

# **AERODYNAMIC DAMPING OF A HAWT ON A SEMISUBMERSIBLE**

Effect of aerodynamic loading on the motions of the OC4-semi in waves

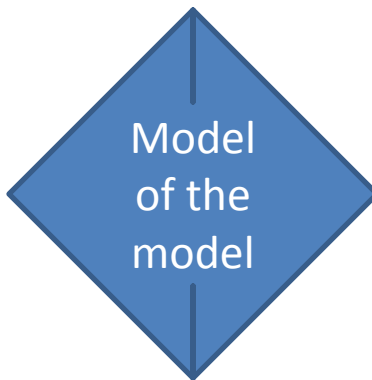
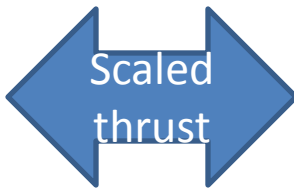
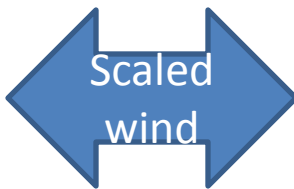
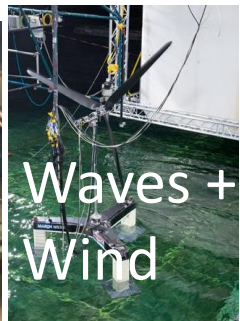
Sebastien Gueydon

EERA DeepWind'2016 conference, Trondheim

- How MARIN is helping developers of floating wind turbines?
  - Model-tests
  - Simulations
- From 'concept design' to validated model 'Model of the model'
  - Example of the OC4-semisubmersible
  - Sensitivity to change in inertia
  - Sensitivity of the model to rotor force coefficients
- Conclusions
- Further work

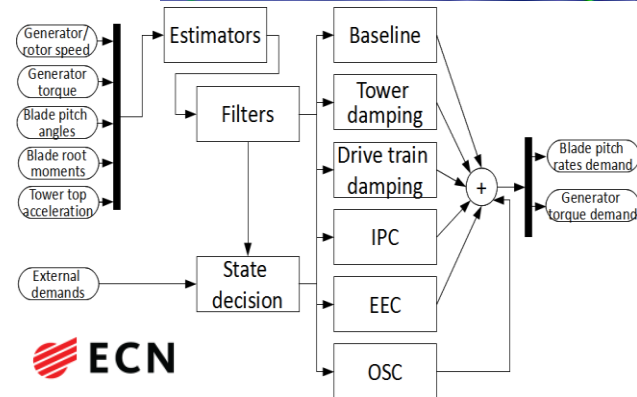
# FLOATING WIND AT MARIN

## Model tests



## Numerical studies

CFD for wind set-up, blades



My objectives:

- R&D: What does matter for the floater?
- BU: Verification => Concept study

# 'MODEL OF A MODEL'

- A concept design evolves before and after the model-tests (different mass distribution, different turbine, etc...)
  - A turbine is available for model-testing in wave and wind (but the actual wind turbine may be slightly different)
  - While modeling wind & waves, a new scaling approach is followed ('performance scaling for the rotor'). This has an impact on the aerodynamic performance of the turbine.
- ⇒ Use model-test data to calibrate a numerical model = 'Model of the model'
- ⇒ What is the influence on the motions of a OFWT of all these differences?

