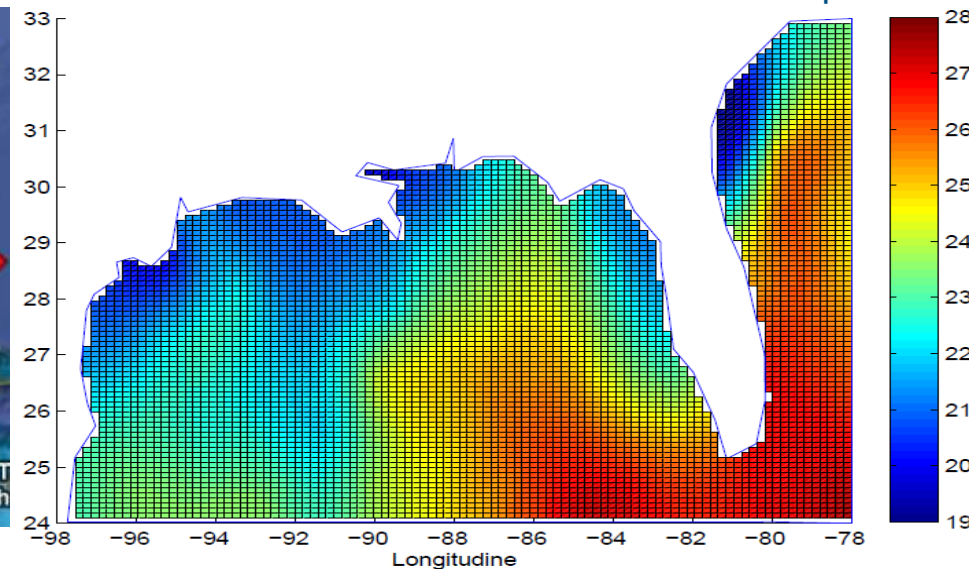
▷ z_i : a real valued variable of interest observed \mathbf{p}_i

▷ $\mathbf{w}_i = (w_{i1}, \dots, w_{iq})^t$: a q -vector of covariates associated to z_i

Buoy data (National Oceanic and Atmospheric Administration)



Estimate of water surface temperature





- ▶ Data: $\Omega \subset \mathbb{R}^2$: a region of interest, bounded, with $\partial\Omega \in \mathcal{C}^2$
 - for $i = 1, \dots, n$
 - ▷ $\mathbf{p}_i = (x_i, y_i) \in \Omega$
 - ▷ z_i : a real valued variable of interest observed \mathbf{p}_i
 - ▷ $\mathbf{w}_i = (w_{i1}, \dots, w_{iq})^t$: a q -vector of covariates associated to z_i

- ▶ Generalized Additive Model:

$$z_i = \mathbf{w}_i^t \boldsymbol{\beta} + f(\mathbf{p}_i) + \epsilon_i \quad i = 1, \dots, n$$

- ▷ $\epsilon_i, i = 1, \dots, n$, i.i.d. mean 0 and variance σ^2
- ▷ $\boldsymbol{\beta} \in \mathbb{R}^q$
- ▷ $f : \Omega \rightarrow \mathbb{R}$



- ▶ Estimate β and f minimizing

$$J_{\lambda}(\beta, f) = \sum_{i=1}^n (z_i - \mathbf{w}_i^t \beta - f(\mathbf{p}_i))^2 + \lambda \int_{\Omega} (\Delta f)^2 d\Omega$$

$$\Delta f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2}$$

Inclusion of simple Partial Differential Equations (PDE) in statistical models:

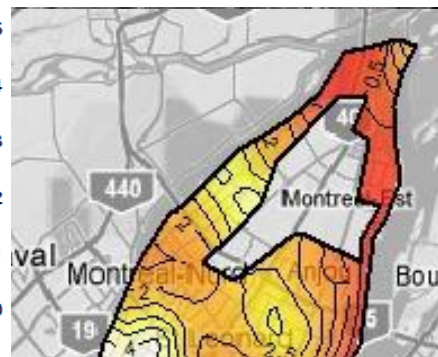
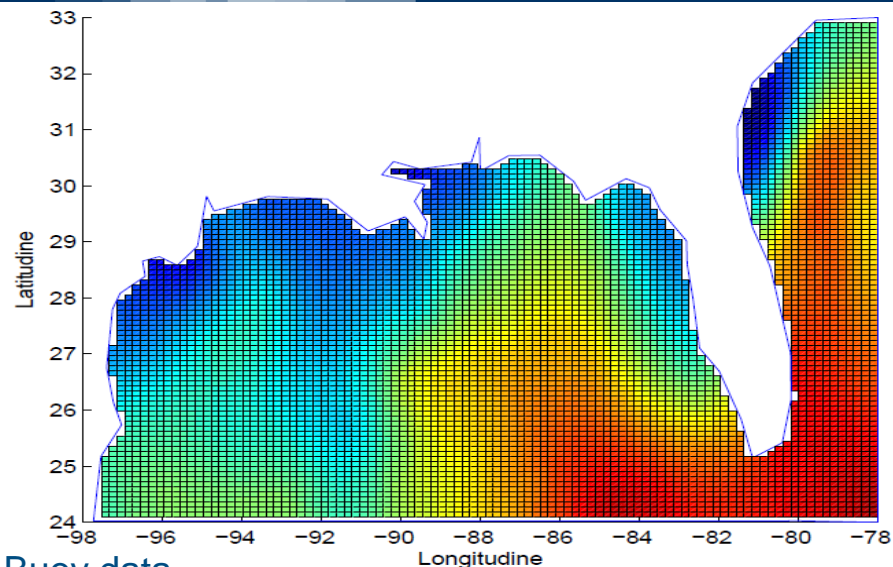
- ▶ Thin-plate splines (Wahba, 1990; Stone, 1988)

$$\sum_{i=1}^n (z_i - f(\mathbf{p}_i))^2 + \int_{\mathbb{R}^2} \left(\frac{\partial^2 f}{\partial x^2} \right)^2 + 2 \frac{\partial^2 f}{\partial x \partial y} + \left(\frac{\partial^2 f}{\partial y^2} \right)^2$$

- ▶ Bivariate Splines (Guillas and Lai, 2010)
- ▶ FEL-splines (Ramsay, 2002), Soap-film smoothing (Wood *et al.*, 2008): *irregular domains*
- ▶ Stochastic PDE: Lindgren *et al.* (2011), Bayesian inverse problems: Stuart (2010).

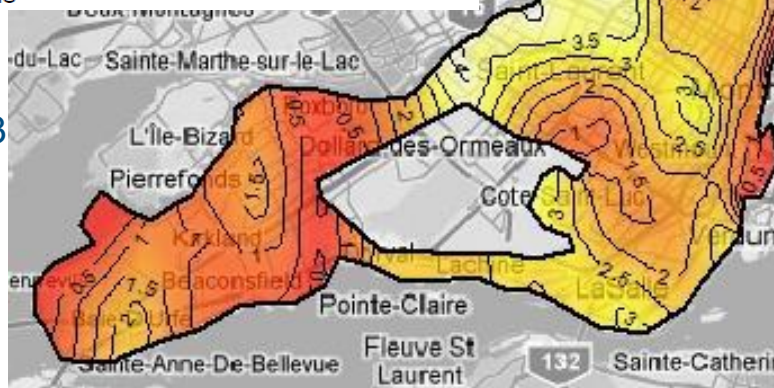


Irregularly shaped domains



Fisheries data (NOAA)

Buoy data
 (National Oceanic and Atmospheric
 Administration www.ndbc.noaa.gov)
 → Parnigoni Master thesis 2013



Census Canada data



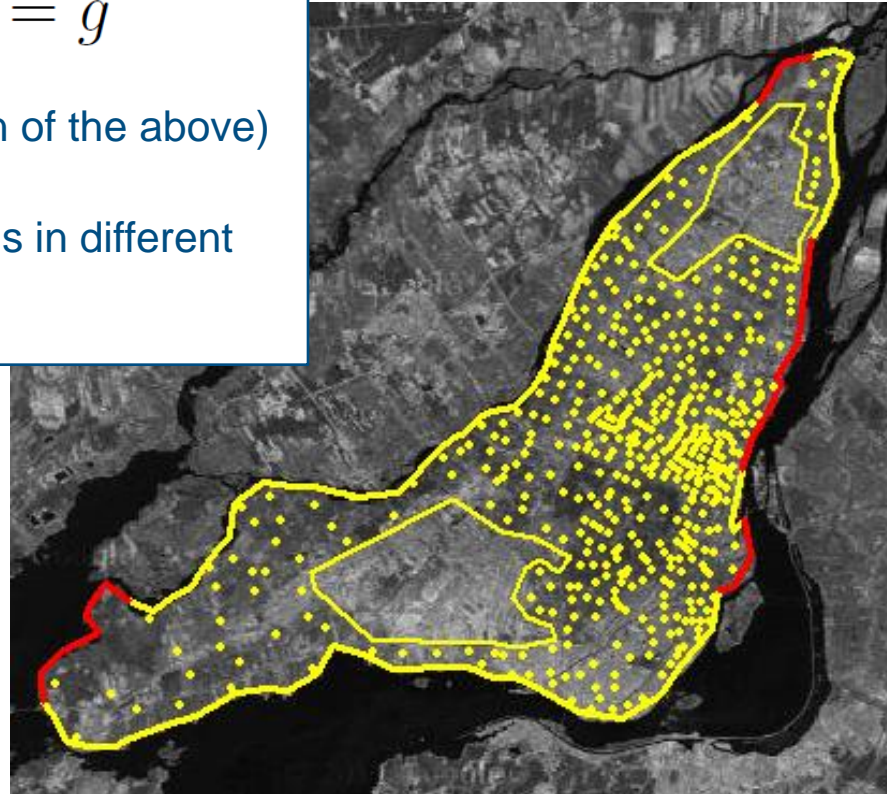
$$Cov(Z(\mathbf{p}_i), Z(\mathbf{p}_j))$$

stationarity, isotropy
 few covariance models



Boundary conditions

- Dirichlet $f|_{\partial\Omega} = g$
- Neumann $\partial_\nu f|_{\partial\Omega} = g$
- Robin (linear combination of the above)
- Mixed (different conditions in different parts of the boundary)



Census Canada data



Fisheries data (NOAA)



A priori information

Azzimonti et al., 2013a, TechRep
Azzimonti et al., 2013b, TechRep

Incorporating **a priori information**:
using PDE to model space variation
of the phenomenon

$$J_\lambda(\beta, f) = \sum_{i=1}^n (z_i - \mathbf{w}_i^t \beta - f(\mathbf{p}_i))^2 + \lambda \int_{\Omega} (Lf - u)^2 d\Omega$$

log-likelihood data fidelity
prior model fidelity

Problem specific a priori information →
(physics, mechanics, chemistry, morphology)

more complex partial differential operator
(linear second order elliptic PDE)

$$Lf = -div(K \nabla f) + \mathbf{b} \cdot \nabla f + cf$$

spatially varying

- ▶ Diffusion tensor field: *non-stationary anisotropic diffusion*
 - ▶ Transport vector field: *non-stationary directional smoothing*
 - ▶ Reaction term: *non-stationary shrinking effect*
- ▶ PDEs are commonly used to describe *complex phenomena behaviors* in many fields of engineering and sciences
- ▶ model *space variation*



A priori information

$$J_\lambda(\beta, f) = \sum_{i=1}^n (z_i - \mathbf{w}_i^t \beta - f(\mathbf{p}_i))^2 + \lambda \int_{\Omega} (Lf - u)^2 d\Omega$$

Prior (Gulf Stream)

Buoy data

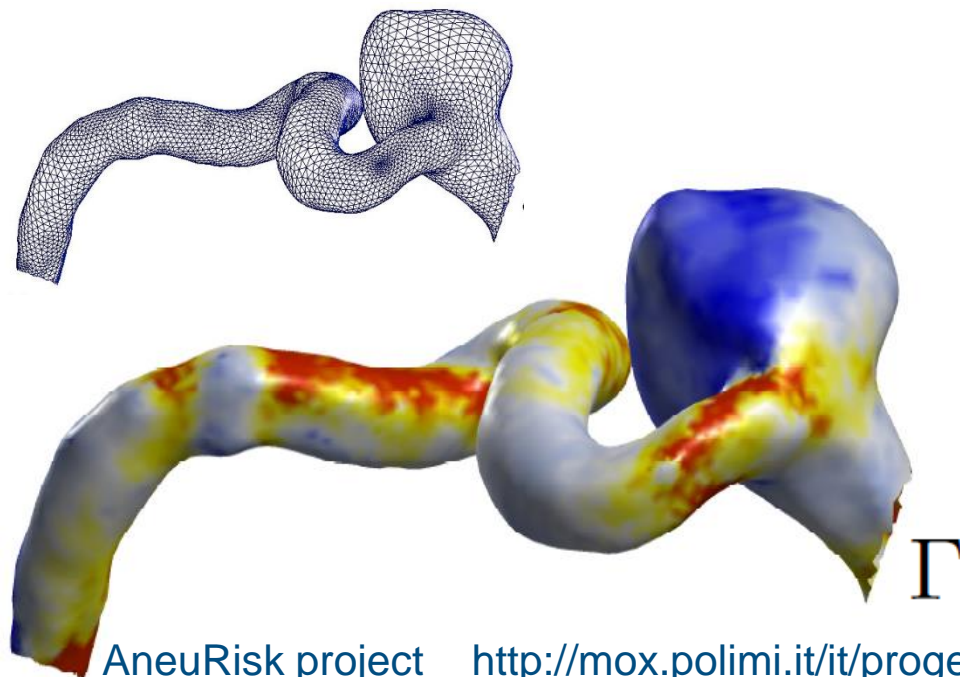




Object Oriented Data Analysis

$$J_{\Gamma, \lambda}(\boldsymbol{\beta}, f) = \sum_{i=1}^n (z_i - \mathbf{w}_i^t \boldsymbol{\beta} - f(\mathbf{x}_i))^2 + \lambda \int_{\Gamma} (\Delta_{\Gamma} f(\mathbf{x}))^2 d\mathbf{x}$$

Laplace-Beltrami operator
associated to Γ



Γ : surface embedded in \mathbb{R}^3

$\mathbf{x}_i \in \Gamma$

$f : \Gamma \rightarrow \mathbb{R}$

AneuRisk project <http://mox.polimi.it/it/progetti/aneurisk/>



► Generalized Additive Model:

$$z_i = \mathbf{w}_i^t \boldsymbol{\beta} + f(\mathbf{p}_i) + \epsilon_i \quad i = 1, \dots, n$$

$$\mathbf{z} = W \boldsymbol{\beta} + \mathbf{f}_n + \boldsymbol{\epsilon}$$

▷ $\mathbf{z} := (z_1, \dots, z_n)^t$

▷ $W := \begin{bmatrix} \mathbf{w}_1^t \\ \vdots \\ \mathbf{w}_n^t \end{bmatrix} \quad H := W(W^t W)^{-1} W^t \quad Q := I - H$

▷ $\mathbf{f}_n := (f(\mathbf{p}_1), \dots, f(\mathbf{p}_n))^t$, where f is any function on Ω

▷ $H^m(\Omega)$: set of functions in $L^2(\Omega)$ having all weak derivatives up to order m in $L^2(\Omega)$

▷ $H_{n0}^m(\Omega)$: subset of $H^m(\Omega)$ consisting of functions whose normal deriv are 0 on the boundary of Ω
($H^m(\Omega)$ + Neumann b.c.)



Proposition

$$J_\lambda(\beta, f) = \sum_{i=1}^n (z_i - \mathbf{w}_i^t \beta - f(\mathbf{p}_i))^2 + \lambda \int_{\Omega} (\Delta f)^2 d\Omega$$

The estimators $\hat{\beta} \in \mathbb{R}^q$ and $\hat{f} \in H_{n0}^2(\Omega)$ exist unique

$$(\star) \quad \hat{\beta} = (W^t W)^{-1} W^t (\mathbf{z} - \hat{\mathbf{f}}_n)$$

($\star\star$) \hat{f} satisfies

$$\mathbf{u}_n^t Q \hat{\mathbf{f}}_n + \lambda \int_{\Omega} (\Delta u)(\Delta \hat{f}) = \mathbf{u}_n^t Q \mathbf{z} \quad \text{for all } u \in H_{n0}^2(\Omega)$$

▷ *Weak formulation:* find $(\hat{f}, g) \in (H^1(\Omega) \cap C^0(\Omega)) \times H^1(\Omega)$ such that

$$\mathbf{u}_n^t Q \hat{\mathbf{f}}_n - \lambda \int_{\Omega} (\nabla u \cdot \nabla g) = \mathbf{u}_n^t Q \mathbf{z}$$

$$\int_{\Omega} v g - \int_{\Omega} (\nabla v \cdot \nabla \hat{f}) = 0$$

for all $(u, v) \in (H^1(\Omega) \cap C^0(\Omega)) \times H^1(\Omega)$.

Thanks to the regularity of the problem, \hat{f} belongs to $H_{n0}^2(\Omega)$.



