

Measurement of wind profile with a buoy mounted lidar

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History



First Automatic Wind Turbine 1887 Maykirk Scotland



First Norwegian Wind Mill at Fram



Partisipants





Fugro OCEANOR



University of Bergen

CM Instrumentation

Christian Michelsen Research



Statoil



Marintek

Project tasks



- Formulation of requirement and specification of the system
- Concept study
- Development of a prototype including hydrodynamic simulations
- Development of a compensation algorithm for the buoy motion
- Building of a prototype buoy
- Field test of the buoy



Present technology

FINO1 German Bight



Price NOK 50 mil

Measurement system







Wavescan buoy

ZephIR 300 lidar

ZephIR 300 lidar from Natural Power







- Wind profile, meteorological parameters, waves, current profile and other parameters can be measured from one single buoy
- The ZephIR can measure wind at 10m which is according to the WMO standard
- No recalibration is required for the ZephIR
- The Wavescan buoy is lightweight and small and is therefore easy to deploy and recover from vessels
- A standard single point mooring system is used



Test location Titran





Testing of Lidar buoy off the wind test centre





Preliminary results without compensation







Wind speed and direction









Scatter plott



All data

Strong wind (before 5th April)







Further work



- Comparing the buoy lidar data with the wind sensors at the met mast
- Include fuel cells for powering of <u>Lidar</u> Methanol cartridges to be located in wells below the solar panels Consuming 2 litres of methanol per day 8 carriages from EFOY: Operational time 112 days 4 special designed cartridges: Operational time 180 days
- Interfacing Geni to the Lidar
- Include compensation software in Geni
- Include "slam" Lidar
- Interfacing with the small scale wind model at Kjeller Vindteknikk

<u>Move</u>



Fuel cell from EFOY



SEAWATCH Wind Lidar Buoy