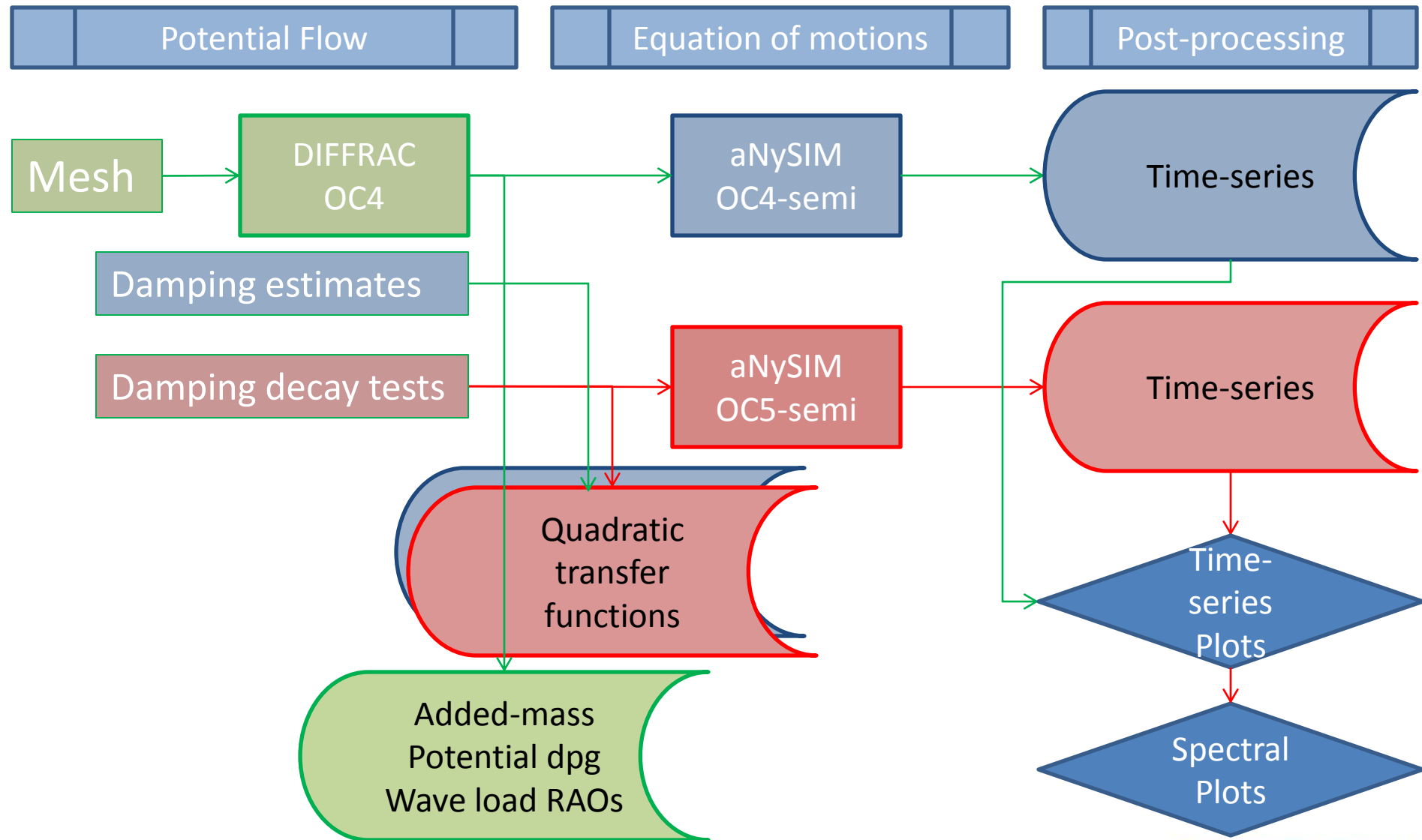
# MODEL OF THE OC4 SEMISUBMERSIBLE

- Differences?
  - (Design) OC4-SEMI
  - (Built) OC5-SEMI

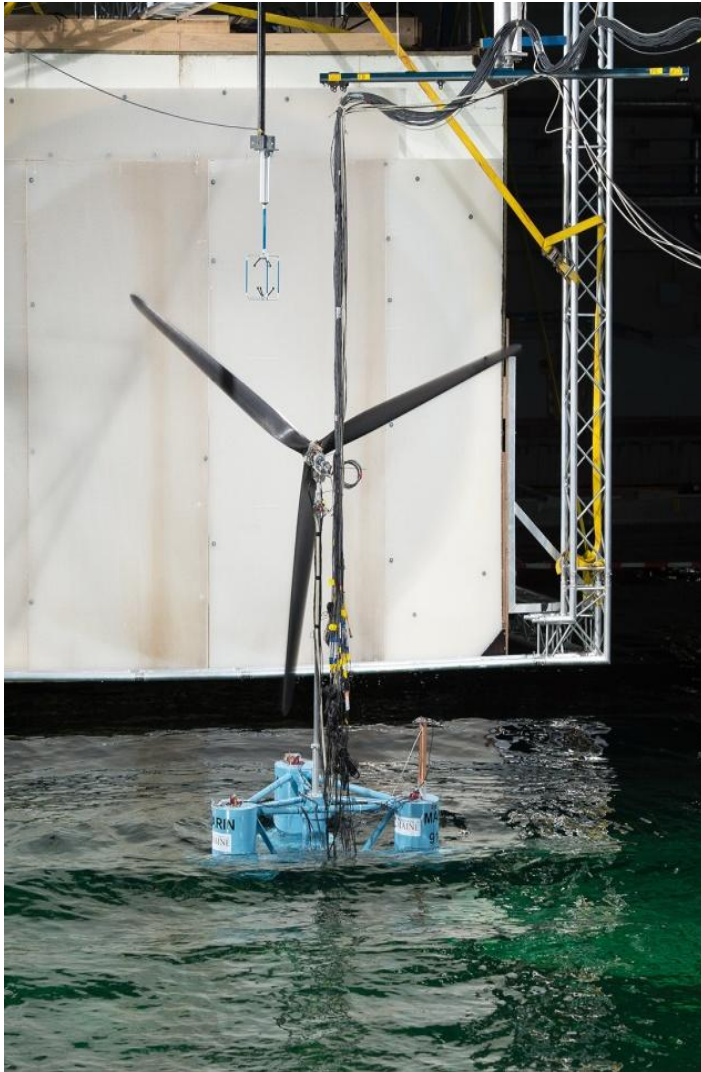
⇒ “Model of the model”

Designation	Symbol	Unit	Values	
			OC4	OC5
			Calculated	As-built
Draft	T	m	20.0	20.0
Mass	M	ton	14,260	13,958
Centre of Gravity above keel	KG	m	9.96	11.93
Longitudinal metacentric height	$GM_L$	m	7.34	5.29
Roll radius of gyration in air	$k_{xx}$	m	32.07	32.63
Pitch radius of gyration in air	$k_{yy}$	m	32.94	33.38
Yaw radius of gyration in air	$k_{zz}$	m	31.83	31.32
Natural pitch period (moored)	$T_\theta$	s	25.1	32.1
Natural heave period (moored)	$T_z$	s	17.0	17.2

# CALCULATION PROCESS & POST-PROCESSING



# POTENTIAL THEORY RESULTS IN WAVES



Load case:

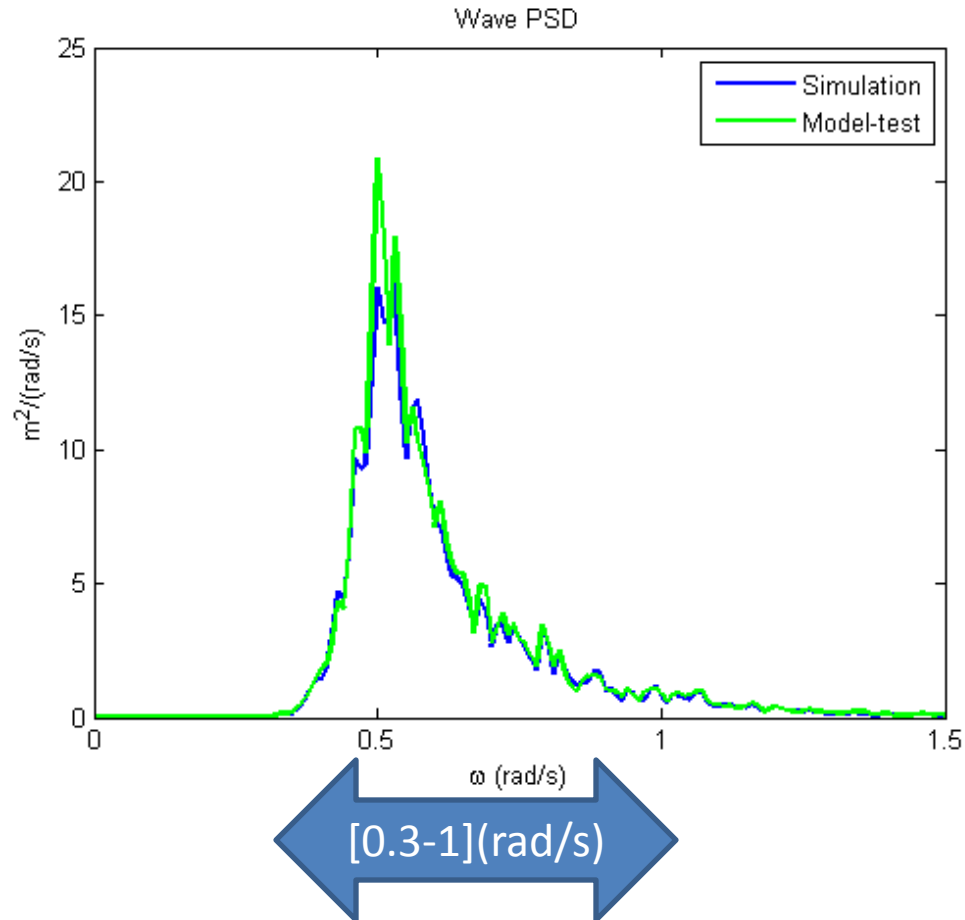
- Long-crested waves
- JONSWAP  $H_s = 7.1$  m  $T_p = 12.1$  s