Triangulation and basis functions

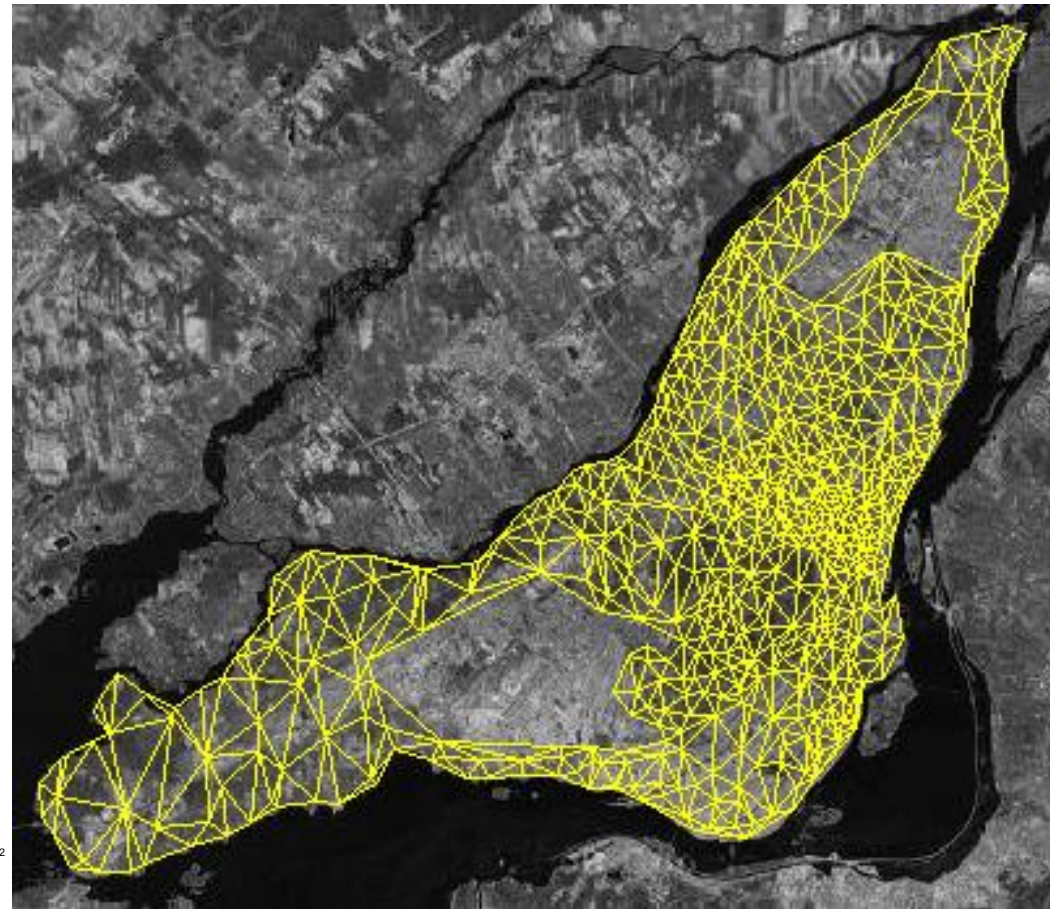
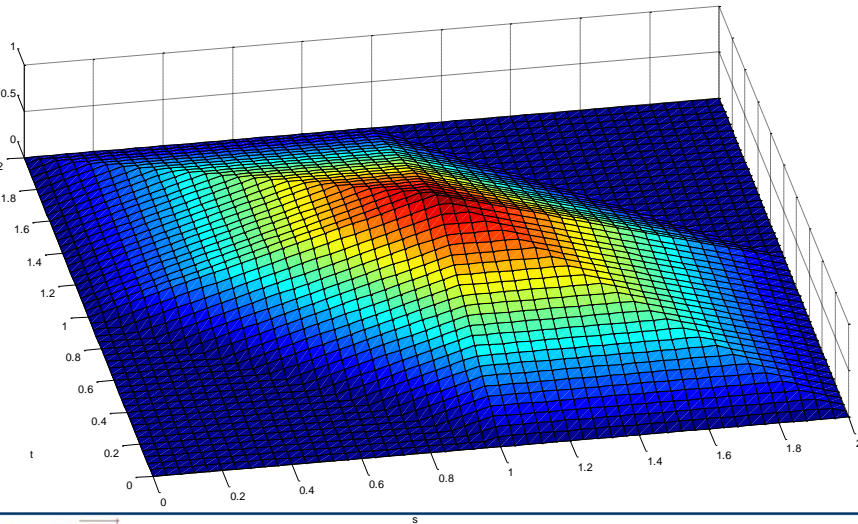
Infinite-dimensional problem

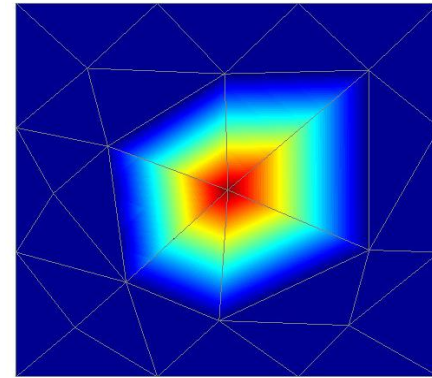
Basis expansion
Finite Elements

Finite-dimensional problem

Finite element analysis has been mainly developed and used in engineering applications, to solve partial differential equations

Finite element space: space of continuous piecewise-polynomial surfaces over a triangulation \mathcal{T} of Ω





- ▷ $\{\xi_1, \dots, \xi_K\}$: nodes of \mathcal{T}
- ▷ $\Omega_{\mathcal{T}}$: triangulated domain; $H_{\mathcal{T}}^1(\Omega)$: finite element space
- ▷ $\psi = (\psi_1, \dots, \psi_K)^t$: finite element basis $\Psi = \{\Psi\}_{ij} := \psi_j(\mathbf{p}_i)$
- ▷ for any g in the finite element space, $g = \mathbf{g}^t \psi$ where $\mathbf{g} := (g(\xi_1), \dots, g(\xi_K))^t$
- ▷ $R_0 := \int_{\Omega_{\mathcal{T}}} (\psi \psi^t)$ $R_1 := \int_{\Omega_{\mathcal{T}}} (\psi_x \psi_x^t + \psi_y \psi_y^t)$

Corollary. The estimators $\hat{\beta} \in \mathbb{R}^q$ and $\hat{f} \in H_{\mathcal{T}}^1(\Omega)$, that solve the discrete counterpart of the estimation problem, exist unique

- ▷ $\hat{\beta} = (W^t W)^{-1} W^t (z - \hat{\mathbf{f}}_n)$
- ▷ $\hat{f} = \hat{\mathbf{f}}^t \psi$, with $\hat{\mathbf{f}}$ satisfying

$$\begin{bmatrix} -\Psi^t Q \Psi & \lambda R_1 \\ \lambda R_1 & \lambda R_0 \end{bmatrix} \begin{bmatrix} \mathbf{f} \\ \mathbf{g} \end{bmatrix} = \begin{bmatrix} -\Psi^t Q z \\ \mathbf{0} \end{bmatrix}$$



- ▶ $\hat{\beta}$ and \hat{f} are linear in \mathbf{z} → *linear estimators*

\hat{f} has typical penalized regression form, being identified by

$$\hat{\mathbf{f}}_n = (\Psi^t Q \Psi + \lambda P)^{-1} \Psi^t Q \mathbf{z}$$

- ▶ Classical inferential tools are readily derived

- ▷ mean and variances of $\hat{\beta}$ and \hat{f}

- ▷ confidence intervals for β

- ▷ confidence bands for f

- ▷ *prediction intervals for new observations*

- ▷ estimate of error variance σ^2

$$J_\lambda(\beta, f) = \sum_{i=1}^n (z_i - \mathbf{w}_i^t \beta - f(\mathbf{p}_i))^2 + \lambda \int_{\Omega} (\Delta f)^2 d\Omega$$

- ▷ selection of smoothing parameter λ via generalized cross-validation



Two sources of bias:

- ▷ $\hat{f} \in H_{\mathcal{T}}^1(\Omega)$ is affected by bias due to discretization:

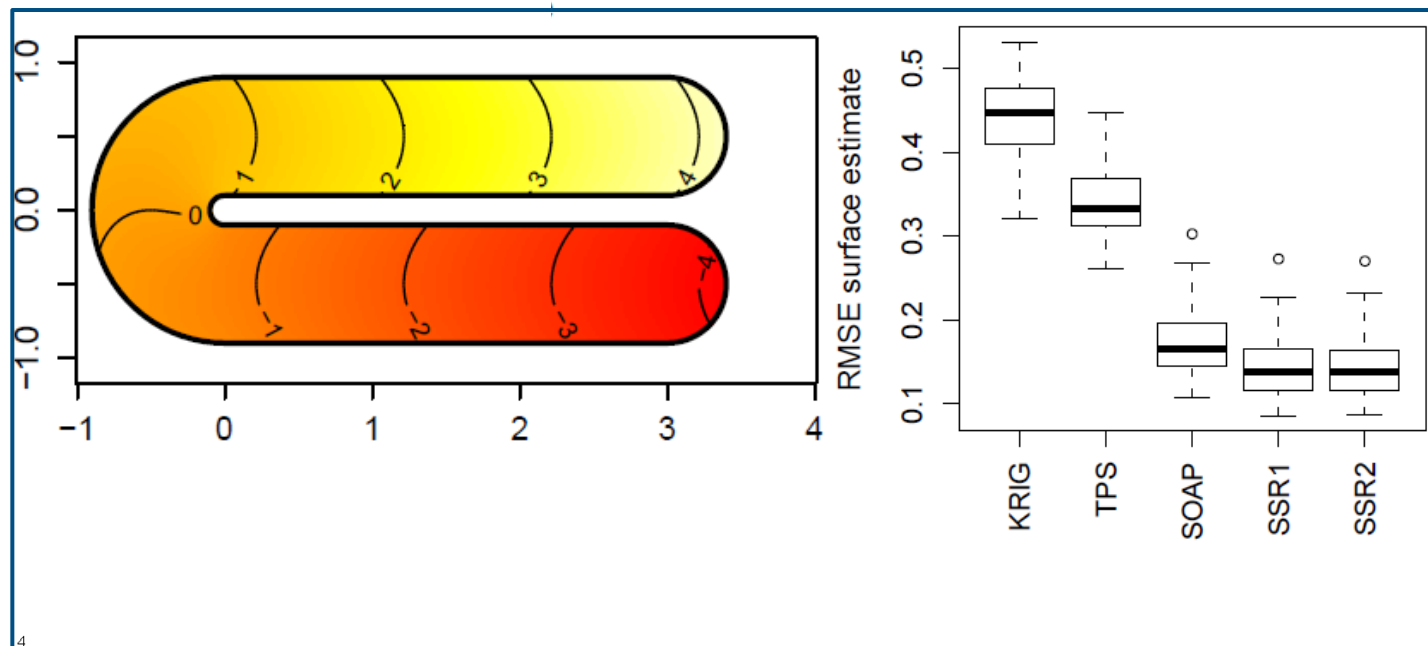
This bias disappears as $n \rightarrow \infty$ with $h \rightarrow 0$

- ▷ $\hat{f} \in H_{n_0}^2(\Omega)$ and $\hat{f} \in H_{\mathcal{T}}^1(\Omega)$ are affected by bias due to regularization

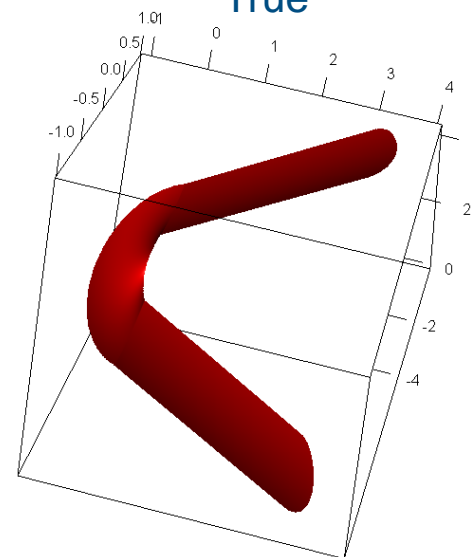
This bias disappears as $n \rightarrow \infty$ with $\lambda \rightarrow 0$



Simulation studies (Sangalli et al. 2013) show that the proposed models outperforms thin-plate splines, filtered kriging and other state-of-the-art methods for spatially distributed data.

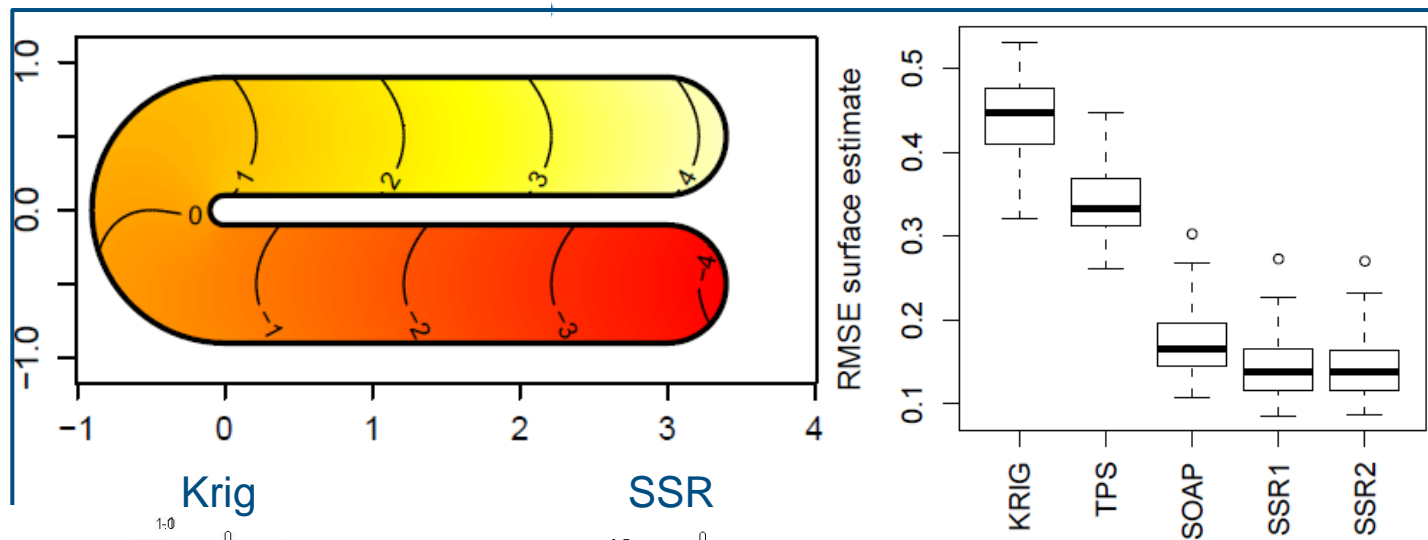


True





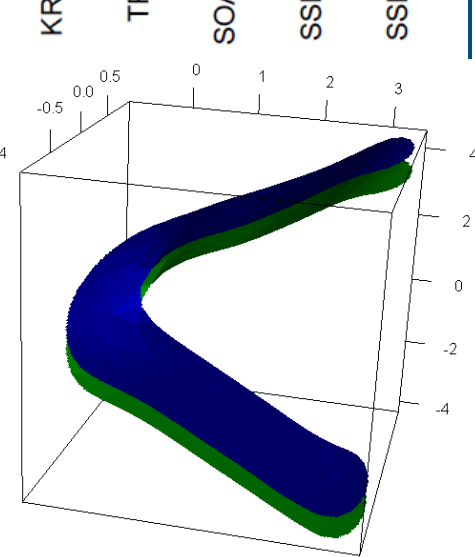
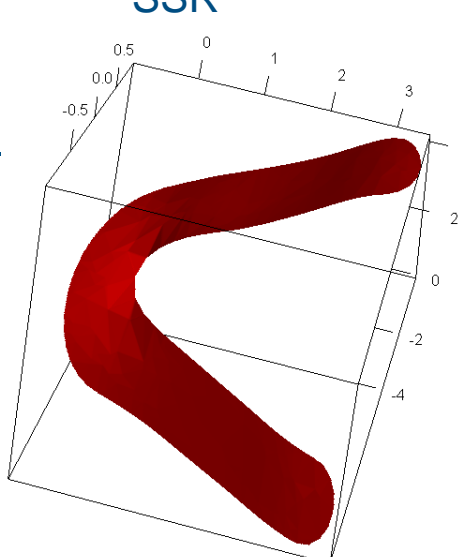
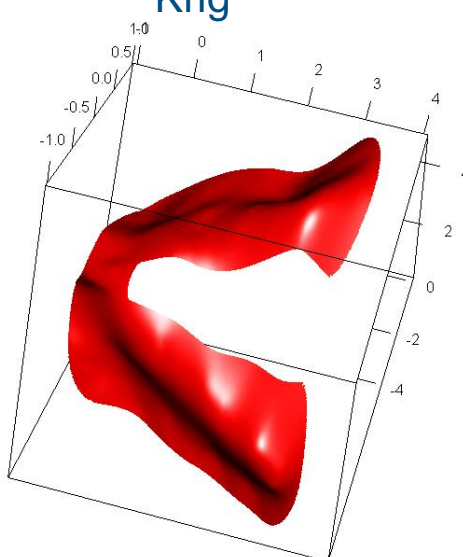
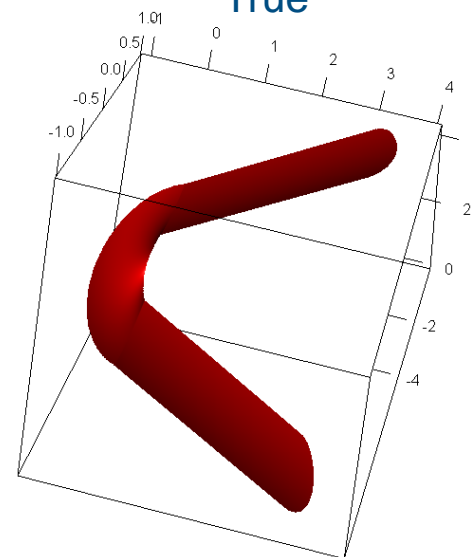
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True

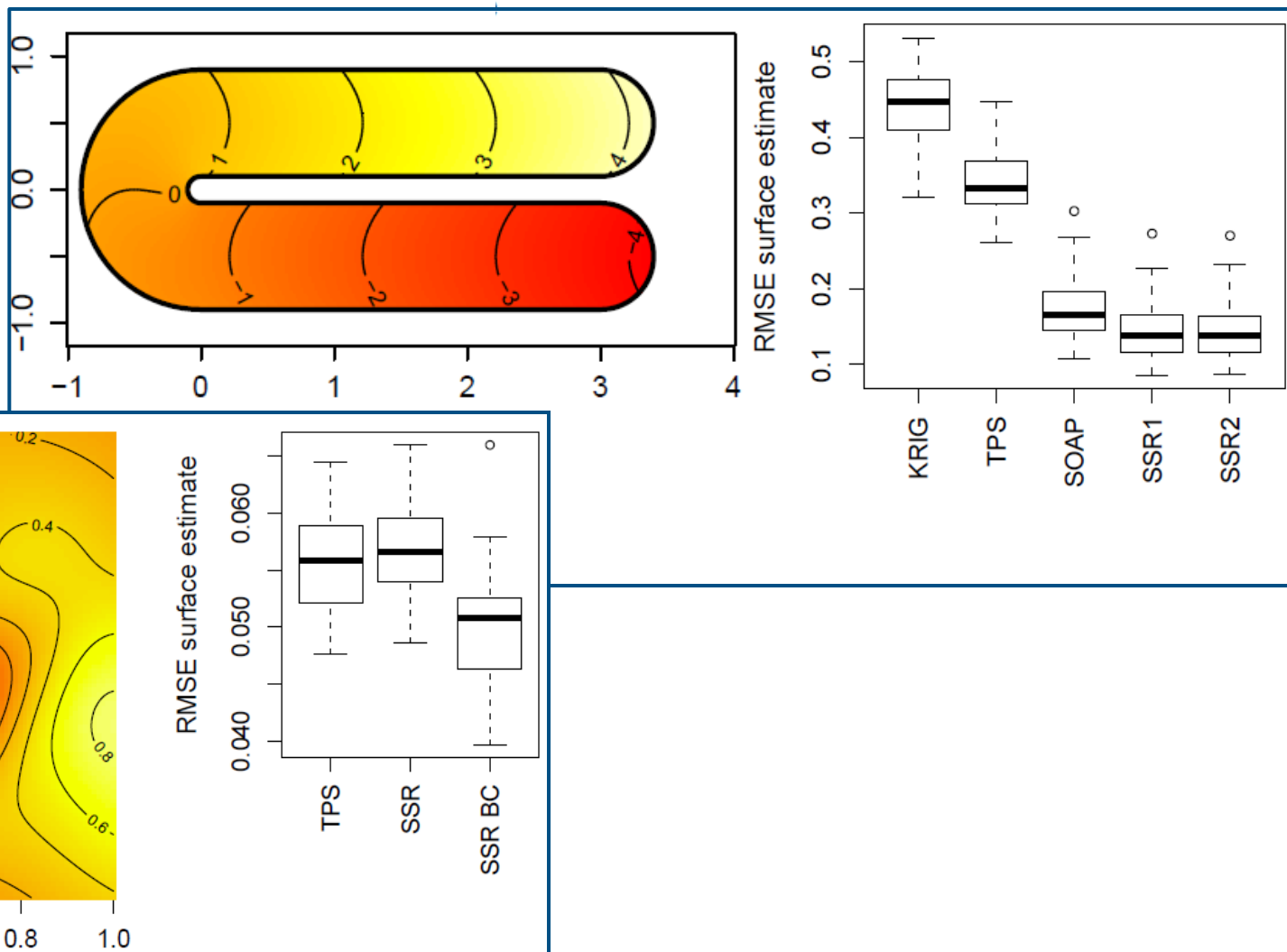
Krig

SSR





Simulation studies (Sangalli et al. 2013) show that the proposed models outperforms thin-plate splines, filtered kriging and other state-of-the-art methods for spatially distributed data.





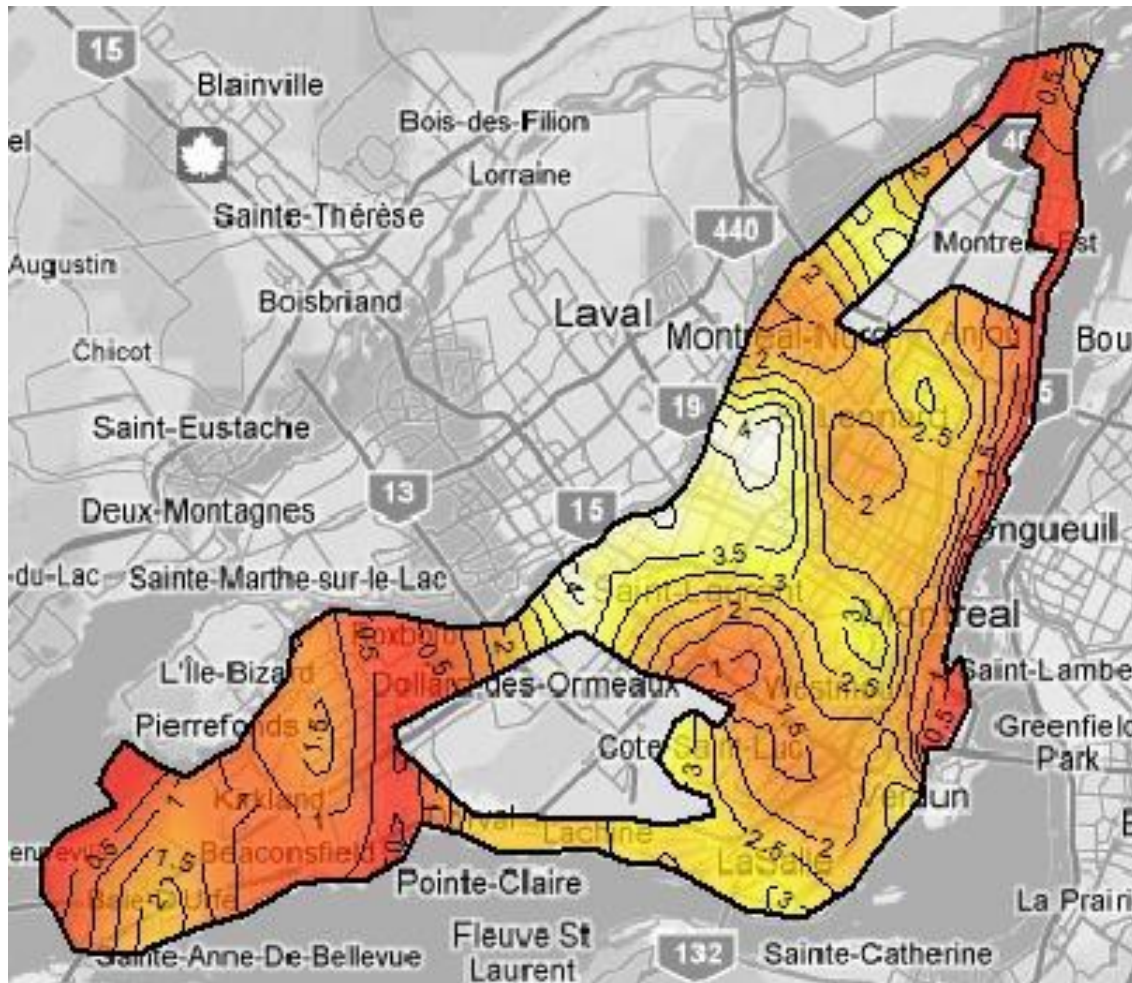
Illustrative example: Island of Montreal census data



- ▷ p_i : centroids of census tracts
- ▷ z_i : population density
(1000 inhabitants per km^2)
- ▷ w_i : indicator of residential (1)
commercial (0) census tract
- ▶ Mixed b.c. (homogeneous Neumann
and homogeneous Dirichlet)



Illustrative example: Island of Montreal census data



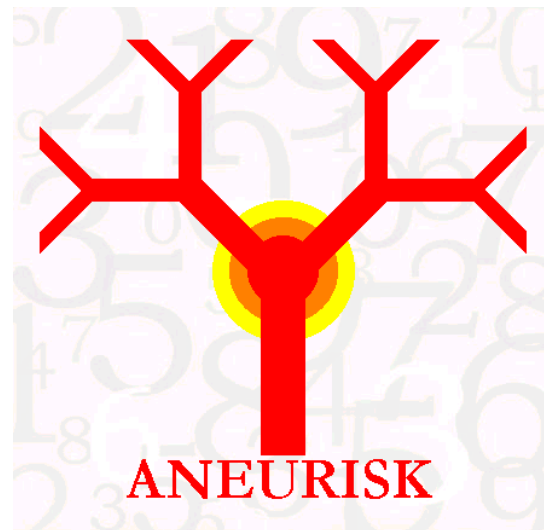
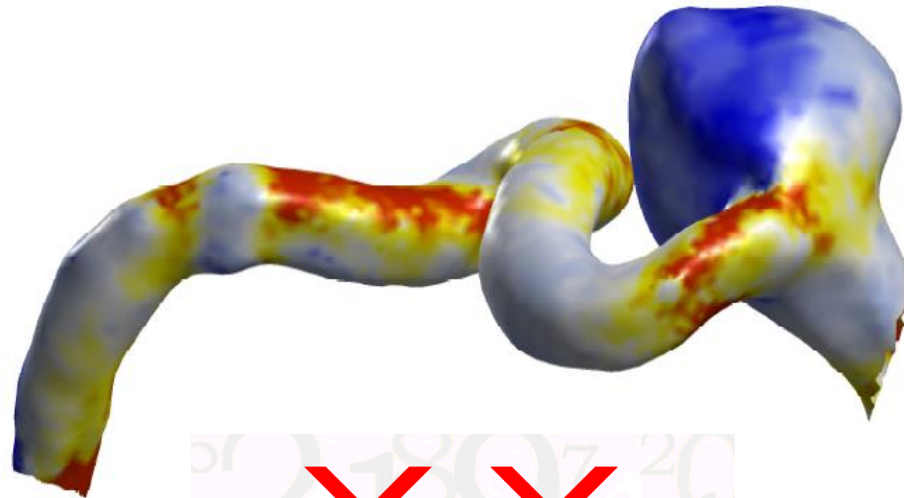
$$\hat{\beta} = 1.300$$

approx. 95% confidence interval [0.755; 1.845]



Motivating applied problem: AneuRisk project

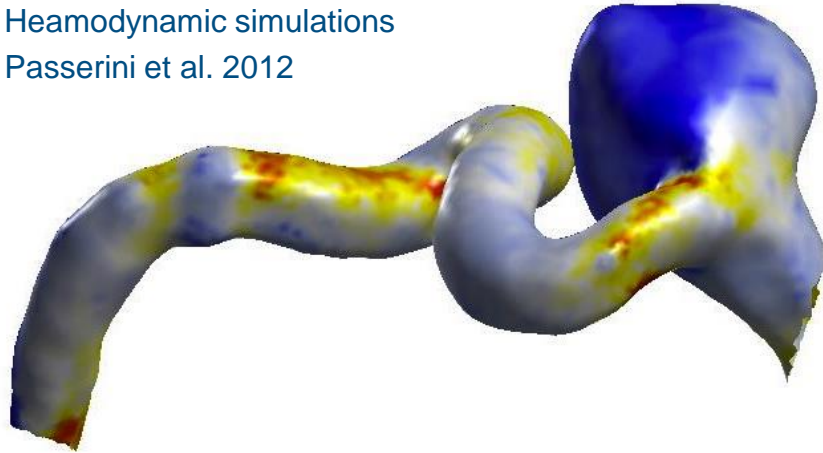
Spatial regression over bi-dimensional
Riemannian manifold domains



<http://mox.polimi.it/it/progetti/aneurisk>



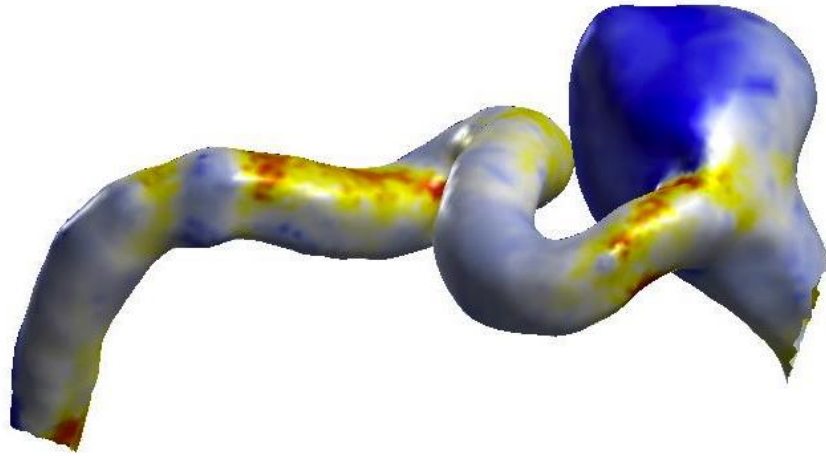
Heamodynamic simulations
Passerini et al. 2012



Object Oriented Data Analysis

- ▷ $\Gamma \subset \mathbb{R}^3$ - a non-planar surface domain
Artery wall
- ▷ $\{\mathbf{x}_i = (x_{1i}, x_{2i}, x_{3i}) \in \Gamma\}$ - data locations
- ▷ $z_i \in \mathbb{R}$ - variable of interest observed at \mathbf{x}_i
Wall shear stress modulus at systolic peak
- ▷ $\mathbf{w}_i = (w_{i1}, \dots, w_{iq}) \in \mathbb{R}^q$ - space varying covariates
Local curvature of vessel wall
Curvature of vessel
Local radius of the vessel

- ▶ Nearest Neighbor Averaging
Hagler, Saygin, Sereno, 2006, *NeuroImage*
- ▶ Heat Kernel Smoothing
Chung et al., 2005, *NeuroImage*
- ▶ Methods for data over spheres, hyperspheres and other manifolds
Baramidze, Lai, Shum, 2006, *SIAM J.S.C.*
Wahba, 1981, *SIAM J.S.C.*
Lindgren, Rue, Lindstrom, 2011, *JRSSB*
Gneiting, 2013, *Bernoulli*

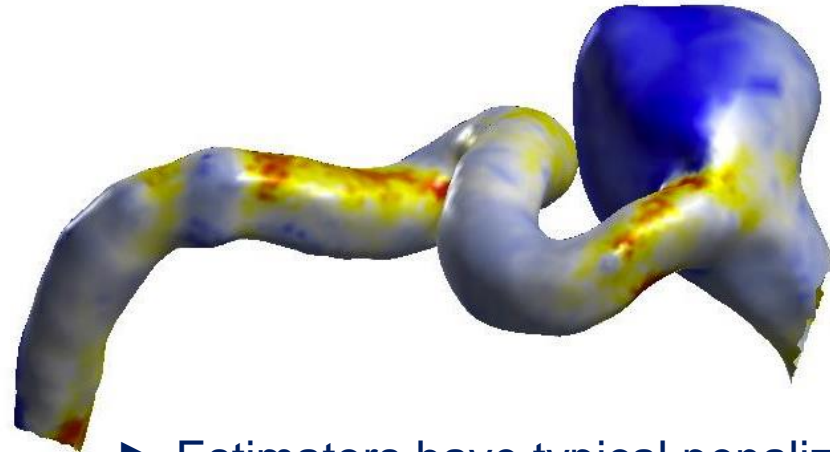


$$z_i = \mathbf{w}_i^t \boldsymbol{\beta} + f(\mathbf{x}_i) + \epsilon_i \quad i = 1, \dots, n$$

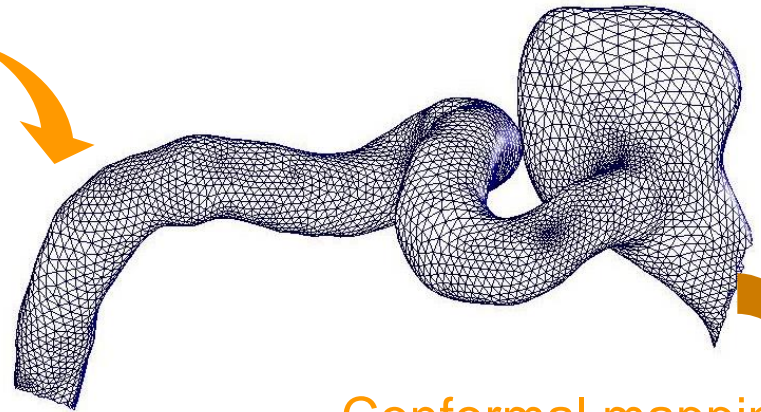
$$J_{\Gamma, \lambda}(\boldsymbol{\beta}, f) = \sum_{i=1}^n (z_i - \mathbf{w}_i^t \boldsymbol{\beta} - f(\mathbf{x}_i))^2 + \lambda \int_{\Gamma} (\Delta_{\Gamma} f(\mathbf{x}))^2 d\mathbf{x}$$