Comparison of simulations for:

- A. OC5 = calibrated model*
- B. OC4 = original 5MW*
- C. Measurements*

# VERIFICATION OF HYDRODYNAMIC RESPONSE

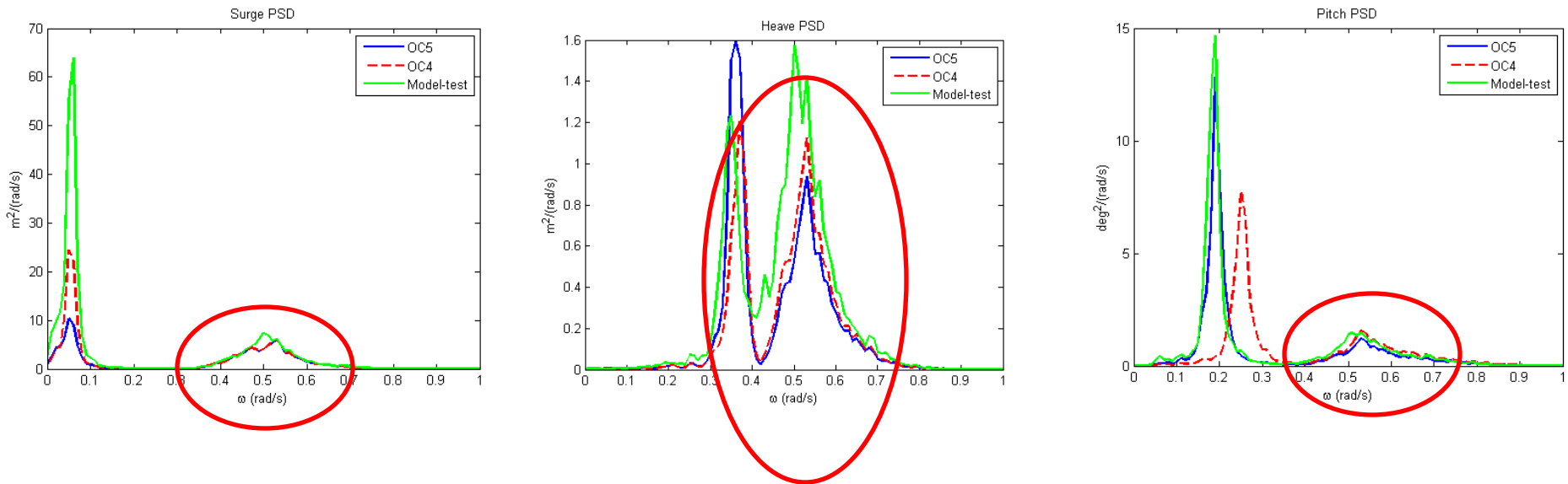
- Operational sea, head waves





# VERIFICATION OF HYDRODYNAMIC RESPONSE

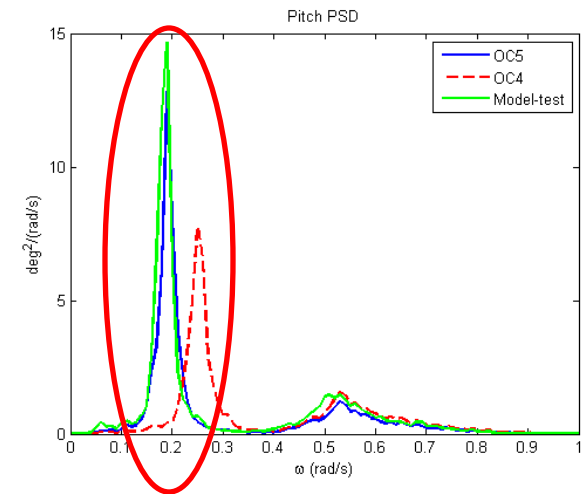
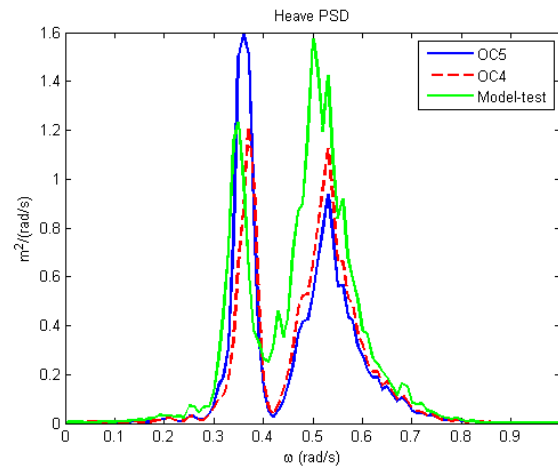
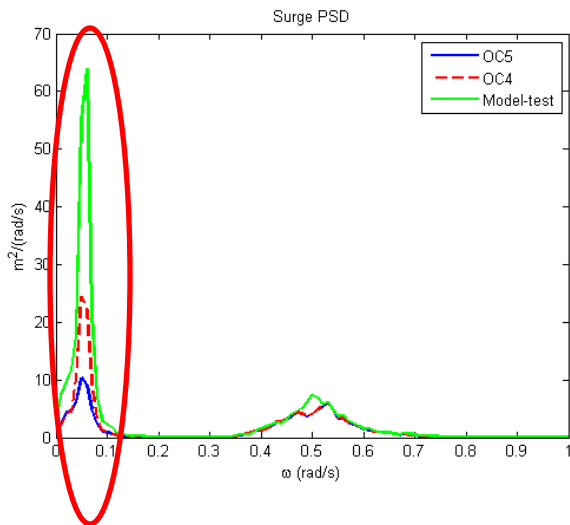
- Operational sea, head waves



- Response in wave energy range (1<sup>st</sup> order) are similar

# VERIFICATION OF HYDRODYNAMIC RESPONSE

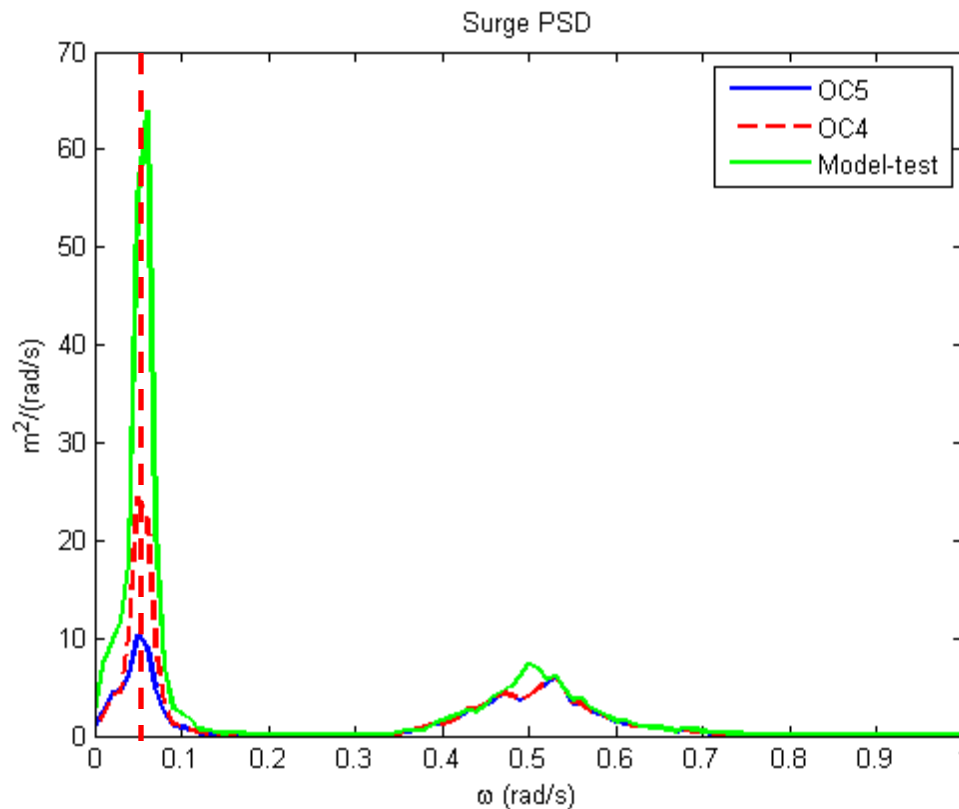
- Operational sea, head waves



- Response in low frequency range (2<sup>nd</sup> order) are different
- Difference at resonance (surge, heave & pitch)

# COMPARISON: MODEL OF THE MODEL

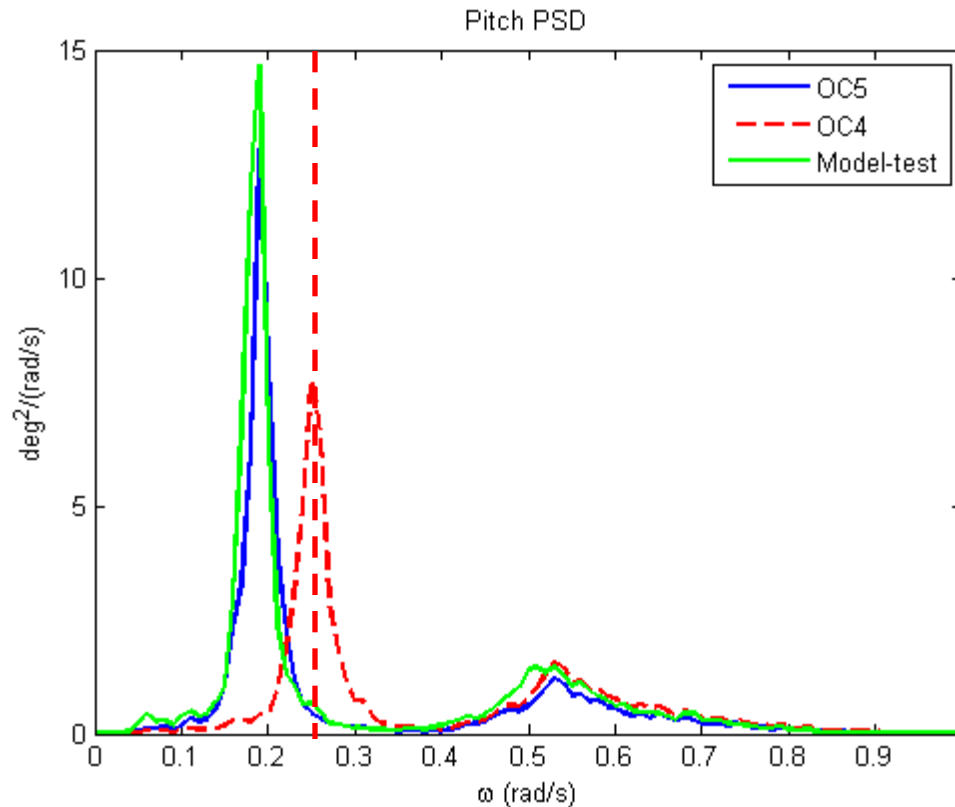
- OC5 Calibrated / OC4 Design / Model-test data



- Surge resonance peak of simulations are different and much smaller than in the model-test data.

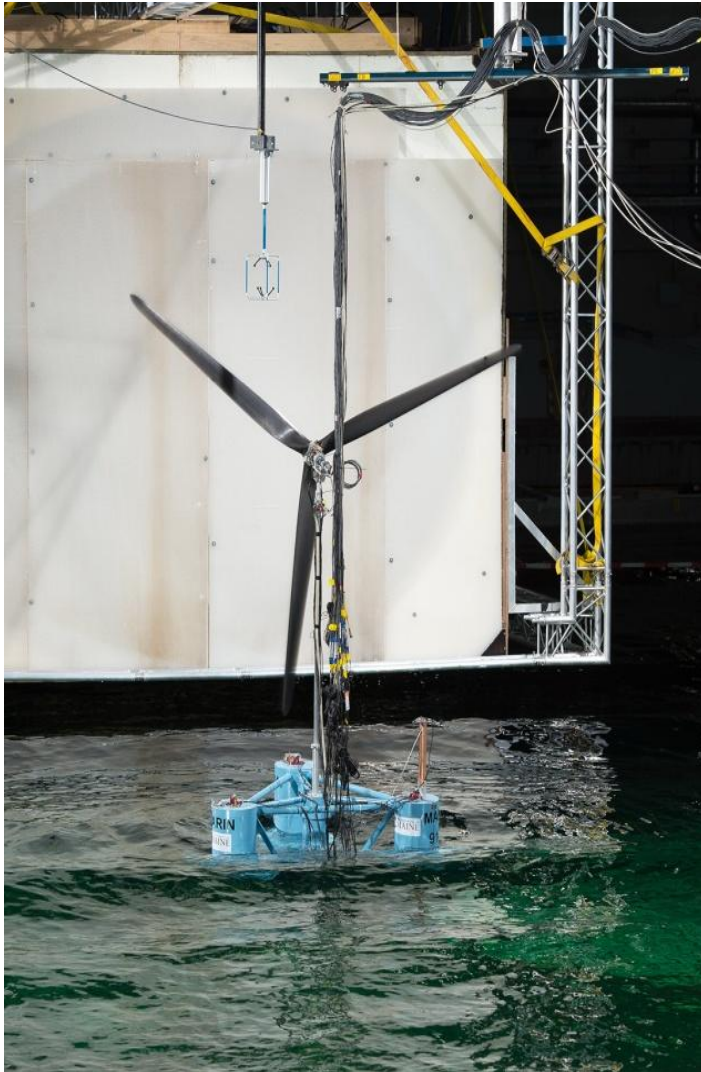
# COMPARISON: MODEL OF THE MODEL

- OC5 Calibrated / OC4 Design / Model-test data



- Pitch resonance peak are different:
  - OC4 < model-test

# BEMT RESULTS IN WAVES & WIND



Load case:

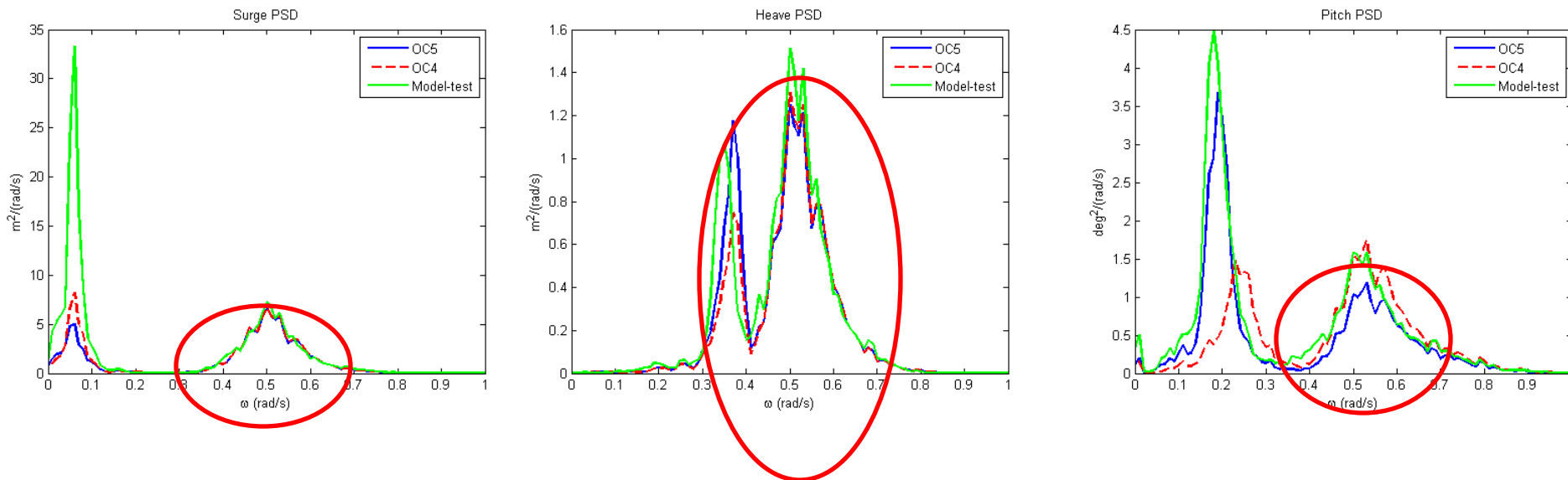
- Co-linear waves and wind
- JONSWAP  $H_s = 7.1$  m  $T_p = 12.1$  s
- Wind speed  $V = 13$  m/s
- Rotor fixed rpm = 12.1
- Blade pitch angle = 1 deg  
=> TSR = 6.156

Comparison of simulations for:

- A. OC4 design (XFOIL @ FS)
- B. OC5 model (UMaine @ MS)
- C. OC5 model (ECN RFOIL @ MS)

# VERIFICATION OF RESPONSE IN WIND & WAVES

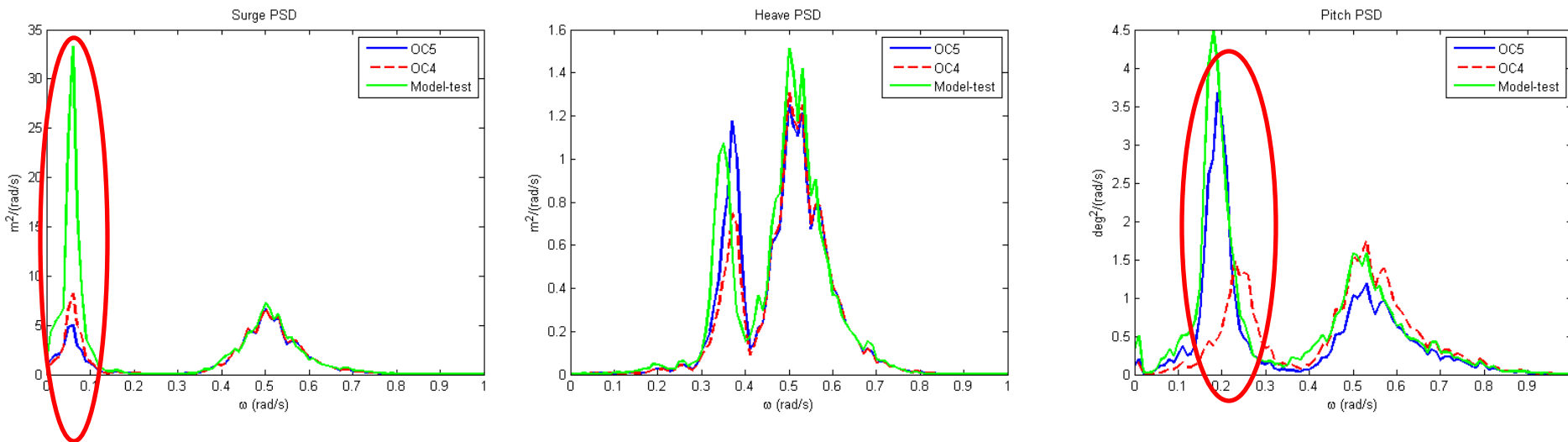
- Operational sea + steady wind, head waves



- Response in wave energy range (1<sup>st</sup> order)