Spatial regression over Riemannian manifolds

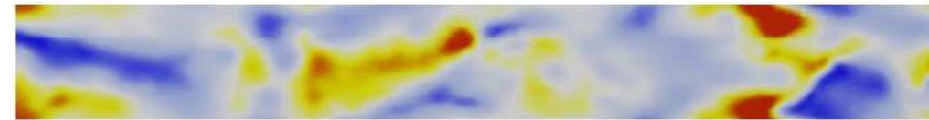
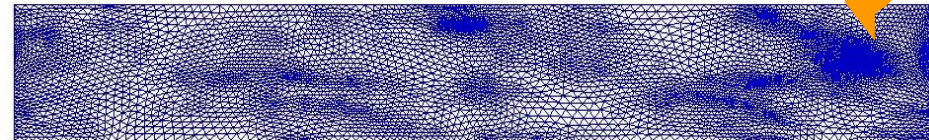


- ▶ Estimators have typical penalized regression form
- ▶ Linear in observed data values
- ▶ Classical inferential tools



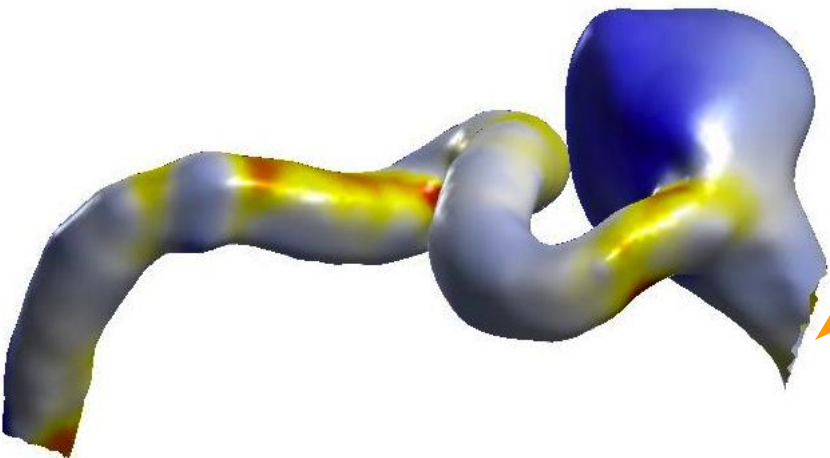
Conformal mapping

(fully encode information about complex 3D geometry)



Equivalent estimation problem on planar domain

→ Extend method for planar domains

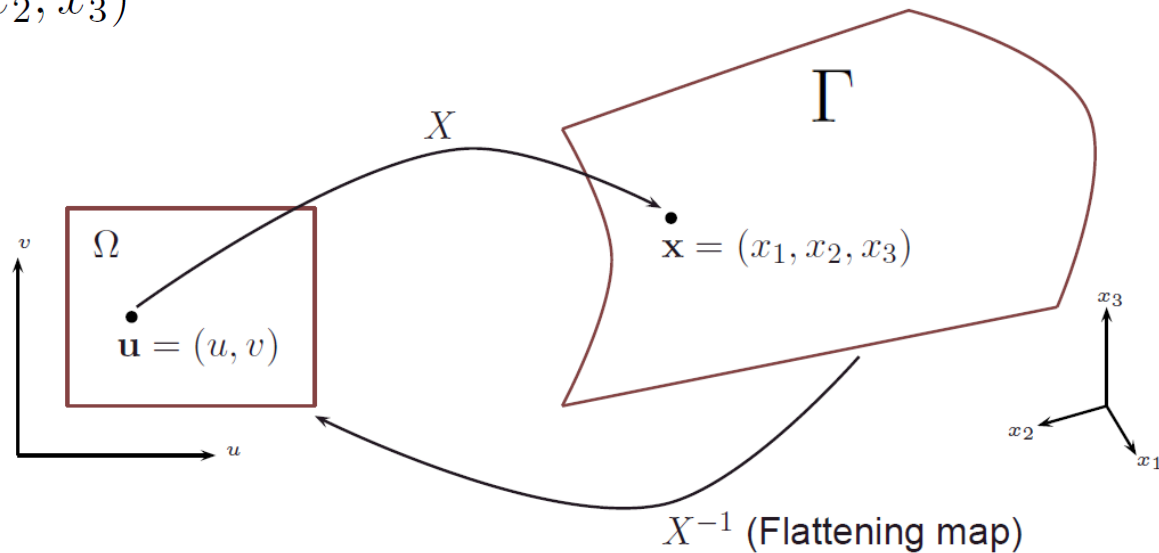




▷ $X : \Omega \rightarrow \Gamma$

(Ω : open, convex, bounded set in \mathbb{R}^2)

$$\mathbf{u} = (u, v) \mapsto \mathbf{x} = (x_1, x_2, x_3)$$





- ▷ $\frac{\partial X}{\partial u}(\mathbf{u}), \frac{\partial X}{\partial v}(\mathbf{u})$: column vectors
- ▷ space varying metric tensor:

$$G(\mathbf{u}) := \nabla X(\mathbf{u})' \nabla X(\mathbf{u}) = \begin{pmatrix} \left\| \frac{\partial X}{\partial u}(\mathbf{u}) \right\|^2 & \left\langle \frac{\partial X}{\partial u}(\mathbf{u}), \frac{\partial X}{\partial v}(\mathbf{u}) \right\rangle \\ \left\langle \frac{\partial X}{\partial u}(\mathbf{u}), \frac{\partial X}{\partial v}(\mathbf{u}) \right\rangle & \left\| \frac{\partial X}{\partial v}(\mathbf{u}) \right\|^2 \end{pmatrix}$$

- ▷ $\mathcal{W}(\mathbf{u}) := \sqrt{\det(G(\mathbf{u}))}$;

$$\mathcal{W}(\mathbf{u}) d\mathbf{u} = d\mathbf{x}$$

- ▷ $\mathbf{K}(\mathbf{u}) = \mathcal{W}(\mathbf{u}) G^{-1}(\mathbf{u})$

- ▷ For $f \circ X \in \mathcal{C}^2(\Omega)$,

$$\mathbf{u} = X^{-1}(\mathbf{x})$$

$$\nabla_{\Gamma} f(\mathbf{x}) = \nabla X(\mathbf{u}) G^{-1}(\mathbf{u}) (\nabla f(X(\mathbf{u})))$$

$$\Delta_{\Gamma} f(\mathbf{x}) = \operatorname{div}_{\Gamma}(\nabla_{\Gamma} f(X(\mathbf{u}))) = \frac{1}{\mathcal{W}(\mathbf{u})} \operatorname{div}(\mathbf{K}(\mathbf{u}) \nabla f(X(\mathbf{u})))$$



$$\triangleright H_{n0,\mathbf{K}}^m(\Omega) = \{h \in H^m(\Omega) : \mathbf{K}\nabla h \cdot \mathbf{n} = 0 \text{ on } \partial\Omega\} \subset H^m(\Omega)$$

Equivalent estimation problem over the planar domain Ω

Find $\beta \in \mathbb{R}^q$ and f with $(f \circ X) \in H_{n0,\mathbf{K}}^2(\Omega)$ that minimizes

$$J_{\Omega,\lambda}(\beta, f \circ X) = \sum_{i=1}^n (z_i - \mathbf{w}'_i \beta - f(X(\mathbf{u}_i)))^2 + \lambda \int_{\Omega} \frac{1}{\mathcal{W}} \left(\text{div}(\mathbf{K}\nabla(f \circ X)) \right)^2 d\Omega$$

where $\mathbf{u}_i = X^{-1}(\mathbf{x}_i)$

For conformal maps, i.e. $\left\| \frac{\partial X}{\partial \mathbf{u}}(\mathbf{u}) \right\|^2 = \left\| \frac{\partial X}{\partial \mathbf{v}}(\mathbf{u}) \right\|^2$ and $\left\langle \frac{\partial X}{\partial u}(\mathbf{u}), \frac{\partial X}{\partial v}(\mathbf{u}) \right\rangle = 0 \forall \mathbf{u} \in \Omega$,

$$J_{\Omega,\lambda}(\beta, f \circ X) = \sum_{i=1}^n (z_i - \mathbf{w}'_i \beta - f(X(\mathbf{u}_i)))^2 + \lambda \int_{\Omega} \left(\frac{1}{\sqrt{\mathcal{W}(\mathbf{u})}} \Delta f(X(\mathbf{u})) \right)^2 d\Omega$$



$$\triangleright H_{n0, \mathbf{K}}^m(\Omega) = \{h \in H^m(\Omega) : \mathbf{K} \nabla h \cdot n = 0 \text{ on } \partial\Omega\} \subset H^m(\Omega)$$

Equivalent estimation problem over the planar domain Ω

Find $\beta \in \mathbb{R}^q$ and f with $(f \circ X) \in H_{n0, \mathbf{K}}^2(\Omega)$ that minimizes

$$J_{\Omega, \lambda}(\beta, f \circ X) = \sum_{i=1}^n (z_i - \mathbf{w}'_i \beta - f(X(\mathbf{u}_i)))^2 + \lambda \int_{\Omega} \frac{1}{W} \left(\operatorname{div}(\mathbf{K} \nabla (f \circ X)) \right)^2 d\Omega$$

where $\mathbf{u}_i = X^{-1}(\mathbf{x}_i)$

→ Extend method for planar domains



Proposition. The estimators $\hat{\beta} \in \mathbb{R}^q$ and $\hat{f} \in H_{n0, \mathbf{K}}^2(\Omega)$ exist unique

$$(*) \quad \hat{\beta} = (W^t W)^{-1} W^t (\mathbf{z} - \hat{\mathbf{f}}_n)$$

(**) \hat{f} satisfies

$$\mu_n^t \mathbf{Q} \hat{\mathbf{f}}_n + \lambda \int_{\Omega} \frac{1}{\mathcal{W}} \left(\operatorname{div}(\mathbf{K} \nabla(\mu \circ X)) \right) \left(\operatorname{div}(\mathbf{K} \nabla(\hat{f} \circ X)) \right) d\Omega = \mu_n^t \mathbf{Q} \mathbf{z}$$

for any μ defined on Γ such that $\mu \circ X \in H_{n0, \mathbf{K}}^2(\Omega)$.

▷ Weak formulation:

Find $(\hat{f} \circ X, \gamma \circ X) \in (H_{n0, \mathbf{K}}^1(\Omega) \cap C^0(\bar{\Omega})) \times H^1(\Omega)$ such that

$$\mu_n^t \mathbf{Q} \hat{\mathbf{f}}_n - \lambda \int_{\Omega} \mathbf{K} \nabla(\mu \circ X) \cdot \nabla(\gamma \circ X) d\Omega = \mu_n^t \mathbf{Q} \mathbf{z}$$

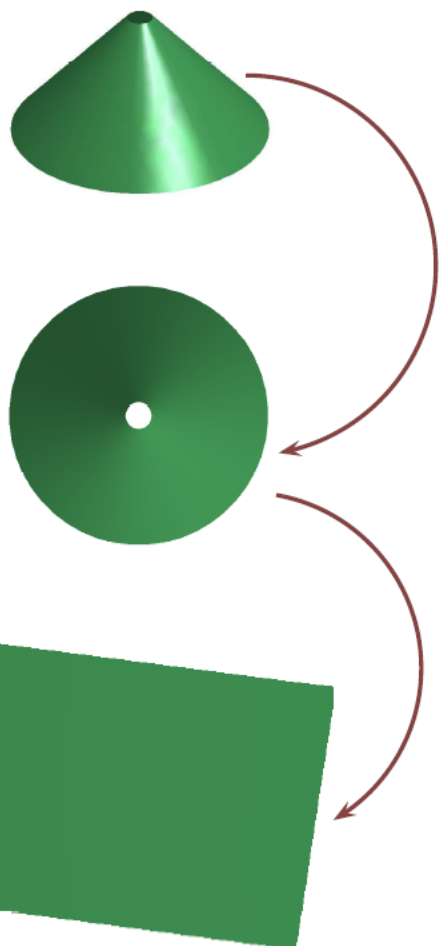
$$\int_{\Omega} (\xi \circ X)(\gamma \circ X) \mathcal{W} d\Omega + \int_{\Omega} \nabla(\xi \circ X) \mathbf{K} \nabla(\hat{f} \circ X) d\Omega = 0$$

for any $(\mu \circ X, \xi \circ X) \in (H_{n0, \mathbf{K}}^1(\Omega) \cap C^0(\bar{\Omega})) \times H^1(\Omega)$.

Thanks to the regularity of the problem, $\hat{f} \circ X$ still belongs to $H_{n0, \mathbf{K}}^2(\Omega)$.



Conformal parametrization



$$\begin{cases} -\Delta_{\Sigma} u = 0 \text{ on } \Sigma \\ u = 0 \text{ on } \sigma_0 \\ u = 1 \text{ on } \sigma_1 \end{cases}$$

$$E_D(u) = \frac{1}{2} \int_{\Gamma} \|\nabla_{\Gamma} u\|^2 d\Gamma$$

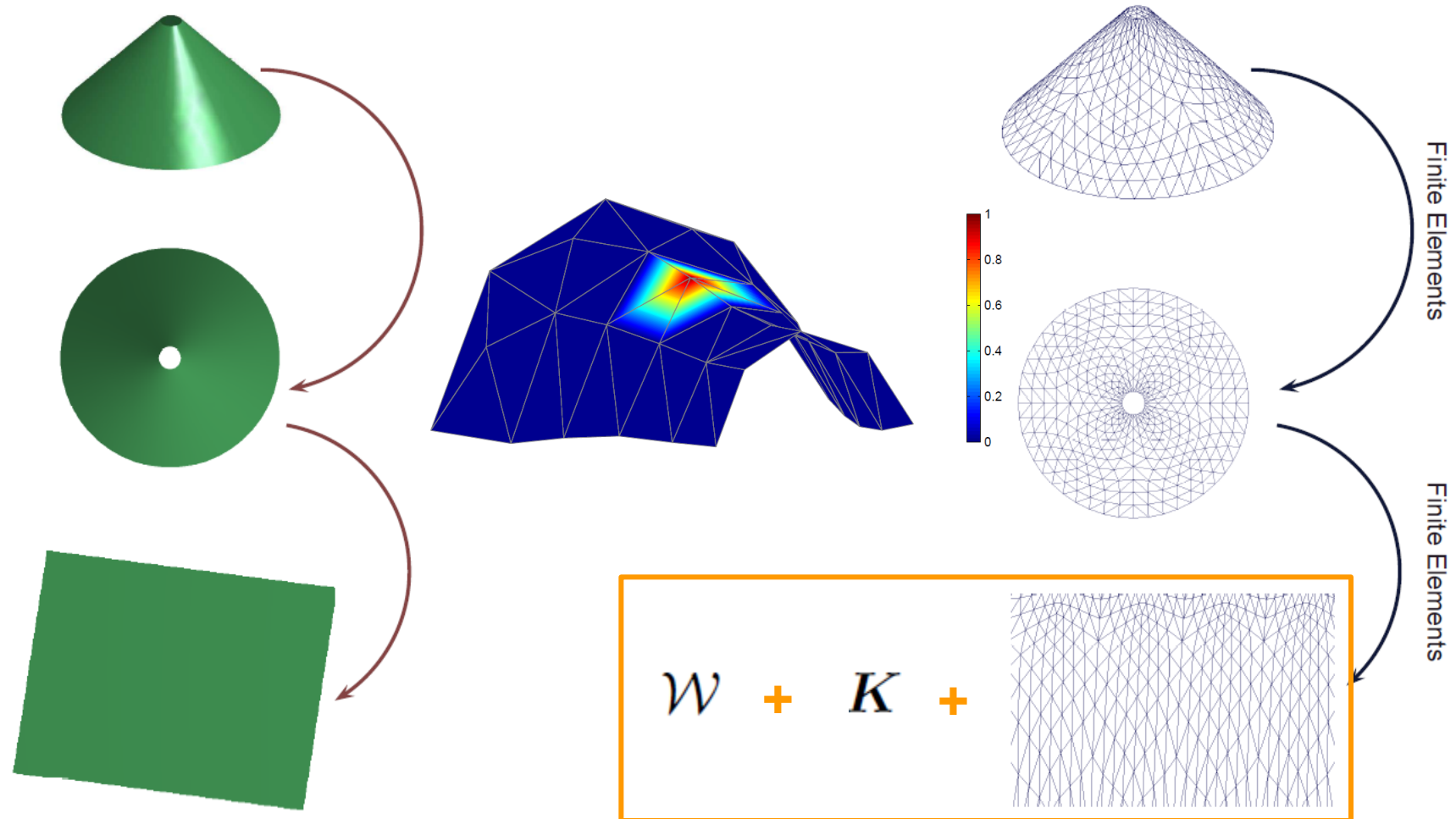
$$\begin{cases} -\Delta_{\Sigma} v = 0 \text{ on } \Sigma \\ v(\zeta) = \int_{\zeta_0}^{\zeta} \frac{\partial u}{\partial v} ds \text{ on } B \end{cases}$$

$$E_D(v) = \frac{1}{2} \int_{\Gamma} \|\nabla_{\Gamma} v\|^2 d\Gamma$$

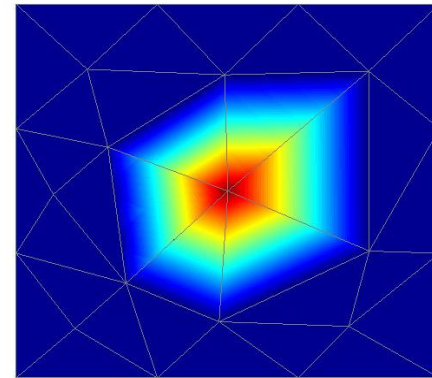
Haker et al, 2000, *IEEE Trans. Med. Imag*



Conformal parametrization



Haker et al, 2000, *IEEE Trans. Med. Imag*



- ▷ $\{\xi_1, \dots, \xi_K\}$: nodes of planar triangulation \mathcal{T}
- ▷ $\Omega_{\mathcal{T}}$: planar triangulated domain; $H_{\mathcal{T}}^1(\Omega)$: finite element space
- ▷ $\psi = (\psi_1, \dots, \psi_K)^t$: finite element basis $\Psi = \{\Psi\}_{ij} := \psi_j(\mathbf{p}_i)$
- ▷ for any h in the finite element space, $h = \mathbf{h}^t \psi$ where $\mathbf{h} := (h(\xi_1), \dots, h(\xi_K))^t$
- ▷ $R_0 := \int_{\Omega_{\mathcal{T}}} (\psi \psi^t) \mathcal{W}$ $R_1 := \int_{\Omega_{\mathcal{T}}} \nabla \psi' \mathbf{K} \nabla \psi$

Corollary. The estimators $\hat{\beta} \in \mathbb{R}^q$ and $\hat{f} \in H_{\mathcal{T}}^1(\Omega)$, that solve the discrete counterpart of the estimation problem, exist unique

- ▷ $\hat{\beta} = (W^t W)^{-1} W^t (z - \hat{\mathbf{f}}_n)$
- ▷ $\hat{f} = \hat{\mathbf{f}}^t \psi$, with $\hat{\mathbf{f}}$ satisfying

$$\begin{bmatrix} -\Psi^t Q \Psi & \lambda R_1 \\ \lambda R_1 & \lambda R_0 \end{bmatrix} \begin{bmatrix} \mathbf{f} \\ \mathbf{g} \end{bmatrix} = \begin{bmatrix} -\Psi^t Q z \\ \mathbf{0} \end{bmatrix}$$



Simulation (without covariates)

TRUE



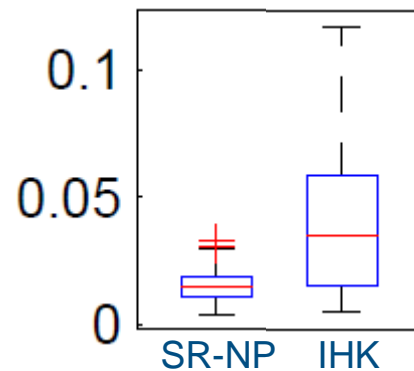
TRUE + NOISE



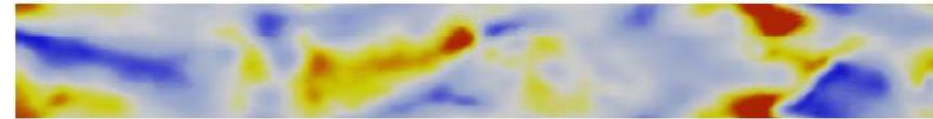
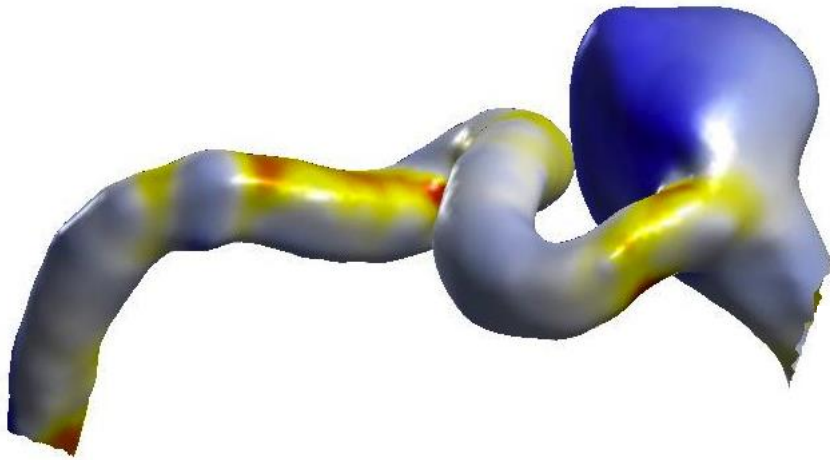
ESTIMATE



RMSE

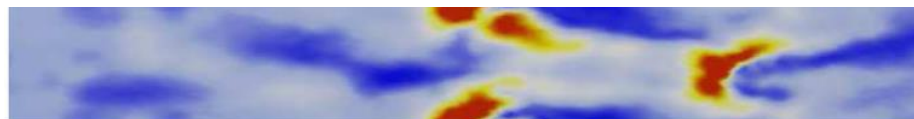
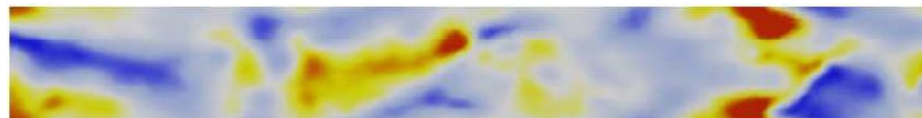
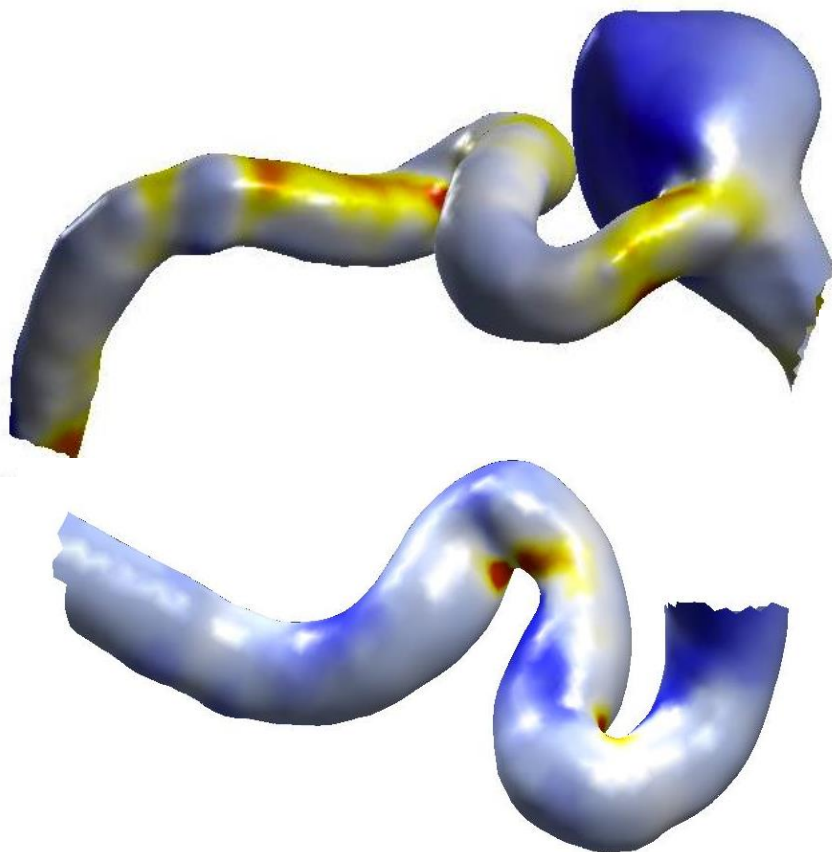


50 simulation replicates



Covariates:

- Local curvature of vessel wall → Negative association
- Curvature of vessel → Positive association
- Local radius of vessel → Negative association



Variability across patients

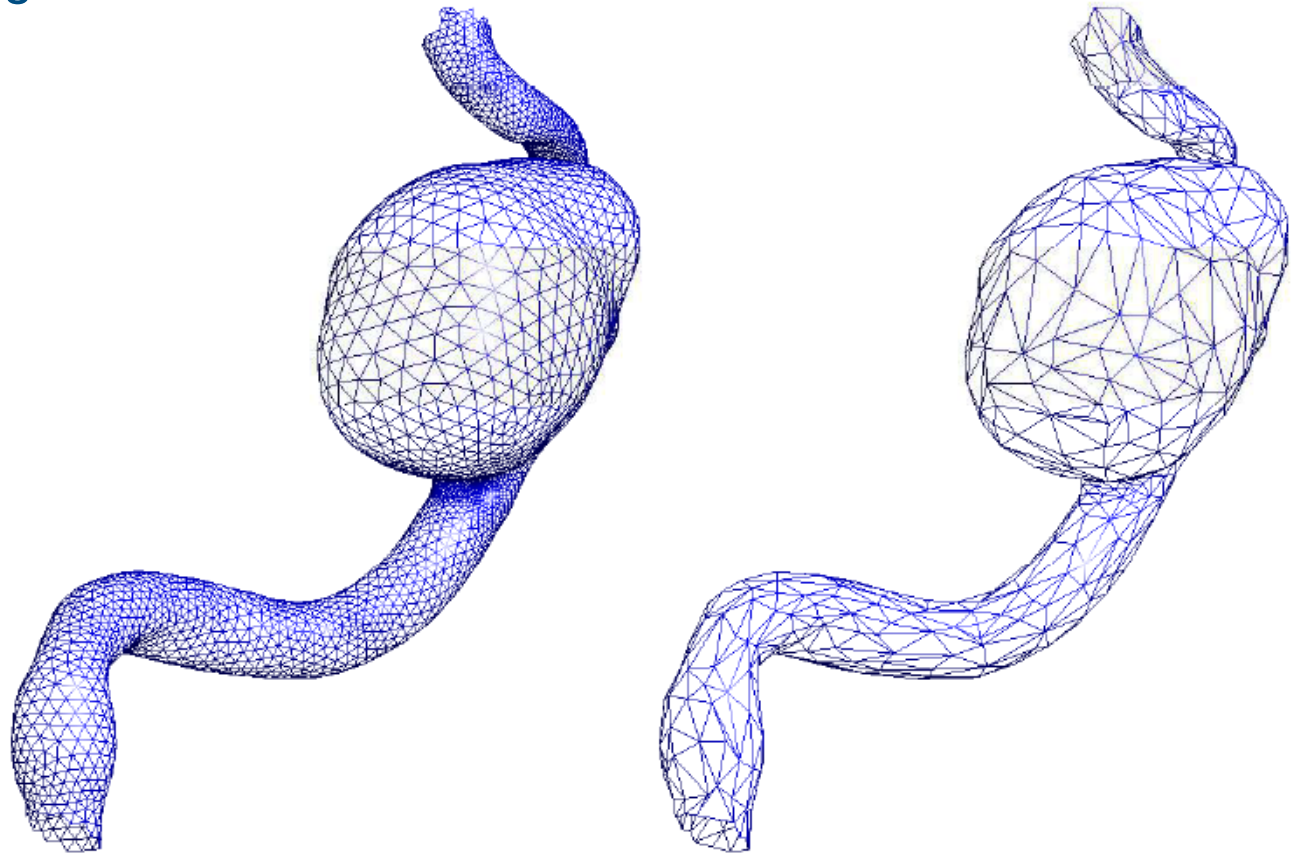


(data registration)



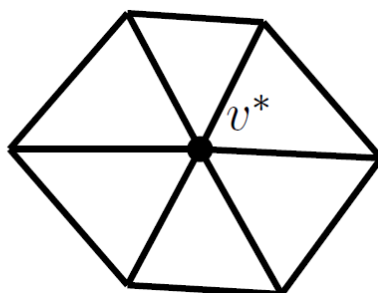
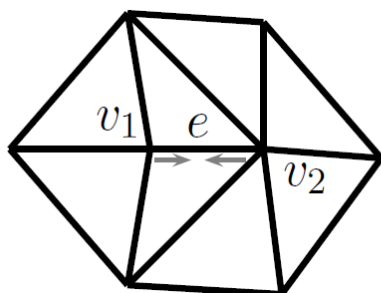
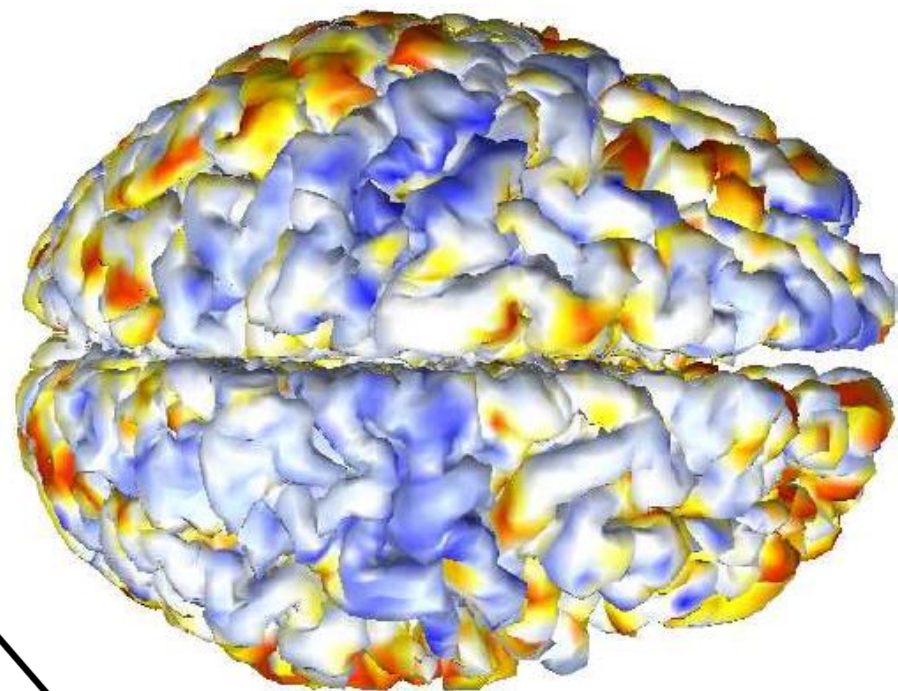
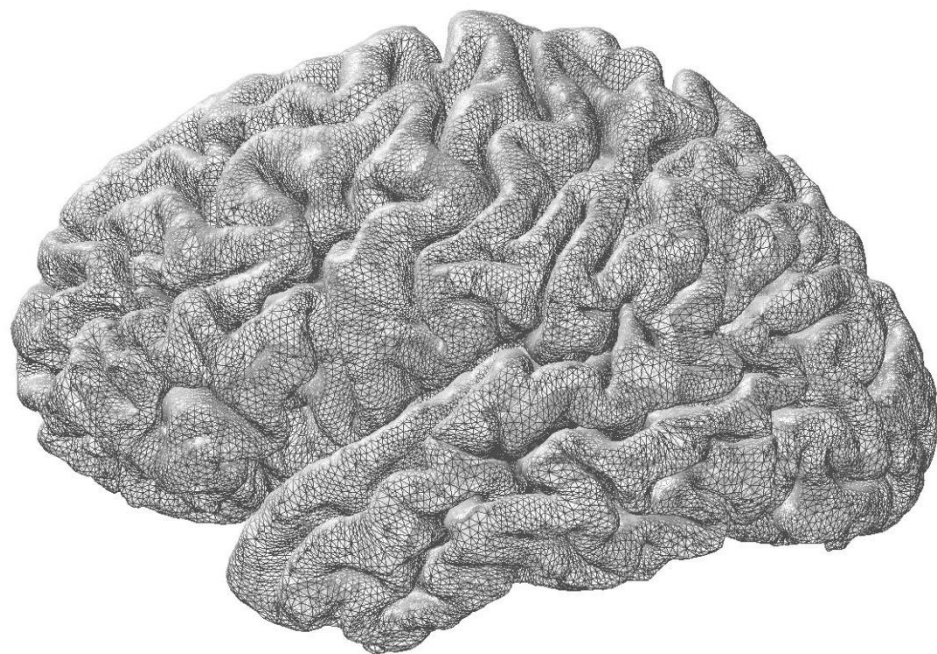
Facing big data challenges:

- iterative algorithms
- mesh simplification algorithms





Spatial Regression models over Riemannian manifolds



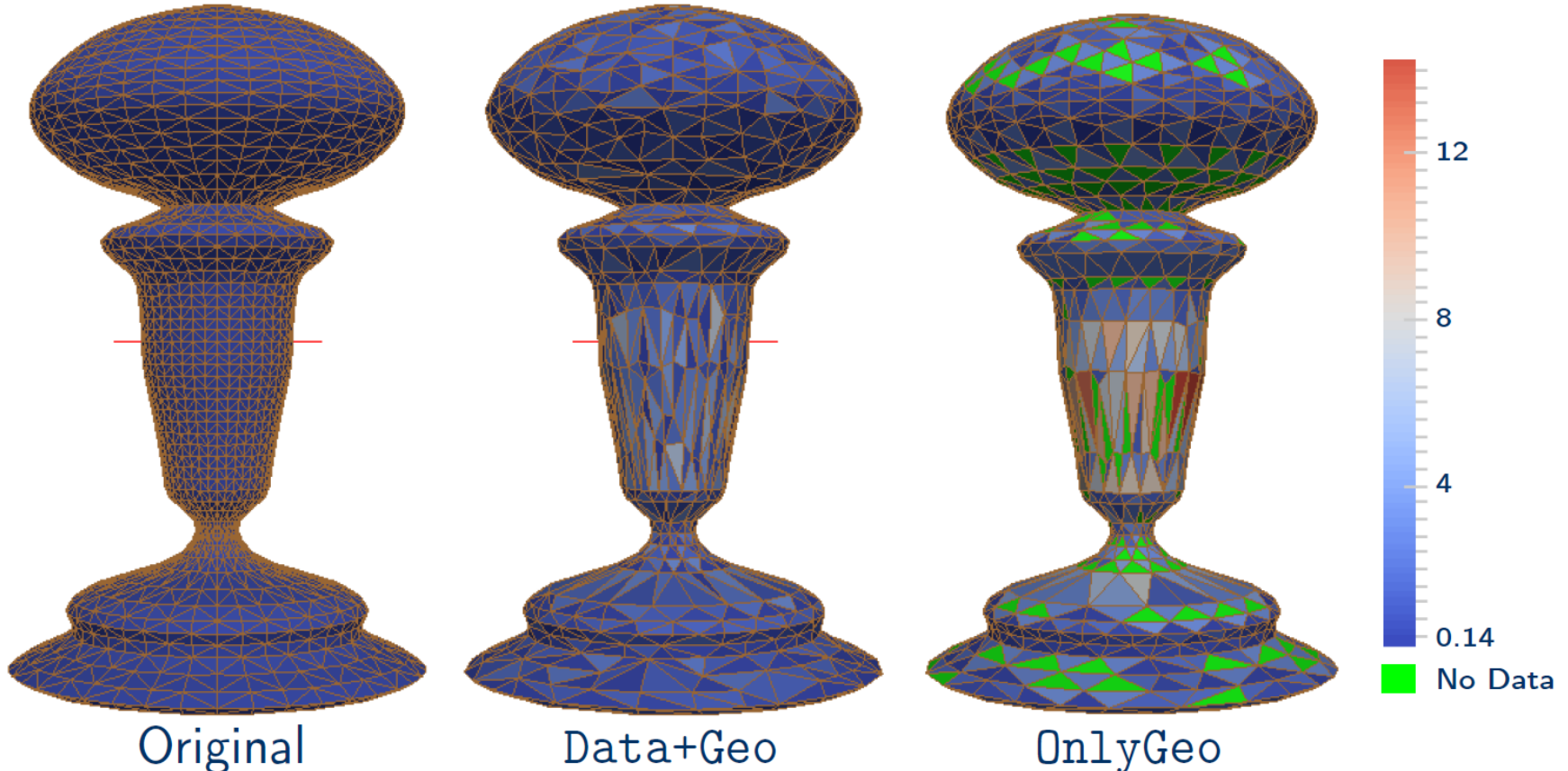
$$c(e, v^*) := \alpha c_{\text{geo}}(e, v^*) + (1 - \alpha) c_{\text{data}}(e, v^*), \quad 0 \leq \alpha \leq 1$$



Spatial regression over Riemannian manifolds

$$c_{\text{equi}}(e, v^*) := \frac{1}{\#(\mathcal{T}_{\text{cont}})} \left(\sum_{T \in \mathcal{T}_{\text{cont}}} (N_T - \bar{N})^2 \right)$$

$$N_T := n_{\text{faces}} + \frac{1}{2}n_{\text{edges}} + \frac{1}{\#(\mathcal{T}_{v_1})}n_{v_1} + \frac{1}{\#(\mathcal{T}_{v_2})}n_{v_2} + \frac{1}{\#(\mathcal{T}_{v_3})}n_{v_3}$$



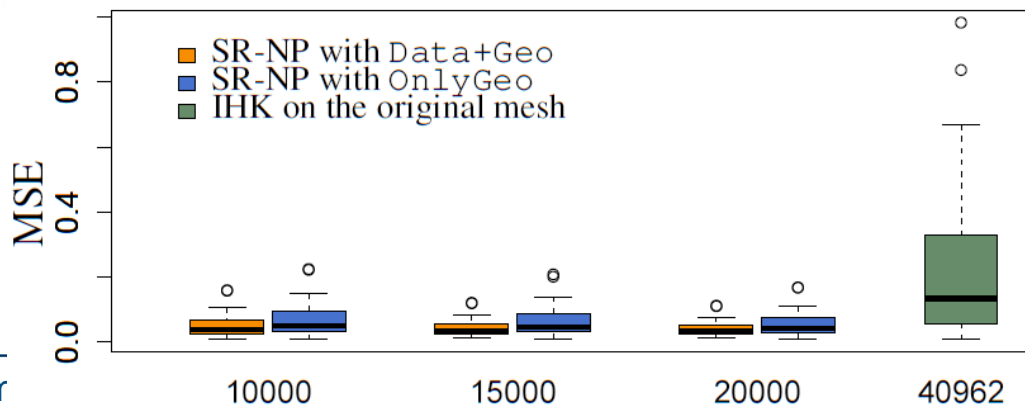
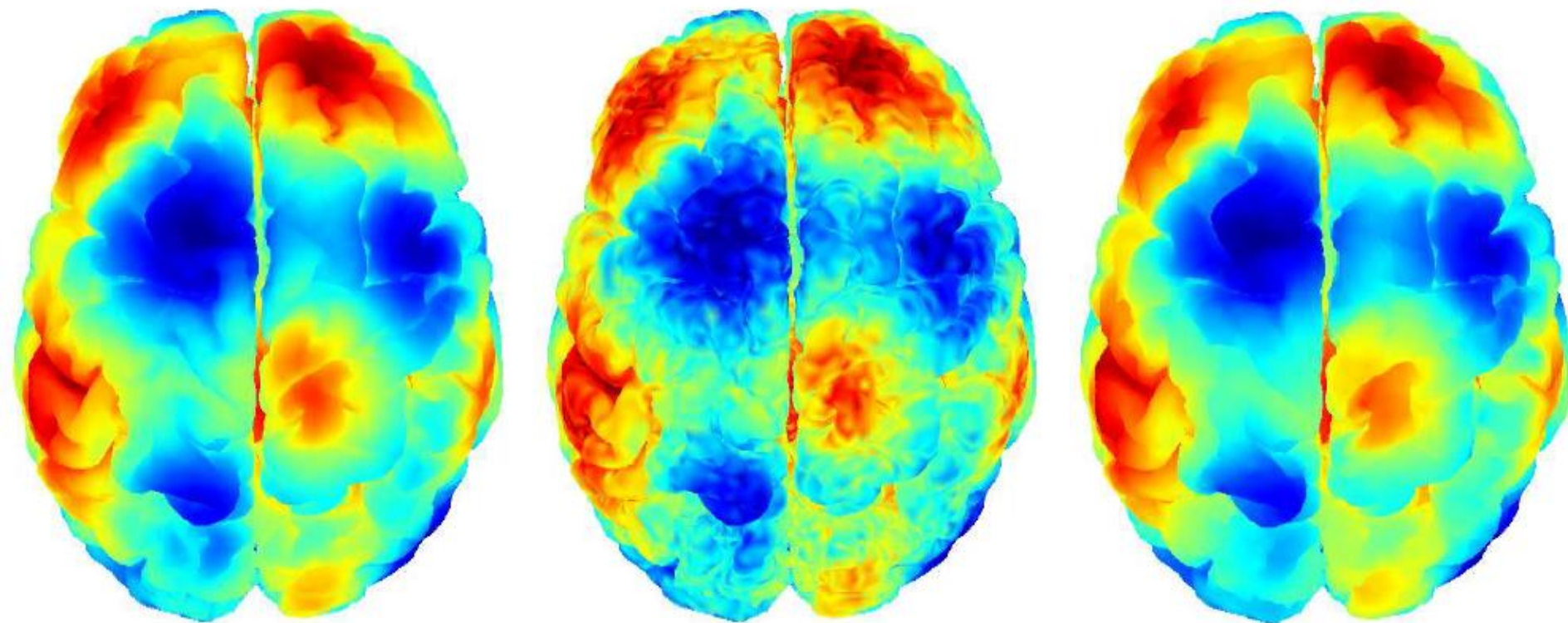


Spatial regression over Riemannian manifolds

TRUE

TRUE + NOISE

ESTIMATE





Motivating applied problem: MACAREN@MOX

MACAREN@MOX Project: MAtematics for CARotid ENdarterectomy @ MOX

Aim: Study the pathogenesis of atherosclerotic plaques



Statistics

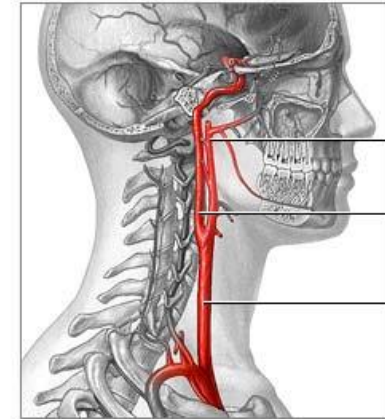
Computer science



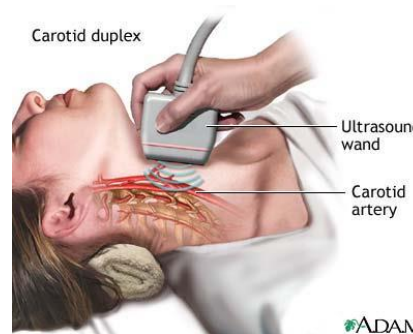
Numerical analysis



Vascular surgery



External carotid artery
Internal carotid artery
Common carotid artery



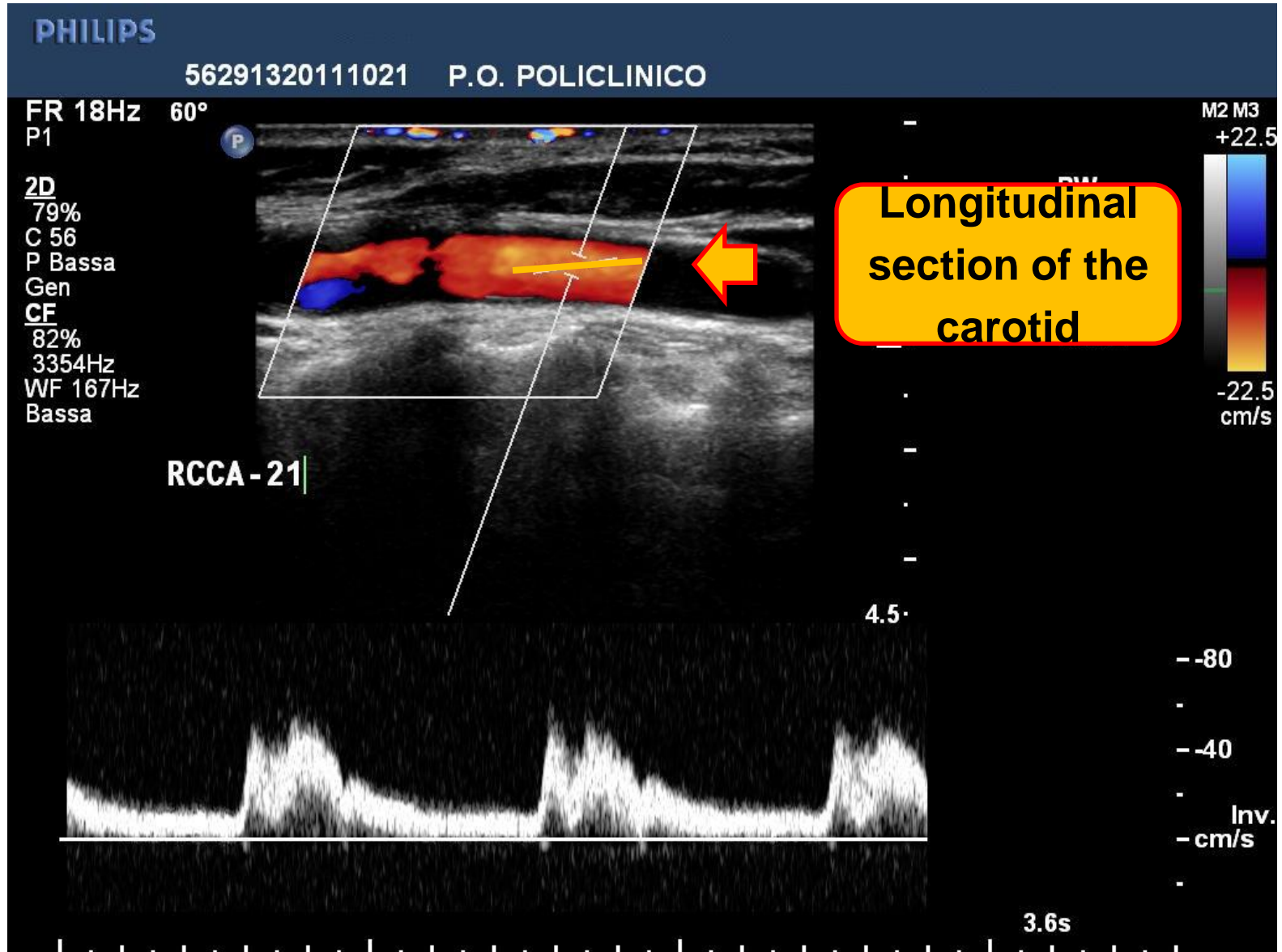
Echo-Color Doppler (ECD)
Blood fluid-dynamics