# VERIFICATION OF RESPONSE IN WIND & WAVES

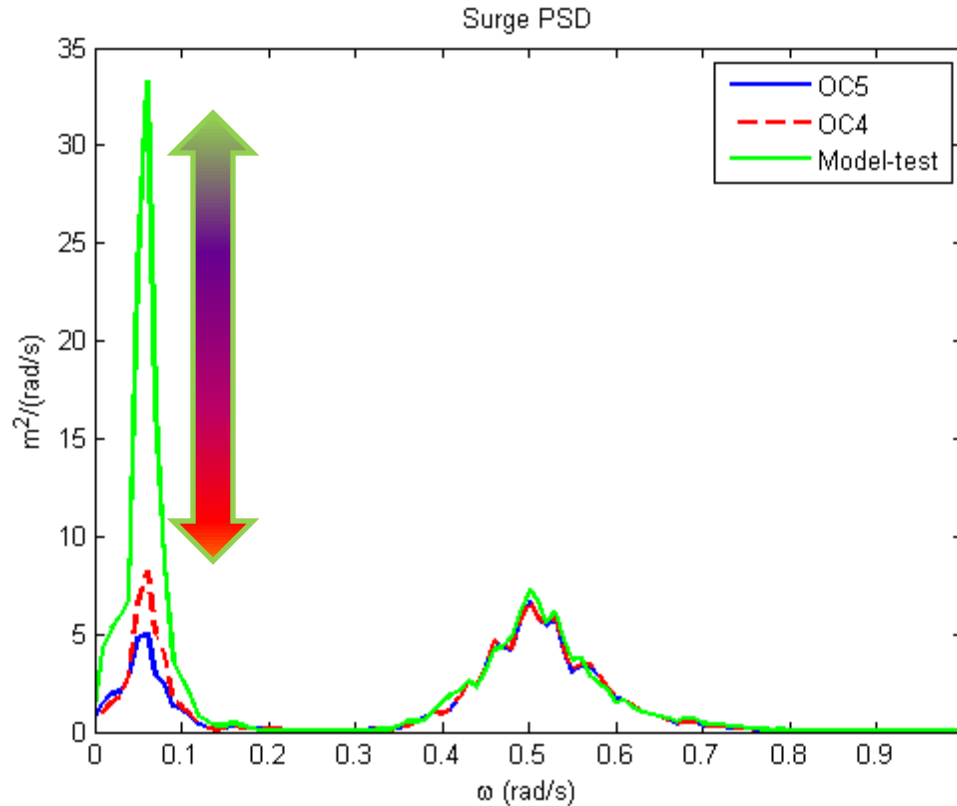
- Operational sea + steady wind, head waves



- Response in low frequency range (2<sup>nd</sup> order)

# COMPARISON: MODEL OF THE MODEL

- OC5 Calibrated / OC4 Design / Model-test data



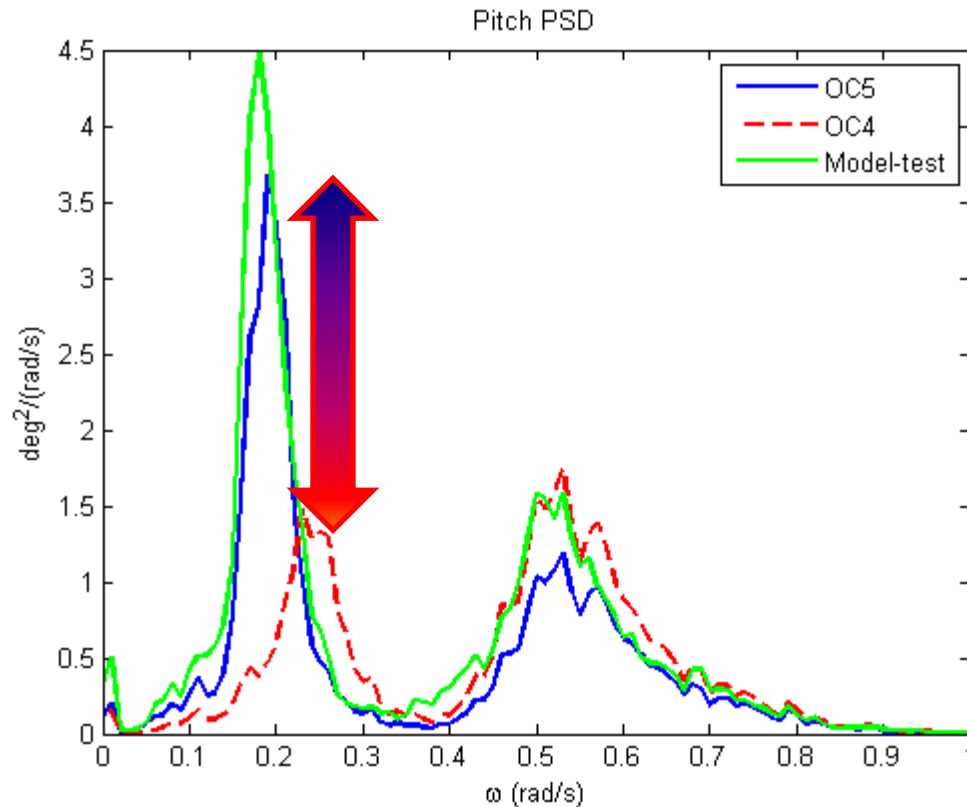
⇒ Less damping for the model-tests than the simulations

⇒ Effect mainly visible at resonance (slow drift 2<sup>nd</sup> order response)



# COMPARISON: MODEL OF THE MODEL

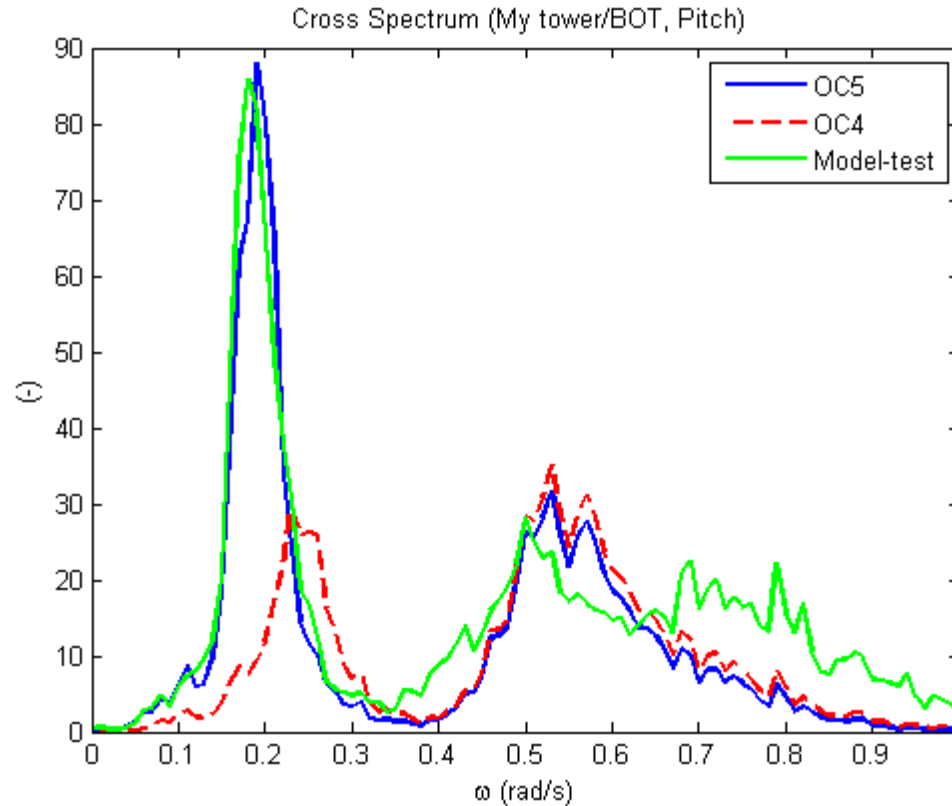
- OC5 Calibrated / OC4 Design / Model-test data