Magnetic Resonance Imaging (MRI)
Vessel morphology

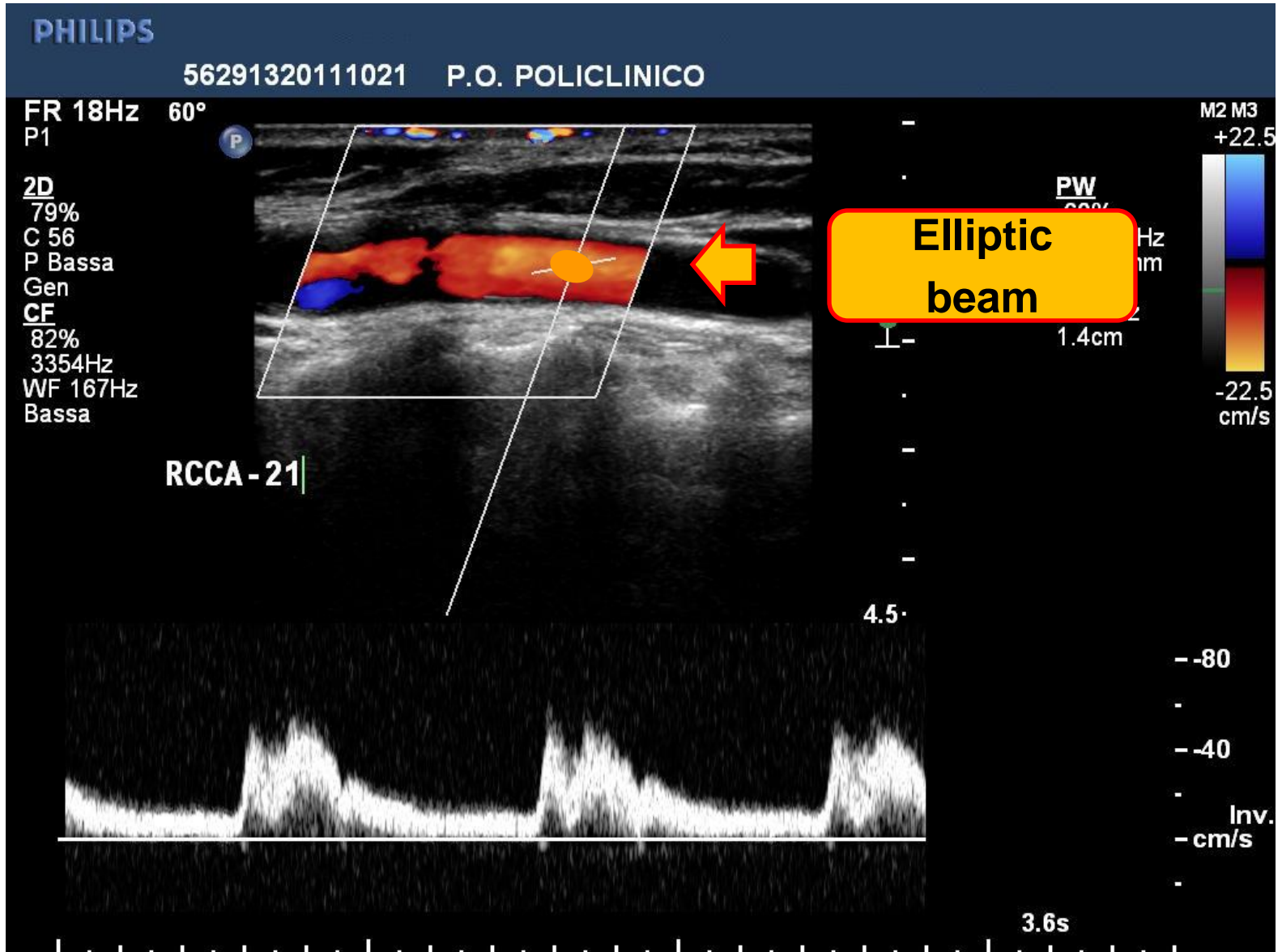


Motivating applied problem: MACAREN@MOX



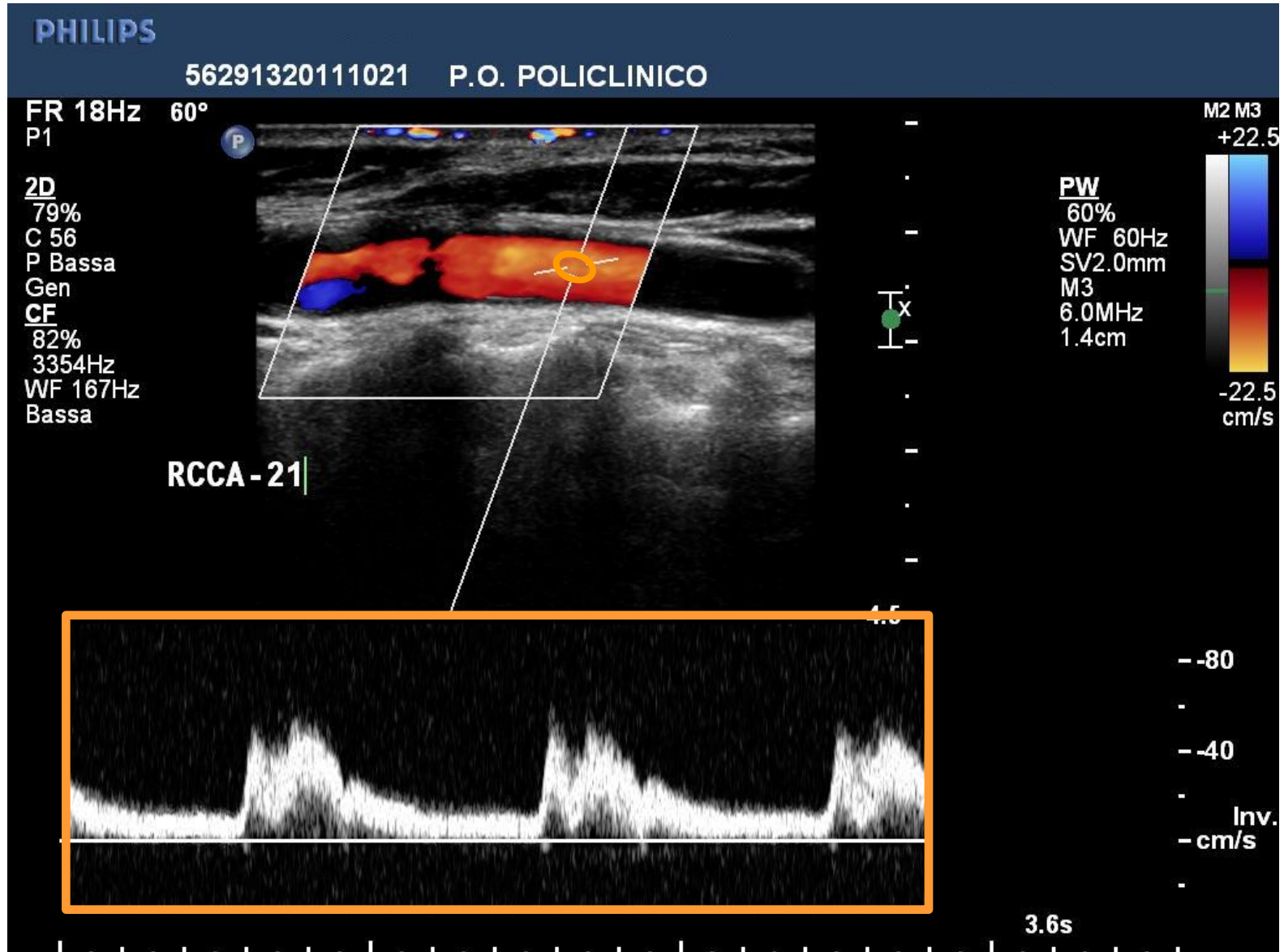


Motivating applied problem: MACAREN@MOX



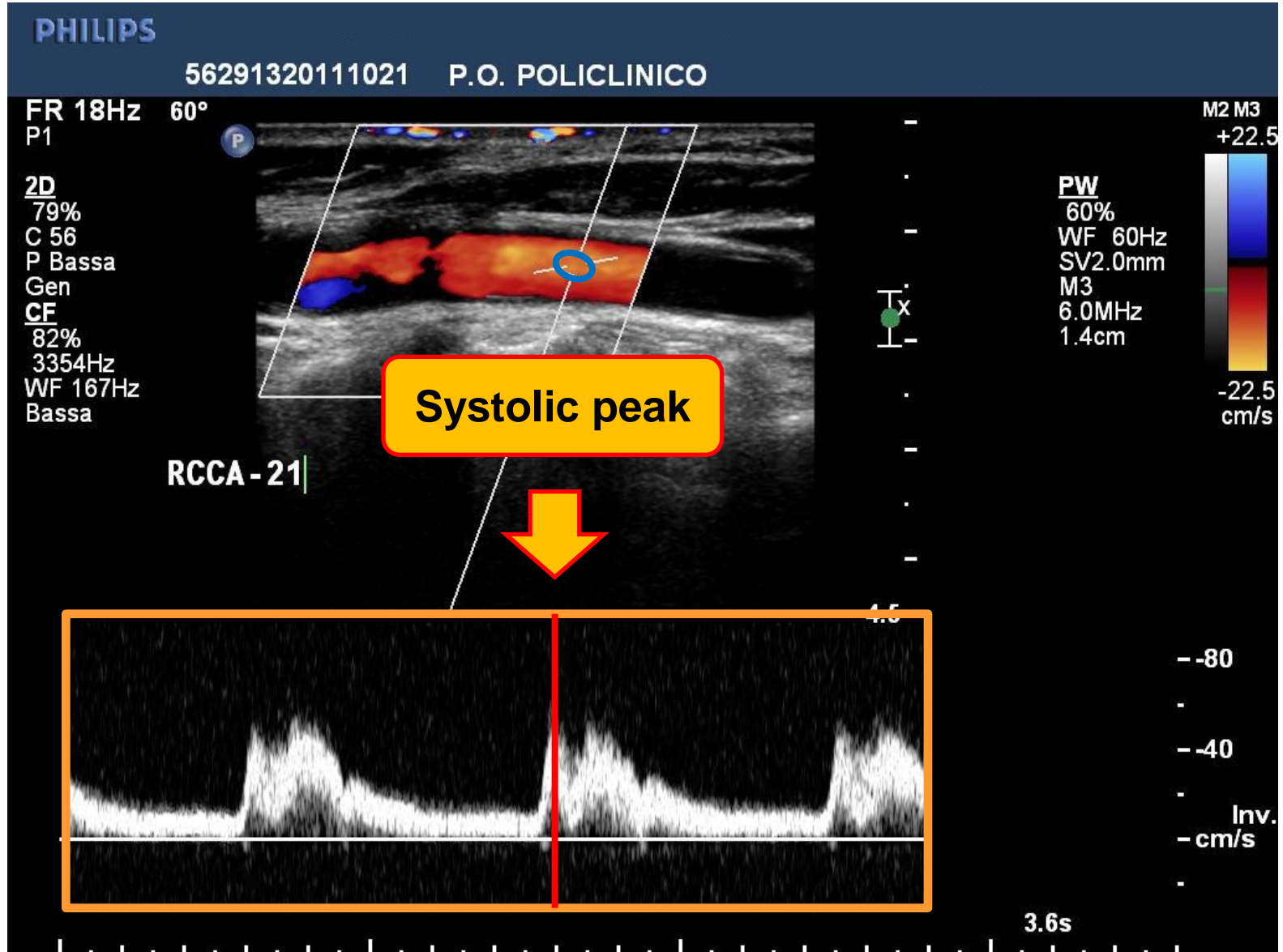


Motivating applied problem: MACAREN@MOX



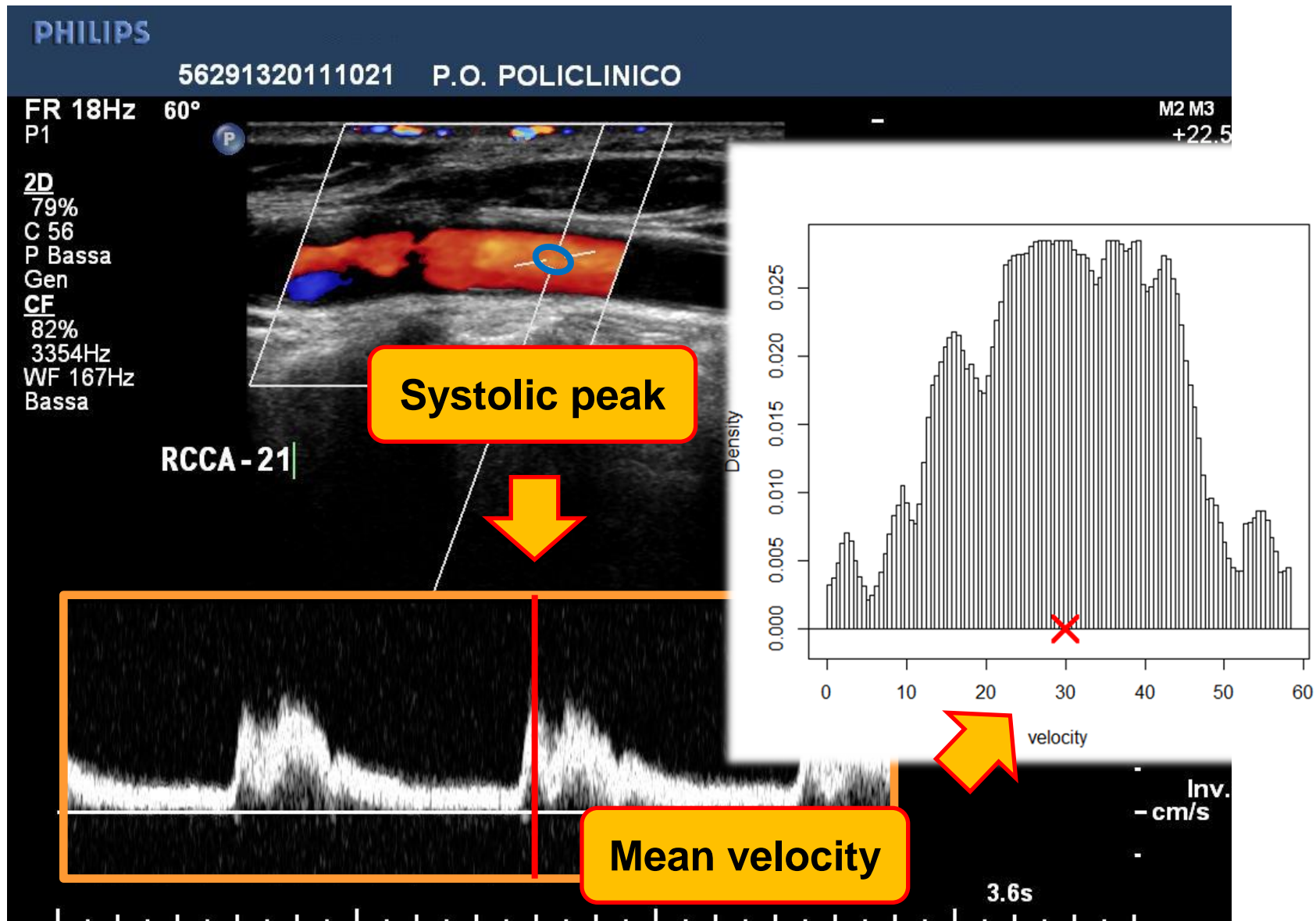


Motivating applied problem: MACAREN@MOX





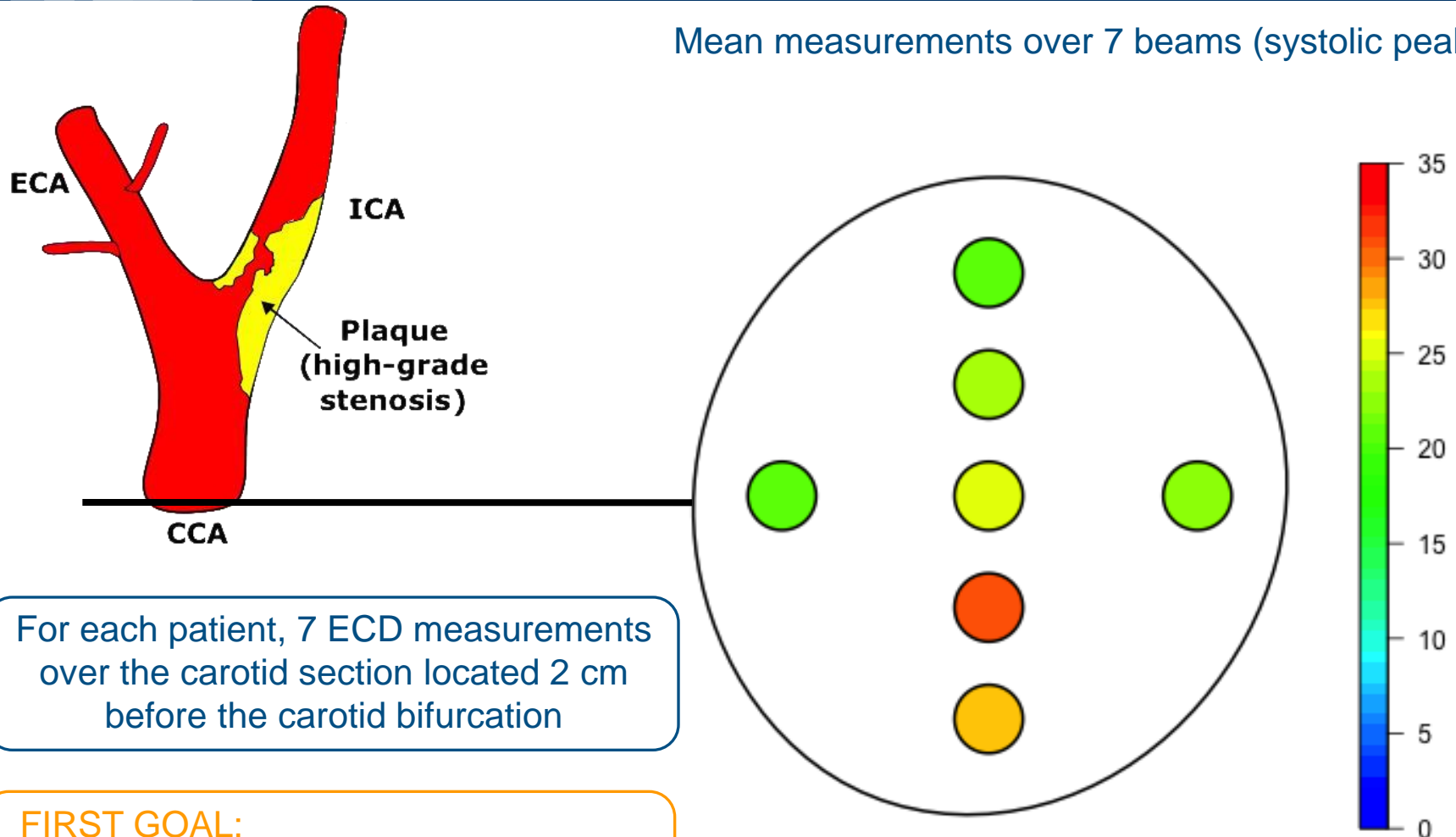
Motivating applied problem: MACAREN@MOX





Motivating applied problem: MACAREN@MOX

Mean measurements over 7 beams (systolic peak)



For each patient, 7 ECD measurements
over the carotid section located 2 cm
before the carotid bifurcation

FIRST GOAL:
estimate blood-flow velocity field over
the carotid section



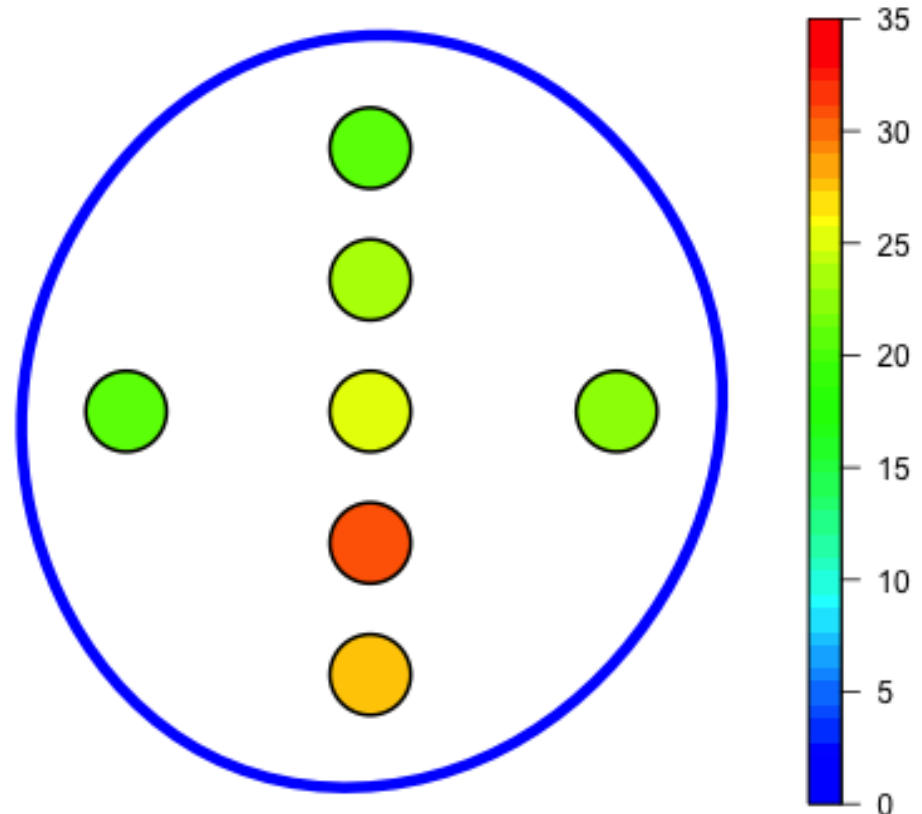
Spatial Spline Regression

$$J(f) = \sum_{i=1}^n (f(\mathbf{p}_i) - z_i)^2 + \lambda \int_{\Omega} (\Delta f)^2$$

Boundary conditions

- Dirichlet $f|_{\partial\Omega} = 0$

Mean measurements over 7 beams (systolic peak)



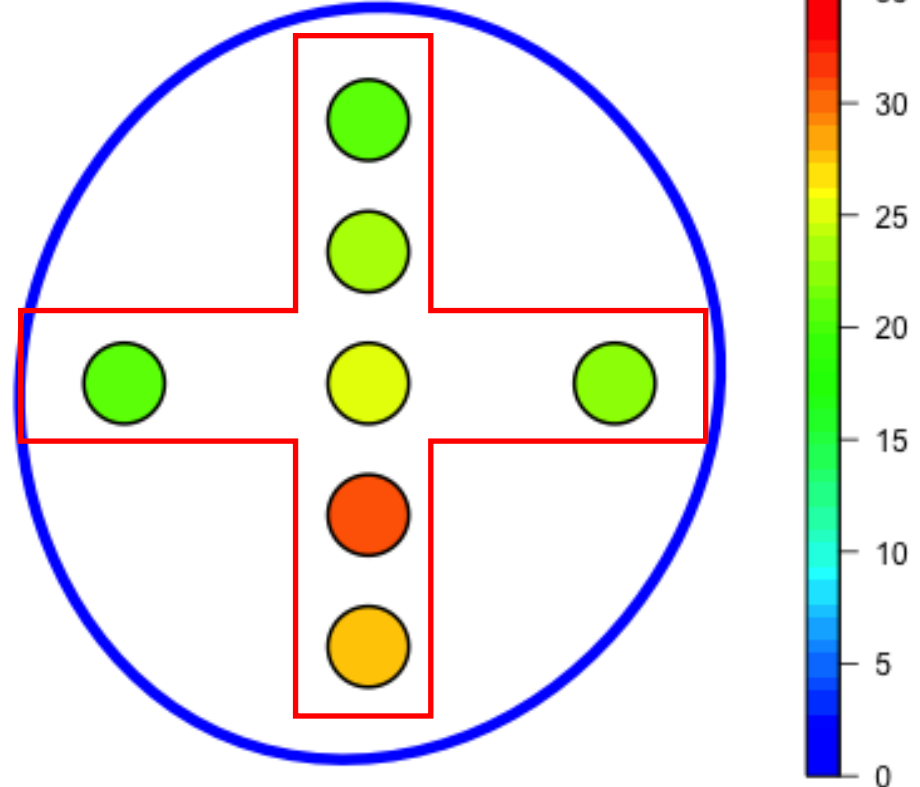
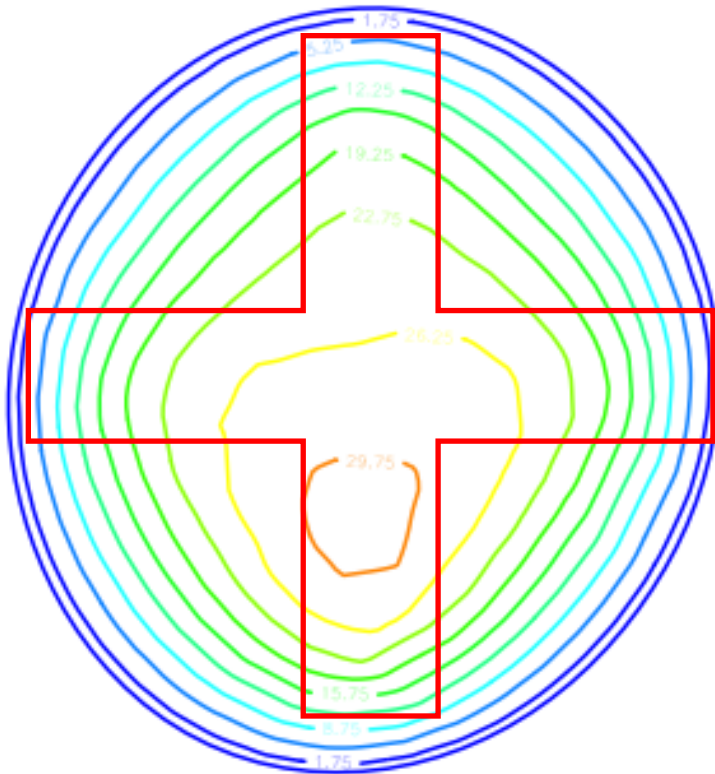
► *Physiological boundary conditions:*
velocity=0 near the arterial wall



Spatial Spline Regression

Mean measurements over 7 beams (systolic peak)

$$J(f) = \sum^n (f(\mathbf{p}_i) - z_i)^2 + \lambda \int_{\Omega} (\Delta f)^2$$



- *Non-physiological velocity field:*
Squared isolines caused by cross-shaped pattern of observations

- *Prior information:*
theoretical solution for velocity field in perfectly straight pipe without turbulence has parabolic profile



Spatial regression models with differential regularization

$$\bar{z}_i = \frac{1}{|D_i|} \int_{D_i} f_0 + \eta_i$$

Areal data
(subdomain D_i : i-th beam)

$$\bar{J}(f) = \sum_{i=1}^N \frac{1}{|D_i|} \left(\int_{D_i} (f - \bar{z}_i) \right)^2 + \lambda \int_{\Omega} (Lf - u)^2$$

→ Weighted least-square-error term for areal mean over subdomains D_i

→ Roughness term penalizing misfit with respect to more complex PDE known to model to some extent the phenomenon under study

general second order elliptic operator

$$Lf = -div(\mathbf{K} \nabla f) + \mathbf{b} \cdot \nabla s + cs$$

forcing term

$$u \in L^2(\Omega)$$

The parameters can be space-varying



Spatial regression models with differential regularization

PRIOR information described by a partial differential model

Forcing term

$$Lf = -div(K \nabla f) + \mathbf{b} \cdot \nabla s + cs$$

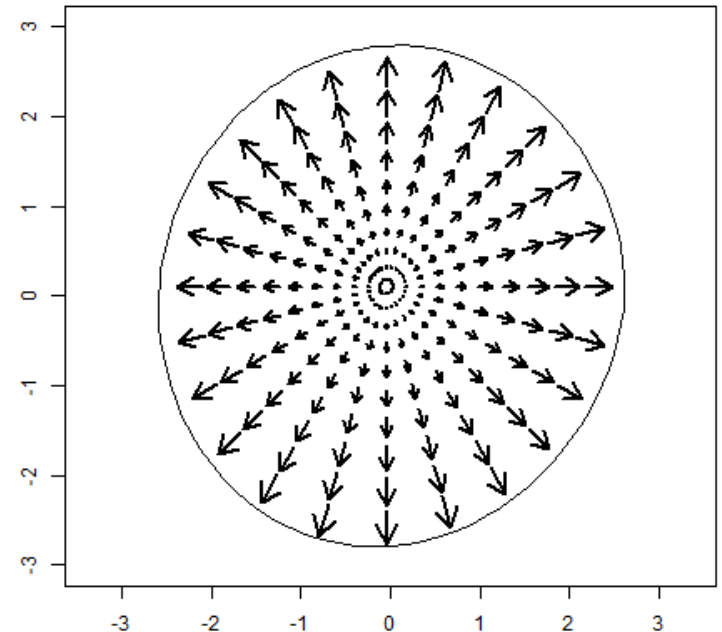
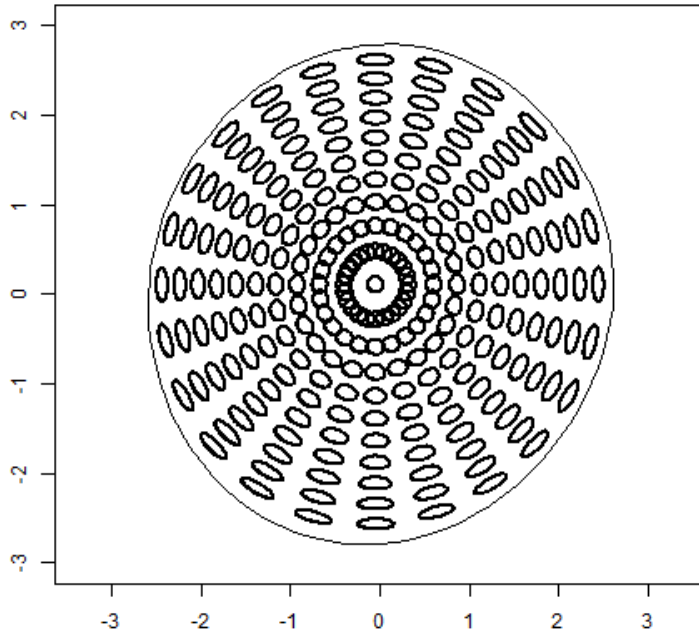
$$u \equiv 0$$

Reaction term: *shrinking effect*

$$c = 0$$

Diffusion tensor field: *anisotropic non-stationary diffusion* that smooths the observations along concentric circles

Transport vector field: *directional smoothing* that smooths the observations along the radial direction





Spatial regression models with differential regularization

▷ $\mathbf{z} = (z_1, \dots, z_n)^t$

▷ $\{\xi_1, \dots, \xi_K\}$: nodes of \mathcal{T}

▷ $\psi = (\psi_1, \dots, \psi_K)^t$: finite element basis $\Psi = \{\Psi\}_{ij} := \psi_j(\mathbf{p}_i)$

▷ for any g in the finite element space, $g = \mathbf{g}^t \psi$ where $\mathbf{g} := (g(\xi_1), \dots, g(\xi_K))^t$

▷ $R = \{R\}_{jk} := \int_{\Omega_{\mathcal{T}}} (\psi_j \psi_k^t)$ $A = \{A\}_{jk} := \int_{\Omega_{\mathcal{T}}} (\mathbf{K} \nabla \psi_j \cdot \nabla \psi_k + \mathbf{b} \cdot \nabla \psi_j \psi_k + c \psi_j \psi_k)$

Corollary. The finite element estimator \hat{f} that solve the discrete counterpart of the estimation problem, exist unique and is given by $\hat{f} = \mathbf{f}^t \psi$ where \mathbf{f} satisfies

$$\begin{bmatrix} -\Psi^t \Psi & \lambda A \\ \lambda A & \lambda R \end{bmatrix} \begin{bmatrix} \mathbf{f} \\ \mathbf{g} \end{bmatrix} = \begin{bmatrix} -\Psi^t \mathbf{z} \\ \mathbf{0} \end{bmatrix}$$

(Here for simplicity: pointwise case, $u \equiv 0$, homogeneous Neumann b.c.)



\hat{f} is *linear* in \mathbf{z} and has typical penalized regression form:

$$\mathbf{f}_n = (\Psi^t \Psi + \lambda P)^{-1} \Psi^t \mathbf{z}$$

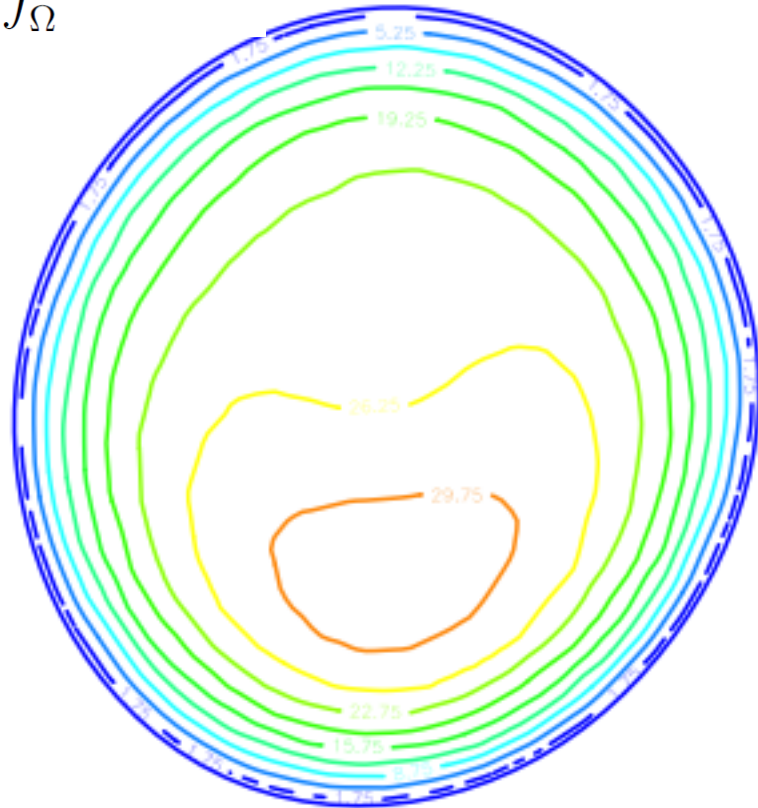
$$P = A^t R^{-1} A \quad \text{is discretization of penalty}$$

- ▶ Classical inferential tools are readily derived
 - ▷ mean and variance of \hat{f}
 - ▷ confidence bands for f
 - ▷ prediction intervals for new observations
 - ▷ estimate of error variance σ^2
 - ▷ selection of smoothing parameter λ via generalized cross validation



Spatial regression models with differential regularization

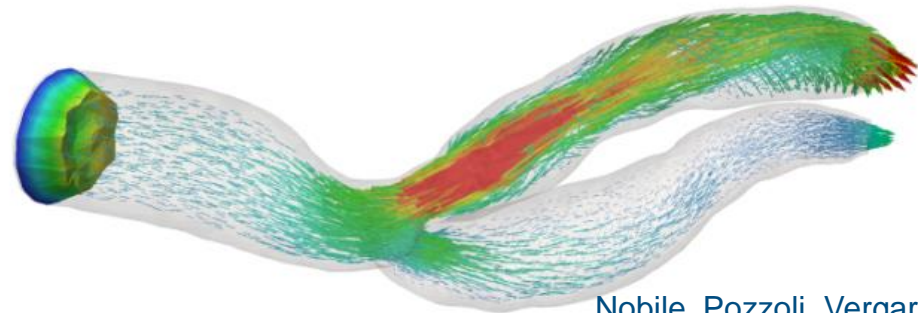
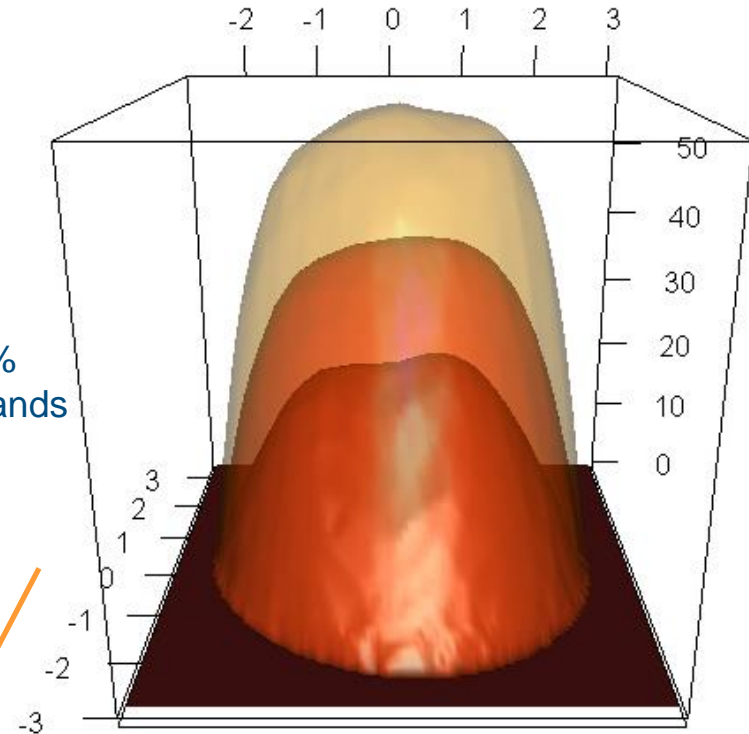
$$\int_{\Omega} (Lf - g)^2$$



Physiological velocity field
Asymmetry due to curvature of carotid
artery and to carotid bifurcation

Relevant features: eccentricity,
reversion of fluxes

pointwise 95%
confidence bands



Nobile, Pozzoli, Vergara

Patient-specific inflow conditions for Computational Fluid-Dynamics



Irregularly shaped domains and boundary conditions

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Incorporating a priori knowledge

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Manifold domains

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<http://mox.polimi.it/users/sangalli/firbSNAPLE.html>

Dote Ricercatore Politecnico di Milano – Regione Lombardia: Research Project (2010 - 2013)
“Functional data analysis for life sciences”.



McGill University: Visiting research grant (Apr.- July 2010), Department of Mathematics and Statistics, McGill University, Montreal, Canada.

SAMSI: Visiting research grant (Jan.- Feb. 2011), SAMSI Statistical and Applied Mathematical Sciences Institute, Research Triangle Park, North Carolina, US

<http://mox.polimi.it/users/sangalli>