=> Less damping for the 'Model of the model' than the 'Design' case

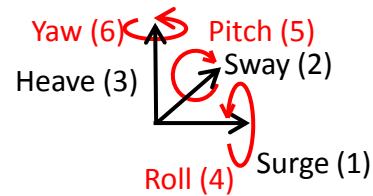
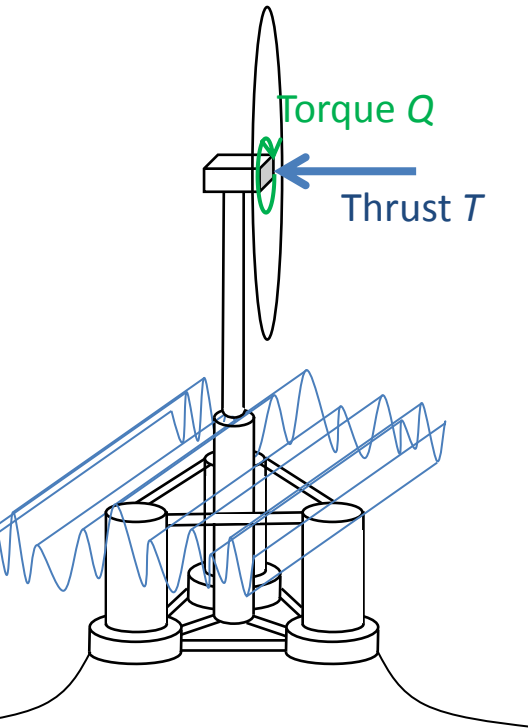
# COMPARISON: MODEL OF THE MODEL

- OC5 Calibrated / OC4 Design / Model-test data



⇒ Correlation of pitch moment at tower foot and pitch motion

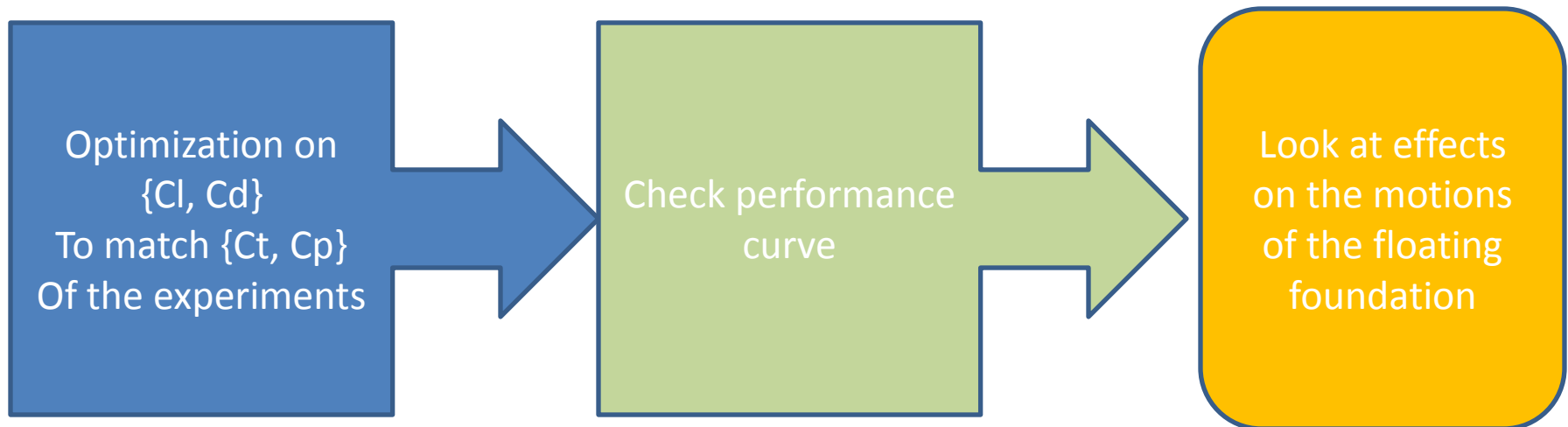
# CALIBRATION OF THE ROTOR OF THE WIND TURBINE



- Parallel wind and wave, no yaw
- Thrust acts mainly on
  - Surge
  - Pitch
- Test in a basin at scale 1/50 with a re-designed rotor that mimics the full scale rotor  $\{C_t, (C_p)\}$  for a range of TSR
- What are the  $\{C_l, C_d\}$ ?

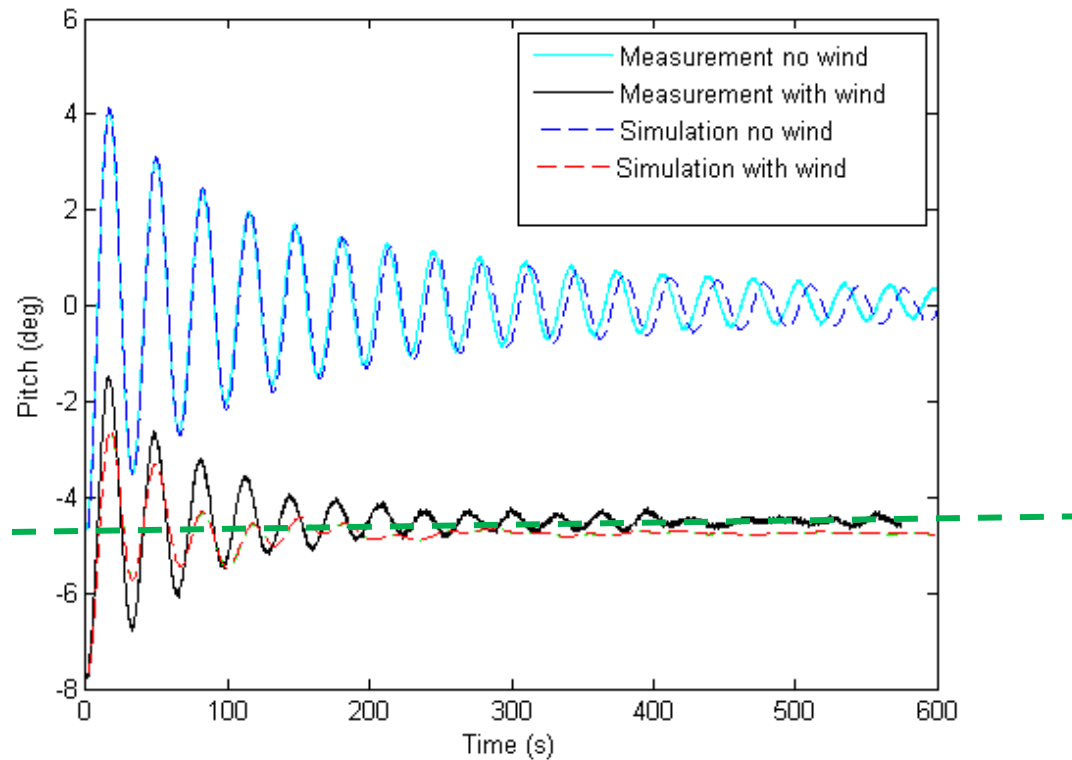
# CALIBRATION OF AERODYNAMIC LOAD COEFFICIENTS

- Optimization = vary  $\{C_l, C_d\}$  to match measured  $\{C_t, C_p\}$



# LOOK AT THE DYNAMIC RESPONSE

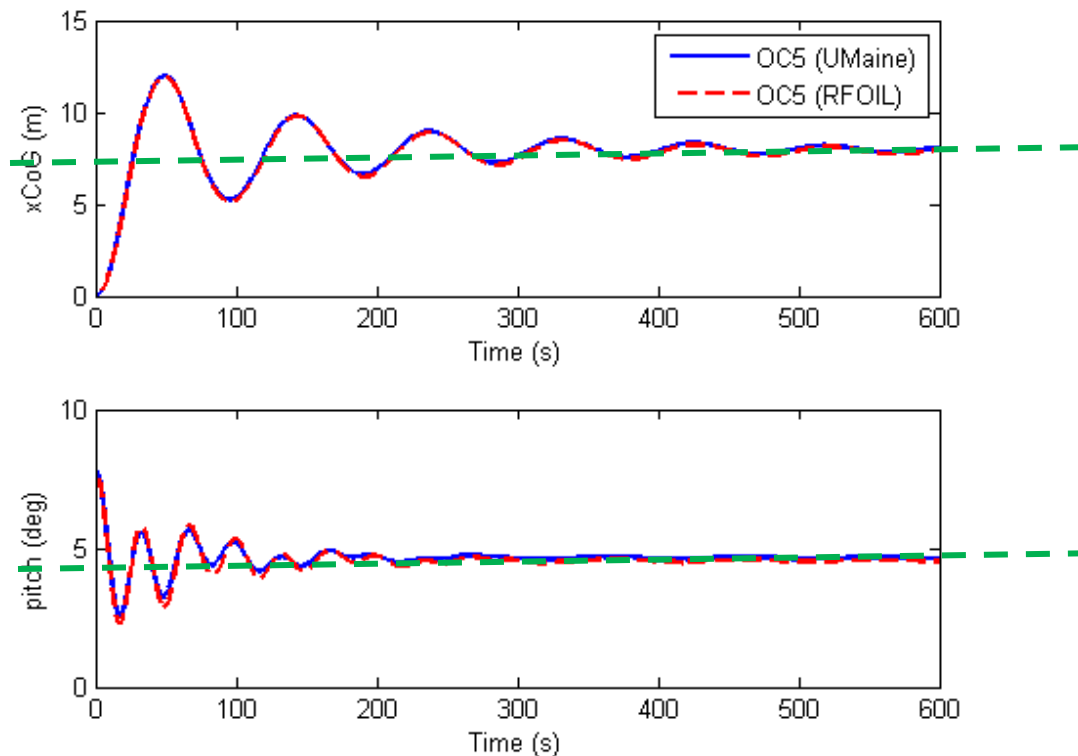
- Simulation of a pitch decay test in steady wind (13 m/s)



=> More damping for the 'Model of the model' than the model-test

# LOOK AT EFFECT OF {CL,CD} ON THE RESPONSE

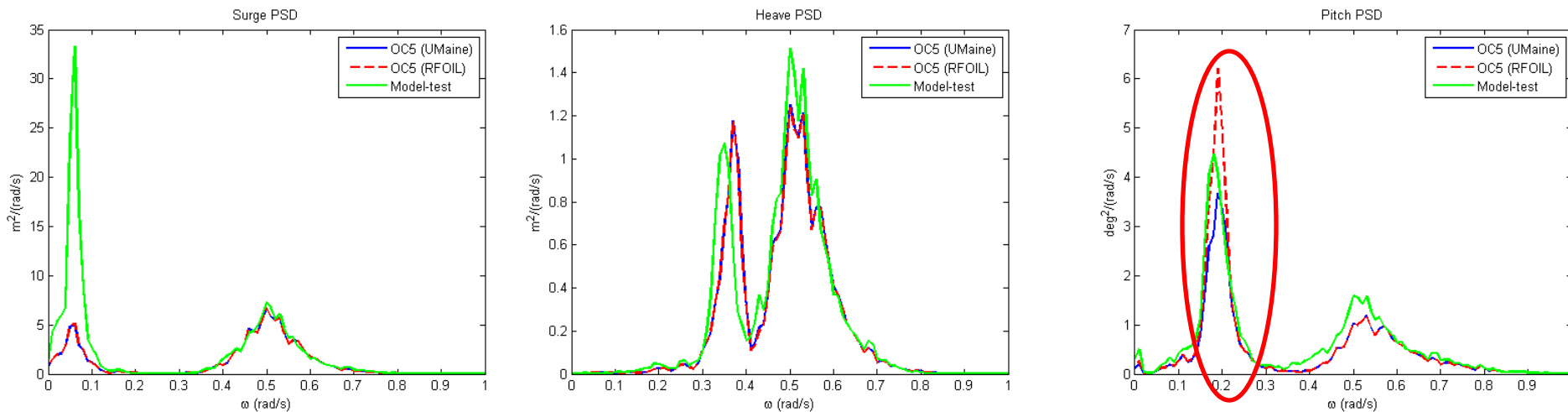
- Simulation of a pitch decay test in steady wind (13 m/s) with other {Cl, Cd}



- Surge (and heave) are identical
- Less damping with **RFOIL** than **UMaine**

# LOOK AT EFFECT OF {CL,CD} ON THE RESPONSE

- Operational sea + steady wind (13 m/s), head waves
- RFOIL** versus **UMaine** coefficients



- Surge and heave are identical
- Different amplitudes of pitch resonance peak
- Less damping with **RFOIL** than **UMaine**

## Lessons learnt:

- OC5 and OC4 behave in similar ways (small differences)
- ‘Model of the model’ => learn about main physics at play
- Response to 2<sup>nd</sup> order wave loads in surge and pitch
- Rotor loads acts primarily on resonance peaks
- Aerodynamic damping is mainly effective on surge and **PITCH**
- Level of damping (aero + hydro) is important to know if a numeric model is conservative or not
- Further work necessary on the determination of the damping:
  - Horizontal (hydrodynamics)
  - Pitch (aerodynamics)
  - Also on the wave loads (surge)



# THANK YOU



## Acknowledgments:

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